

for a greener tomorrow changes

Programmable Controllers MELSEC-L series





Convenience that fits in the palm of your hand

The L Series is a compact-class controller, part of the MELSEC products renowned for exceptional cost verses performance and strong reliability. It provides the performance, functions, and capabilities required for today's demanding applications in a small package.

MELSEC-L Series greatly expands the range of functionality traditionally associated with compact programmable controllers and through user-centric design, pushes the limits of ease of use.





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L Series Features

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Flexible

Ideally configured to satisfy the applications requirements

MELSEC L Series has been designed with three key concepts in mind.

Reliability

Robust and trusted MELSEC product quality.

Ease-of-use

Enabling engineers and programmers to do their job as efficiently as possible to reduce costs.

Flexibility

L Series is a cost-efficient control system flexible to various applications, enabling an ideal system design.



Maximum Functionality

The CPU module contains a diverse range of control functions

A large variety of I/O types and features are built-in for convenience. Due to an abundance of advanced functionality, L Series CPUs are flexible enough to meet a wide variety of needs.

Maximum

Performance

High speed, large memory capacity CPU

The CPU has a basic operation processing speed of 9.5 ns*4 and 260K steps*5 of program capacity ideal for complex programs and equipment control.

Maximum

Capabilities

Advanced capabilities focused on improving efficiency

The user-friendly display unit enables routine operations to be made without a computer. An SD memory card slot¹³ is included as standard for data logging and program storage. Write programs and manage L Series controllers using GX Works2 and iQ Works, the most advanced and effective software for Mitsubishi controllers yet.

- *1: Option (sold separately)
- *2: Included with L26CPU-(P)BT
- *3: Included with L02CPU(-P), L06CPU(-P), L26CPU(-P), L26CPU-(P)BT
- *4: For L06CPU(-P), L26CPU(-P), L26CPU-(P)BT
- *5: For L26CPU(-P), L26CPU-(P)BT

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MITSUBISHI MODE = ERR. RUN = JOERR. BAT. USER PULL USE COK SD SD PULL USB C. TO DE CORREST TO THE ST T

L Series Built-in I/O Features

Every L Series CPU comes with 24 points of built-in I/O standard. These I/O points are capable of many functions usually reserved for separate modules. Save on system costs by using the built-in functions rather than relying exclusively on additional modules.

The built-in I/O*1 comes in sink or source type format and may be chosen based on the application.

■ L Series CPU Built-in I/O Functions

Positioning High-Speed Counter

(Built-in control of 2 axes)	(Two channels built-in)	Puls	e Catch	Interrupt Input	Input/Output	
	Function			Features		
Positioning*2	Number of axes: Maximum 2 ax	es		l: 200K pulses/s vation: 30 µs (Shortest activat ation and deceleration are sup		
High-Speed Counter*2	Number of channels: Maximum	2 channels	Maximum counting speed: 200K pulses/s Open collector, Differential line driver input High accuracy ON/OFF measurements with a resolution of 5 µs High precision PVM control up to 200 kHz (High speed pulse output)			
Pulse Catch	Number of input points: 16 point	ts		esponse time: 10 µs nose ON time is shorter than t	he scan time can be detected.	
Interrupt Input	Number of interrupt points: 16 p	oints	Built-in CPU provides high-speed processing. All input points support interrupt inputs.			
	Number of high-speed inputs: 6 Number of standard inputs: 10 p		Minimum input response time of high-speed input: 10 µs Minimum input response time of standard input: 100 µs			
General-purpose Output	Number of output points: 8 points Output response time: 1 µs or less					

^{*1:} The L02SCPU, L02CPU, L06CPU, L26CPU and L26CPU-BT are sink type, and the L02SCPU-P, L02CPU-P, L06CPU-P, L26CPU-P and L26CPU-PBT are source type.

Easy setup of built-in I/O functions

Configuring built-in I/O functions can be done easily by setting parameters using the programming tool.

	Input Signal Function Selec	tion	Input Response Time		Interrupt Processing Condition	
Xn0	Pulse Catch	-	0.01ms	*	Rising	
Xn1	Pulse Catch	~	0.01ms	*	Rising	
Xn2	Interrupt Input	~	1ms	*	Rising	
Xn3	Interrupt Input	~	1ms	*	Faling	
Xn4	Interrupt Input	~	1ms	*	Rising	
Xn5	Interrupt Input	~	1ms	*	Faling	
Xn6	General Input	-	10ms	-	Rising	
Xn7	General Input	-	10ms	-	Rising	
Xn8	General Input	-	10ms	-	Rising	
Xn9	General Input	-	10ms	-	Rising	
XnA	General Input	-	10ms	-	Rising	
XnB	General Input	-	10ms	-	Rising	
XnC	General Input	-	10ms	-	Rising	,
XnD	General Input	-	10ms	*	Rising	
XnE	General Input	-	10ms	-	Rising	
XnF	General Input	-	10ms	-	Rising	

Pulse Output Mode	CW/CCW Mode	•		
Rotation Direction Setting	Current Value Increment with Forward Run Pulse Output	•		
S/W Stroke Upper Limit (pulse)	2147483	64		
S/W Stroke Lower Limit (pulse)	e) -214748364			
Speed Limit Value (pulse/s)	1000			
Bias Speed at Start (pulse/s)				
Acceleration/Deceleration System Selection	Trapezoid Acceleration/Deceleration	,		

Operation Mode Setting	Normal Mode	,
Count Source Selection	A Phase/B Phase	,
Pulse Input Mode	1-Phase Multiple of 1	,
Counting Speed Setting	100kpps	
Z Phase (Preset) Trigger Setting	Rising	-
External Preset (Z Phase) Request Detection Setting	ON at detection	
Counter Format	Linear Counter	,
Function Input Logic Setting	Positive Logic	
Counter Function Selection	Count Disabling Function	
Coincidence Output Time Preset Setting	Not preset	
Coincidence Detection Interrupt Setting (Counter Value Coincidence No. 1)	Not used	
Coincidence Detection Interrupt Setting (Counter Value Coincidence No. 2)	Not used	
Sampling Time Setting (ms)		
Frequency Movement Averaging Processing Count		
Frequency Measurement Unit Time Setting		
Rotation Speed Movement Averaging Processing Count		
Rotation Speed Measurement Unit Time Setting		
Number of Pulses per Rotation (pulse)		
Pulse Measurement Target Setting		

General-purpose

Built-in I/O function example parameter settings
Pulse Catch: 0.01 ms (response time)
Interrupt Input: 1 ms (response time)

Positioning function example parameter settings
Pulse Output Mode: CW/CCW mode
Rotation Direction Setting:
Current Value Increment with Forward Run Pulse Output

High-speed counter function example parameter settings
Pulse Input Mode: 1-Phase Multiple of 1
Counting Speed Setting: 100 kpps

Positioning High-Speed Counter

Built-in CPU positioning control function

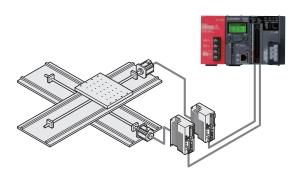
Positioning Function

The built-in positioning function has a start time of just 30 μ s with a maximum high speed output of 200K pulses per second.

Furthermore, it supports S-curve acceleration and deceleration for applications that require minimal machine vibration.

High-Speed Counter Function

Two channels support the high speed counting function. The differential line driver inputs support counting speeds up to 200K pulses per second.



^{*2:} Points used by the positioning and high speed counting functions are fixed (as in A phase, B phase, near-point dog).

Custom points for these functions may not be assigned.

CPU

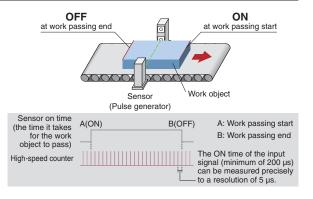


Make highly accurate measurements with a resolution of 5 µs

High-Speed Counter

Using pulse measurement mode, where the input signal ON/ OFF time is 200 µs or greater, highly accurate measurements in units of 5 µs or greater are possible.

For example it is possible to calculate length by knowing the "work object passing speed" and measuring the ON time of the sensor.



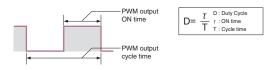
High-Speed Counter

High precision PWM control up to 200 kHz

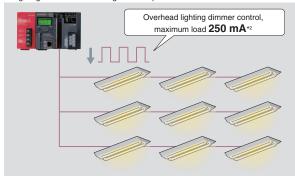
Using the pulse width modulation control function of the high speed outputs, cycle times as fast as 5 µs can be created. Simply input the ON time and cycle time to drive a wide range of devices from lighting dimmer control, motors, and heaters to precision inspection equipment requiring high resolution performance.

Setting item	Setting range	Description
PWM output ON time*1	0 or 10 10000000*1 (0.1 µs)	Set the ON time of output pulse
PWM output cycle time*1	50100000000*1 (0.1 μs)	Set the cycle time of output pulse

*1: The PWM output ON time must be ≤ than PWM output cycle time.



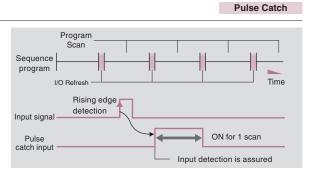
■ Lighting dimmer control using PWM output



*2: In cases where the first six digits of the serial number are "120722" or later. Previous serial numbers of the CPU module are applied to 100 mA

Guaranteed input pulse detection

Typical programmable controller input devices are unable to detect pulse signals whose ON time is shorter than the scan time or do not occur during I/O refresh periods. The pulse catch function allows these signals to be reliably detected and passed to the sequence program. This function is different from the interrupt input function in that it does not require any special programming. Pulse catch inputs may be used in programs exactly the same as traditional input (X) signals.



CPU with built-in CC-Link network connectivity

L Series CC-Link ready CPUs are compatible with the latest generation of CC-Link devices and support connections with over 1,000 different product types. Without adding a module, these CPUs can perform high-speed communication with a maximum of 128 words*3 between a master station and a local station. CC-Link is the dominate FA network standard in Asia and continues to gain support worldwide.

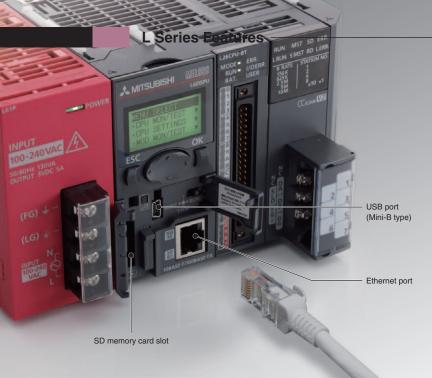


CPUs with built-in CC-Link can function as master or local stations. Up to 128 words*3 CC-Link Local stations (Up to 26)

Choose from an extensive range of CC-Link compatible equipment Up to 64 devices can be connected.

L26CPU-(P)BT

^{*3:} When the number of occupied stations is 4 and the extended cyclic setting is



Convenient communication and storage options come as standard

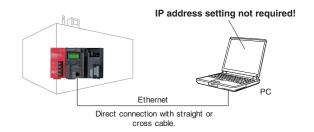
Program, configure, and perform diagnostics on L Series systems using either the USB 2.0 or Ethernet connections. The SD Memory Card slot has many uses including the easy backup and restore of programs and parameters.



L02CPU(-P) L06CPU(-P) L26CPU(-P) L26CPU-(P)BT

USB and Ethernet connections standard

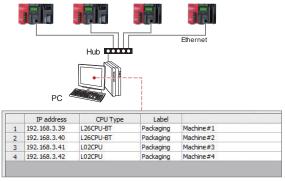
Use the USB 2.0 interface or Ethernet to connect directly at the instillation site. The Ethernet interface supports direct connection with either a cross or straight LAN cable and does not require any configuration of the programmable controller or PC to operate.



Easy connection through hub

All CPUs connected to the same hub can be searched and displayed in a list.

By selecting the access target CPU from the list, it can be connected to even if the IP address is unknown.

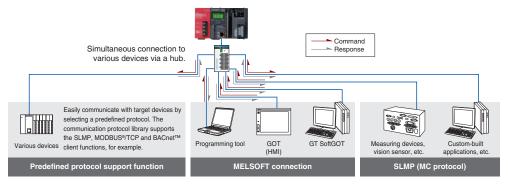


Use GX Works2 to retrieve a list of all CPUs connected to the network.

Easily connect to BACnet™ and MODBUS®/TCP Improved function

Ethernet realizes a high-speed connection, such as communication with external devices.

By using the predefined protocol support function, various devices that require open network protocol support, such as BACnet™ and MODBUS®/TCP are supported.



MELSEG L series

Network timestamp

Synchronize systems on an Ethernet network using an SNTP*1 server. Time synchronization can be achieved to enable simultaneous operations, quality control, or error tracking.

*1: SNTP: Simple Network Time Protocol



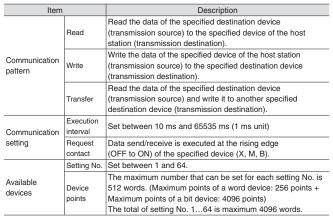
Program-less device data transfer

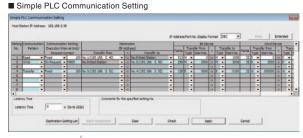
Simple PLC communication function*2

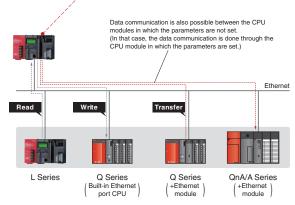
Using the programming tool, a simple parameter setting is all that is needed to transfer device data such as production information with no programming required.

This function makes it possible to easily establish communications not only with L Series, but also Q Series and QnA/A Series controllers.

*2: CPU module whose first five serial number digits are "13042" or later is required.







SD memory card special features

Use the SD/SDHC compatible memory card to quickly and easily back-up the CPU programs and parameters. The backups can then be just as easily restored or used to program other CPUs. The memory card can also be used to hold data captured with the data logging function*3.

*3: For details about the data logging function, please refer to page 9.

Save/load programs directly into the Programmable Controller

Multiple project save/load function*4

Parameters, program files, etc., can be saved/read onto an SD memory card by simply using the onboard display unit, without having to connect to a separate PC. Once saved on the SD memory card, files can be sent via e-mail, for example, when requiring off-site editing of the files.

*4: Supported by CPU module whose first five serial number digits are "14042" or later.



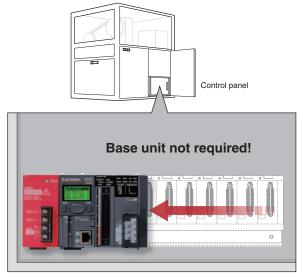


Save space in control panels by utilizing the integrated system bus structure. Flexibility in system design is made possible by choosing only the required expansion modules for the application.

Expand L Series systems with no base unit restrictions

L Series modules do not require a base unit. The installation space is not restricted by base size, and the system can be installed with minimal required space.

Furthermore, the addition of modules to the system is not restricted by the number of available base unit slots and costs may be reduced due to the elimination of extension base units.

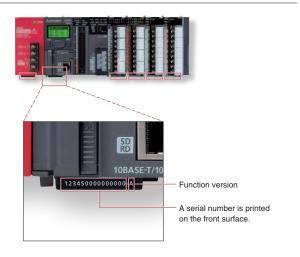


Installation space is reduced in the control panel

Identify important information easily

Every L Series module has the serial number printed on the front surface of the module to allow viewing even during system operation (modules do not need to be removed).

*: Serial numbers can also be checked using GX Works2.



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CPU



System expandable according to production equipment scale

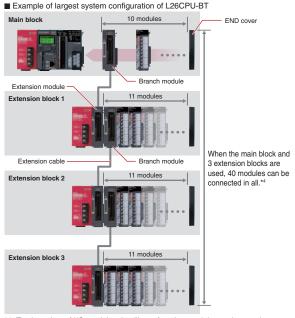
Up to three extension blocks connectable to the main block using branch and extension modules. A maximum of 40 modules* caters a wide range of production equipment and line scale.

CPU module*2	Number of extension blocks	Number of connectable modules*3		
L02SCPU(-P)	Lin to O blooks			
L02CPU(-P)	Up to 2 blocks	Main block: 10 modules		
L06CPU(-P)		Extension block: 11 modules		
L26CPU(-P)	Up to 3 blocks	Extension block: 11 modules		
L26CPU-(P)BT				

- *1: In the case of L06CPU(-P), L26CPU(-P), and L26CPU-(P)BT.
- *2: CPU modules whose first five serial number digits are 13072 or later.
- *3: Total number of I/O modules, intelligent function modules, network modules and branch modules.

This does not include the following: Power supply, CPU, display units, extension modules, RS-232 adapter, RS-422/485 adapter, and END covers.

When adding a branch module to a fully occupied block, relocate one of the other modules to a new block to give way to the branch module.



*4: Total number of I/O modules, intelligent function modules and network modules, excluding branch modules.

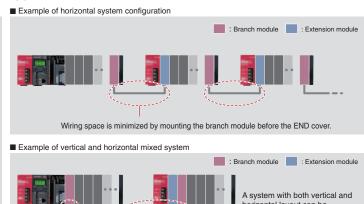
Well-organized control panel with minimum wiring

Branch module can be strategically placed in a block to minimize wiring space. Extension cables are available in 0.6-, 1.0- and 3.0-m. The maximum extension length is 3.0 m^{*5} .

The extension cable is a one-touch type which can be easily connected and disconnected.

*5: The total length of extension cables should be within 3.0 m.





horizontal layout can be configured to match the installation space.

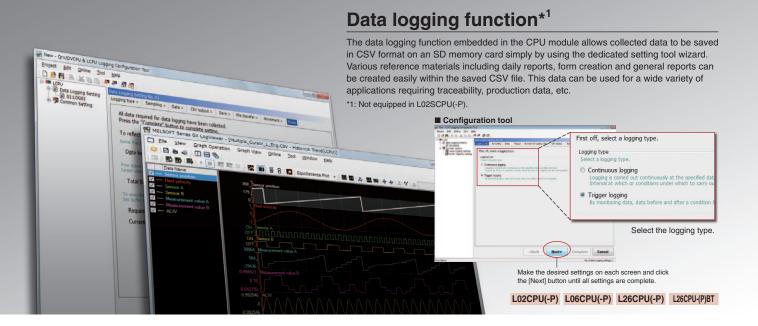
The modules can be replaced according to the system configuration!



Matching marks on the slot and the cable

■ Installation position when branch or extension module is used

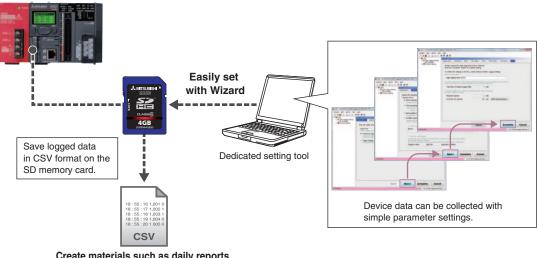
Modules	Installed block	Possible installation position
Branch module	Main block	Right side of CPU module or left side of END cover
	Extension block	Right side of extension module or left side of END cover
Extension module	Main block	Not applicable
	Extension block	Right side of power supply module



Easy logging without a program

Logging of device data just by configuring the parameters.

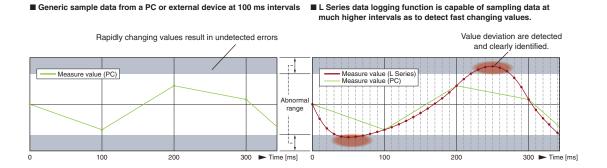
The results can be saved in CSV format on an SD memory card.



Create materials such as daily reports, form creation and general reports

Logging of control data variances

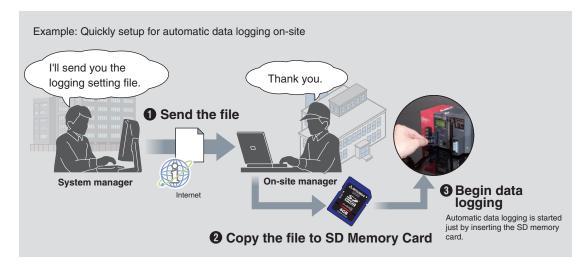
Data is collected during each scan or within millisecond intervals allowing detection of control deviation even at very high speeds. Therefore, identification of errors can be conducted faster and in more detail.





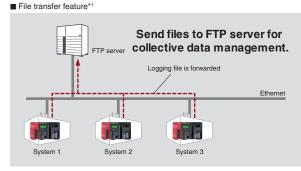
Auto logging function

Automatic data logging realized just by inserting the SD memory card into the CPU, which is achieved as the memory card includes the logging configuration file. Instructing data logging remotely is also realized just by sending the configuration file by e-mail and copying onto the SD memory card.



Automatically send logging files to FTP server

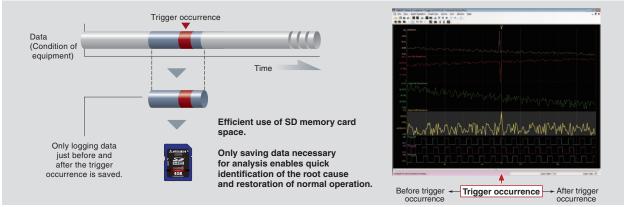
Data logging files saved on the SD memory card can be sent to the FTP server just by making a simple setting with the logging configuration tool. As the logging server can handle multiple files, management and maintenance tasks can be reduced.



*1: Using a CPU module with the first 5 digits of the serial number "12112" or later.

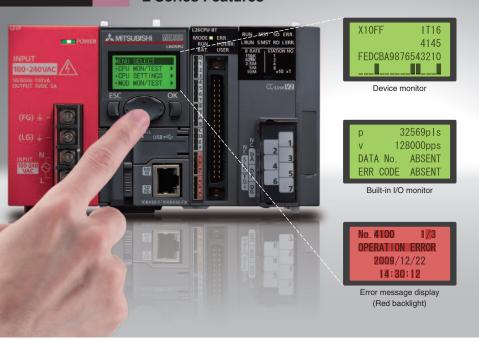
Trigger logging function

Error causes and solutions can be quickly done as only the required data related to the problem is extracted, without having to spend time on filtering large volumes of diagnostic data.



To receive a copy of GX LogViewer, contact your local Mitsubishi Electric representative.

L Series Features



Feature rich and easy to use display

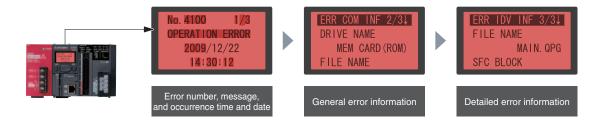
Check the system status and make setting changes directly from the display. Error status is clearly identified and troubleshooting and error investigation can be performed all without the need for any connections or engineering software.

*: Not available for L02SCPU(-P).

L02CPU(-P) L06CPU(-P) L26CPU(-P) L26CPU-(P)BT

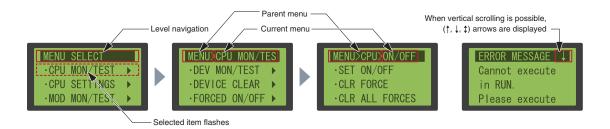
Instant error information check

Error history and detailed error information are available directly from the display unit.



Intuitive menu navigation

The menu navigation guide shows the current menu tree location and an arrow to indicate the scroll direction at the top of the display.



Multilingual operation

The display unit language can be selected (Japanese or English).







An easy-to-use modular design

The L Series module labeling design has been created to ensure clear legibility and identification of information at a glance to avoid mistakes.

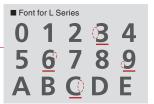
Universal design

Adopting a universal font

A high visibility font has been chosen for characters printed on system modules.



■ Regular Gothic font 4



The characters are thick enough. however the numbers "3, 6, 8, 9" and the alphabet "C" are not clearly distinguishable because the spacing indicated with a red circle is not large enough.

The space indicated with a red circle has been enlarged.

The numbers "3, 6, 8, 9" and the alphabet "C" are clearly distinguishable. Characters are legible even in small print.

Module design

White and red are used to distinguish inputs from outputs respectively to allow for easy identification of terminal connection type.



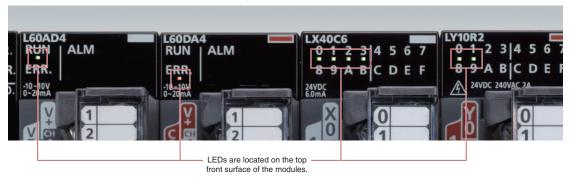
White for input module



Red for output module

Easily identify module status

LEDs display the current status of modules including run and error states.



CPU Modules

unication interface:



L02SCPU

L02SCPU-P

General-purpose output: Sink type Program capacity: 20K steps Basic operation processing speed: 60 ns

General-purpose output: Source type Program capacity: 20K steps Basic operation processing speed: 60 ns

*: End cover is enclosed.

Cannot be mounted on display unit (L6DSPU), RS-232 adapter, RS-422/485 adapter,



L02CPU

L02CPU-P

General-purpose output: Sink type Program capacity: 20K steps Basic operation processing speed: 40 ns

*: END cover is included.

General-purpose output: Source type Program capacity: 20K steps Basic operation processing speed: 40 ns



L06CPU

L06CPU-P

General-purpose output: Sink type Program capacity: 60K steps Basic operation processing speed: 9.5 ns

*: END cover is included.

General-purpose output: Source type Program capacity: 60K steps Basic operation processing speed: 9.5 ns



L26CPU

L26CPU-P

General-purpose output: Sink type Program capacity: 260K steps Basic operation processing speed: 9.5 ns

*: END cover is included.

General-purpose output: Source type Program capacity: 260K steps Basic operation processing speed: 9.5 ns





L26CPU-BT

L26CPU-PBT

General-purpose output: Sink type Program capacity: 260K steps Basic operation processing speed: 9.5 ns

General-purpose output: Source type Program capacity: 260K steps
Basic operation processing speed: 9.5 ns

Model	General-purpose output	Number of I/O points	Program capacity	Basic operation processing speed (LD instruction)	Peripheral connection ports	Built-in network	
L02SCPU		1024 points	001/ -+	60 ns	USB/RS-232	_	
L02CPU		1024 points	20K steps	40 ns		_	
L06CPU	Sink type		60K steps			_	
L26CPU		4096 points		9.5 ns	USB/Ethernet	_	
L26CPU-BT			260K steps			CC-Link	
L02SCPU-P		4004	0017	60 ns	USB/RS-232	_	
L02CPU-P		1024 points	20K steps	20K Steps	40 ns		_
L06CPU-P	Source type	urce type 4096 points	60K steps		LICD/Ethamat	_	
L26CPU-P	,		0001/	9.5 ns	USB/Ethernet -	_	
L26CPU-PBT			260K steps			CC-Link	

CPU packages

- ■L02CPU-SET
- Includes CPU (L02CPU), power supply module (L61P), and display unit (L6DSPU).

 ■L02CPU-P-SET
- Includes CPU (L02CPU-P), power supply module (L61P), and display unit (L6DSPU).



- ■L26CPU-SET
- Includes CPU (L26CPU), power supply module (L61P), and display unit (L6DSPU).
- ■L26CPU-P-SET
- Includes CPU (L26CPU-P), power supply module (L61P), and display unit (L6DSPU).



- ■L06CPU-SET
- Includes CPU (L06CPU), power supply module (L61P), and display unit (L6DSPU).

 ■L06CPU-P-SET

Includes CPU (L06CPU-P), power supply module (L61P), and display unit (L6DSPU).



- ■L26CPU-BT-SET
- Includes CPU (L26CPU-BT), power supply module (L61P), and display unit (L6DSPU).
- ■L26CPU-PBT-SET
- Includes CPU (L26CPU-PBT), power supply module (L61P), and display unit (L6DSPU).



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MELSEG L series

■ General specifications

General specifications indicate the environmental specifications in which this product can be installed and operated. Unless otherwise specified, these general specifications apply to all L Series products.

*: General specifications of jointly developed products are different from those of MELSEC products. For more information, please refer to the product manuals or contact your local Mitsubishi Electric representative.

Item			Specific	ation			
Operating ambient temperature	055°C						
Storage ambient temperature			-257	75°C			
Operating ambient humidity Storage ambient humidity	595%RH, non-condensing						
Vibration resistance			Frequency	Constant acceleration	Half amplitude	Sweep count	
	Compliant with JIS B 3502 and IEC 61131-2	Under intermittent vibration	58.4 Hz	_	3.5 mm	10 times each in	
			8.4150 Hz	9.8 m/s ²	_	X, Y, and Z directions	
		Under continuous	58.4 Hz	_	1.75 mm		
		vibration	8.4150 Hz	4.9 m/s ²	_		
Shock resistance		Compliant with JIS B 35	02 and IEC 61131-2 (14	7 m/s2, 3 times each in X	, Y, and Z directions)		
Operating atmosphere			No corrosiv	/e gases			
Operating altitude*1			0200	00 m			
Installation location			Inside a con	itrol panel			
Overvoltage category*2	≤∏						
Pollution degree*3	≤2						
Equipment class			Class	; I			

^{*1:} Do not use or store the programmable controller under pressure higher than the atmospheric pressure of altitude 0 m.

Doing so may cause malfunction. When using the programmable controller under pressure, please consult your local Mitsubishi Electric representative.

2: This indicates the section of the power supply to which the equipment is assumed to be connected between the public electrical power distribution network and the machinery

within premises.

Category II applies to equipment for which electrical power is supplied from fixed facilities. The surge voltage withstand level for up to the rated voltage of 300 V is 2500 V.

*3: This index indicates the degree to which conductive material is generated in terms of the environment in which the equipment is used.

Pollution level 2 is when only non-conductive pollution occurs. A temporary conductivity caused by condensing must be expected occasionally.

■ CPU module specifications

CPU module s	pecilica	110115	LOSSOBIL	LOCOBIL	L COORLI	LOCOBIL	I COORLI DE
	Item		L02SCPU L02SCPU-P	L02CPU L02CPU-P	L06CPU L06CPU-P	L26CPU L26CPU-P	L26CPU-BT L26CPU-PBT
Control method				Sto	ored program cyclic operat	ion	
I/O control mode			Refresh mode (The direct access input/output is available by specifying the direct access input/output (DX, DY).)				
Programming languag (sequence control languag			Function block, relay symbol language, MELSAP3 (SFC), MELSAP-L, structured text (ST), logic symbolic language				
Processing speed*4	LD X0		60 ns	40 ns		9.5 ns	
(sequence instruction)	MOV D0 E	01	120 ns	80 ns		19 ns	
Constant scan			'	0.52000 ms (Setting i	s available in increments of	of 0.5 ms by parameter.)	
Program size			20K steps ((80K bytes)	60K steps (240K bytes)	260K steps	(1040K bytes)
	Program n	nemory (drive 0)	80K t	oytes	240K bytes	1040	K bytes
	Memory ca	ard (RAM) (drive 1)					
Memory capacity	Memory ca	ard (ROM) (drive 2)	_		Depends on the SD/SDF	C memory card used.*5	
	Standard I	RAM (drive 3)	128K	bytes		768K bytes	
	Standard I	ROM (drive 4)	512K	•	1024K bytes		K bytes
	Program n	nemory	64 f		124 files	252	? files
	Memory ca	ard (RAM)			_		
	,				Root directory: 511 files (maximum)		
Maximum number of	Memory	lemory SD	Subdirectory: 65533 files (maximum)				
files stored	card (RON	M) SDHC	_		Root directory: 65534 files (maximum)		
		SDHC	_		Subdirectory: 6553	3 files (maximum)	
	Standard RAM		4 files (each one of the	following files: file registe	er file, local device file, sar	npling trace file, and mod	lule error collection file)
	Standard I	ROM	128 files 256 files				
Maximum number of ir	ntelligent	Initial setting	2048 parameters			4096 parameters	
function module param	neters	Refresh	1024 par	4 parameters 2048 parameters			
Maximum number of n	nodules spe	cification*6	3	0		40	
Built-in I/O function				Refer to the I	built-in I/O specifications	P.16 to P.17	
Data logging function			_	Refer to the data logging function specifications ➡ P.17			
Built-in Ethernet function	on		_	Refer to the built-in Ethernet specifications ⇒ P.18			1
Built-in serial commun	ication funct	tion	Refer to the built-in serial communication specifications ⇒ P.18	_			
Built-in CC-Link function	Built-in CC-Link function		Refer to the Master/Loca				Refer to the CC-Link Master/Local Module specifications. → P.51
	Displayed	information	Year, mo	onth, date, hour, minute, s	second, and day of the wee	ek (automatic leap year d	letection)
Clock function				0°C: -2.9	96+3.74 s (TYP. +1.42 s)	per day	
CIOCK IUIICUOII	Accuracy				18+3.74 s (TYP. +1.50 s		
		With display unit		1.00 A	1.0	· · · · ·	1.43 A
5 V DC internal	ICPH 1	Without display unit	0.75 A	0.94 A	1.0		1.37 A
current consumption		r (Accessory)*7	0.73 A	U.34 A	0.04 A	V A	1.57 A
		With display unit	_		0.40 kg		0.50 kg
Weight	ICPU	Without display unit					0.50 kg 0.47 kg
Weight		. ,	0.32 kg		0.37 kg		0.47 Kg
END cover (Accessory)*7			0.06 kg				

^{*4:} Indexing devices does not delay processing time.

^{*5:} The operation of devices that are not manufactured or recommended as compatible products by Mitsubishi Electric cannot be guaranteed.
*6: The total number of modules that can be mounted to a CPU. Refer to the "Maximum number of modules specification" for each module.

^{*6:} The total number of modules that can be mounted to a CPU. Refer to the "Maximum number of modules specification" for each module. (Power supply modules, CPU module, Display unit, Extension module, RS-232 adapter, RS-422/485 adapter, END cover, and END cover with error terminal are not included. Note that only one CPU or head module per system is possible.)

^{*7:} The END cover is included with the CPU module and must be placed on the right end of the last module in the system.

■ CPU module device specifications

	Item	L02SCPU L02SCPU-P	L02CPU L02CPU-P	L06CPU L06CPU-P	L26CPU L26CPU-P	L26CPU-BT L26CPU-PBT		
Number of I/O dev			8	192 points (X/Y0X/Y1FFF	=)			
· · · · · · · · · · · · · · · · · · ·	available on a program)				<u>*</u>			
Number of I/O poi	nts	1024 points (X/Y0X/Y3FF) 4096 points (X/Y0X/YFFF)						
nternal relay (M)				(M0M8191) by default (c	• ,			
atch relay (L)				(L0L8191) by default (ch				
ink relay (B)				(B0B1FFF) by default (c				
Γimer (T)		2048 poi	(Low-speed timer: 1	It (changeable) (Low-speed 1000 ms (in increments of 1 .100 ms (in increments of 0	ms), default: 100 ms)	available)		
Retentive timer (S	Т)	(L	ow-speed retentive timer:	e)(Low-speed and high-spe 11000 ms (in increments 0.1100 ms (in increments	s of 1 ms), default: 100 n	ns)		
Counter (C)			Normal counter 102	4 points (C0C1023) by d	efault (changeable)			
Data register (D)			12288 points	(D0D12287) by default (changeable)			
Extended data register (D)		' '	8D45055) by default geable)	131072 poi	ints (D12288D143359) (changeable)	by default		
Link register (W)			8192 points (W0W1FFF) by default (changeable)					
Extended link register (W)		0 point by default (changeable)						
nnunciator (F)		2048 points (F0F2047) by default (changeable)						
Edge relay (V)		2048 points (V0V2047) by default (changeable)						
Link special relay (SB)		2048 points (SB0SB7FF) by default (changeable)						
ink special regist	er (SW)	2048 points (SW0SW7FF) by default (changeable)						
File register	(R)		(R0R32767) pints are available by g blocks.)	32	2768 points (R0R3276) 6 points are available by			
	(ZR)	65536 points (2	ZR0ZR65535) ed to be switched.)		216 points (ZR0ZR393) s do not need to be switch			
Step relay (S)			8192	points (S0S8191) by de	fault			
ndex register/star	ndard device register (Z)		20	point (Z0Z19) (maximun	n)			
ndex register (Z) 32-bit index modi	fication of ZR device)	10 point (Z0Z18) (maximum) (The index register is used as a double-word device.)						
Pointer (P)		4096 points (P	0P4095) (The local poir	ter range and the common	pointer range can be se	t by parameter.)		
Interrupt pointer (I)		256 points (I0I255) (The fixed scan interval for the system interrupt pointer I28I31 can be set by parameter.) 0.51000 ms (in increments of 0.5 ms) Default I28: 100 ms, I29: 40 ms, I30: 20 ms, I31: 10 ms						
Special relay (SM)				SM2047) (The number of de	· · · · · · · · · · · · · · · · · · ·			
Special register (S				SD2047) (The number of de				
function input (FX					<u> </u>			
Function output (FY)		16 points (FX0FX F) (The number of device points is fixed.) 16 points (FY0FY F) (The number of device points is fixed.)						
unction register (D4) (The number of device	· · · · · · · · · · · · · · · · · · ·	-		
ntelligent function	<u>, </u>	0	evice that directly access	es the buffer memory of an ecification format: U□□/G□	intelligent function modu	ıle		
atch (data retenti	on during power failure) range	(The	8192	2 points (L0L8191) by def the devices, B, F, V, T, ST,	fault	neter.)		

MELSEG L series

■ CPU built-in I/O function – input specifications (general-purpose input/interrupt input/pulse catch function)

	Item		Description	
	Points	oints 10		
Input voltage/current			24 V DC 4.1 mA (TYP.)	
Standard input Minimum input response	time	100 µs		
Input response time settin		ng	0.1 ms, 1 ms, 5 ms, 10 ms, 20 ms, 70 ms	
	Common terminal arrangement		10 points/common (Positive or negative common)	
	Points		6	
		DC input	24 V DC 6.0 mA (TYP.)	
	Input voltage/current	Differential input	EIA Standard RS-422-A Differential line driver level	
High-speed input		Differential input	AM26L31 (manufactured by Texas Instruments Incorporated) or equivalent	
	Minimum input response	time	10 µs	
	Input response time setti	ng	0.01 ms/0.1 ms/0.2 ms/0.4 ms/0.6 ms/1 ms	
	Common terminal arrange	ment	Independent	

■ CPU built-in I/O function – output specifications (general-purpose output function)

Item		Description		
Points		8		
Output voltage/current 524 V DC 0.1 A		524 V DC 0.1 A		
Response time OFF to ON ON to OFF		≤ 1 µs (rated load, resistance load)		
Common terminal arrangement		L02SCPU, L02CPU, L06CPU, L26CPU, L26CPU-BT: 8 points/common (Sink type) L02SCPU-P, L02CPU-P, L06CPU-P, L26CPU-PBT: 8 points/common (Source type)		

■ CPU built-in I/O function – positioning function specifications

Item			Description	
Number of co	Number of controlled axes		2	
Control unit	Control unit		pulse	
PTP*1 control		PTP*1 control	Available	
Operation pa	attern	Path control	Not usable	
Number of p	Number of positioning data		10 data/axis	
	.	PTP*1 control	ABS/INC	
	Positioning control method	Speed/position switching control	INC	
Desiries and an		PTP*1 control	-21474836482147483647 pulses	
Positioning control	Positioning range	Speed/position switching control	02147483647 pulses	
	Speed command		0200k pulses/s	
	Acceleration/decelera	ation system selection	Automatic trapezoid acceleration/deceleration and S-curve acceleration/deceleration	
	Acceleration/decele	eration time	032767 ms	
OPR method	OPR method		6 types	
Starting time (1-axis linear control)		.1\	Trapezoid acceleration/deceleration (single-axis start): 30 μs/axis	
Starting time	(1-axis iirleai contro	'')	S-curve acceleration/deceleration (single-axis start): 35 μs/axis	
Pulse output method		nd	L02SCPU, L02CPU, L06CPU, L26CPU, L26CPU-BT: 524V DC (Sink type)	
Command	<u>'</u>	,u	L02SCPU-P, L02CPU-P, L06CPU-P, L26CPU-P, L26CPU-PBT: 524V DC (Source type)	
pulse output	Pulse output mode		4 types	
paloe output	Maximum output pulse		200k pulses/s	
	Maximum connection of	distance with drive unit	2 m	
		DC input	24 V DC 6.0 mA (TYP.)	
	Zero signal	Differential input	EIA RS-422-A differential line driver level	
		'	AM26L31 (manufactured by Texas Instruments Incorporated) or equivalent	
	Speed/position swit			
External	Near-point dog sign		24 V DC 4.1 mA (TYP.)	
input	Upper and lower lin		24 0 00 4.1 11/1/(11.1)	
Di	Drive unit ready sig	nal		
			Zero signal: 10 μs	
Inp	Input response time	9	Speed/position switching control, near-point dog signal: 100 μs	
			Upper and lower limit signal, drive unit ready signal: 2 ms	
External	Deviation counter of	lear signal	L02SCPU, L02CPU, L06CPU, L26CPU, L26CPU-BT: 524 V DC 0.1A (Sink type) L02SCPU-P, L02CPU-P, L06CPU-P, L26CPU-P, L26CPU-PBT: 524 V DC 0.1A (Source type)	
output	Response time OFF to ON ON to OFF		≤ 1 µs (rated load, resistive load)	

^{*1:} Abbreviation for "Point to Point." This is a type of position control.

■ CPU built-in I/O function – high-speed counter specifications

	Item		Description	
Number of c			2	
Tallibor or o	Harriolo		1-phase input (1 multiple/2 multiples)	
	Phase		CW/CCW.	
Count input	1 11000		2-phase input (1 multiple/2 multiples/4 multiples)	
signal		DC input	24 V DC 6.0 mA (TYP.)	
J.g. 14.	Signal level	Differential	EIA Standard RS-422-A Differential line driver level	
	0.3	input	AM26L31 (manufactured by Texas Instruments Incorporated) or equivalent	
	Maximum counting speed		200k pulses/s (for 2 multiples of 1 phase and 4 multiples of 2 phases)	
	Counting range		-21474836482147483647	
	Model		UP/DOWN preset counter (with ring counter function)	
Counter	Minimum count pulse	1 phase	5 µs	
Ocuritor	width (Duty ratio 50%)	2 phases	10 μs	
	Min. phase differential for		то ра	
	input	2-priase	5 μs	
		DC input	24 V DC 6.0 mA (TYP.)	
	Phase Z (preset)	Differential	EIA Standard RS-422-A Differential line driver level	
		input	AM26L31 (manufactured by Texas Instruments Incorporated) or equivalent	
External	Function start		04 V DC 4.1 == 4 (TVD)	
input	Latch		24 V DC 4.1 mA (TYP.)	
	Innut reen ence time		Phase Z: 10 μs	
	Input response time		Function start, latch: 100 μs	
	Output format		L02SCPU, L02CPU, L06CPU , L26CPU, L26CPU-BT: Sink type	
	Output format		L02SCPU-P, L02CPU-P, L06CPU-P, L26CPU-P, L26CPU-PBT: Source type	
		Coincidence		
External		output No. 1 /	524 V DC/0.25 A*1	
output	Output voltage/current	PWM output		
Juipui		Coincidence	524 V DC/0.1 A	
		output No. 2	5L. 1 25.3.1.1.	
	Response time	OFF to ON	≤ 1 µs (Rated load, resistance load)	
	ricoporioc unic	ON to OFF	= 1 po (Maled load, Polistanio load)	
	Comparison range		-21474836482147483647	
Coincidence			Set value < Counted value	
output	Comparison result		Set value = Counted value	
σαιραι			Set value > Counted value	
	Output points		2 points/channel	
	Output frequency range		DC200 kHz	
PWM	ON width		1 μs	
output	Duty ratio		On width can be set in increments of 0.1 µs.	
	Output points		1 point/channel	
Dulan middle	Measurement item		Pulse width (On width: ≥ 200 μs, Off width: ≥ 200 μs)	
Pulse width measurement	Measurement resolution		5 µs	
neasurement	Measurement points		1 point/channel	
	•			

^{*1:} For units where the first six digits of the serial number are "120722" or later. The specification for previous serial numbers is 5 to 24 V DC/0.1 A.

■ CPU data logging function specifications

<u> </u>	ata loggii	ig function specific	4.10110			
ltem			L02CPU L02CPU-P	L06CPU L06CPU-P	L26CPU L26CPU-P	L26CPU-BT L26CPU-PBT
Number of data logging settings					0	<u> </u>
Data logging buffer capacity		For each setting, any of 32 to 4832K bytes (in units of 1K byte) can be specified. The total value of settings No.1 to No.10 is up to 5120K bytes.				
Data storag	e location		\$	Standard ROM (configuration	files only), SD Memory Card	d
Logging type			 Continuous logging 	Trigger logging		
Sampling interval • Each scanning cycle • Time specification • Condition specification (Device specification, Step No. specification)		cation)				
Data	No. of data	sampling points		Up to 1280 (128	points per setting)	
sampling	AND conju	nction	In the Sampling interval setting, Device and Step No. under "Condition specification" can be specified in combination (AND conjunction).			an be specified in combination
		Trigger condition	 Condition specification (Device change specification, Step No. specification) When trigger instruction executed When data logging trigger activated 			
Data	Trigger	AND conjunction	In the Trigger setting, Device data change and Step No. under "Condition specification" can be specified in combination (AND conjunction).			
processing	logging	Trigger logging range	Data of the specified number of records are logged before and after a trigger.			
		Number of triggers	1			
		Number of trigger logging records		Up to 1	000000	
File name Up to 48 one-byte characters can be used for the following.						
	File name		• File number (serial number)*2 • Chara	cter string (name)*3 • Date	e and time*3
	File format			CS	/ file	
File output Data ty	Data type		BitDouble word (unsigned)FLOAT (double precision	Word (unsigned)Double word (signed)Character string: 1	ed) • FL	ord (signed) OAT (single precision) Imeric string: 1…256 bytes
	Data outpu	t format (CSV file)	Decimal format			mat
Handling of	File	File switching timing		No. of records	• File size	
output files	switching	Number of saved files		16	5535	

^{*2:} Part of the saved file name, this number is automatically assigned.
*3: Optional data to be appended to the saved file name.

MELSEG L series

■ CPU built-in Ethernet function specifications

Item			L02CPU L02CPU-P	L06CPU L06CPU-P	L26CPU L26CPU-P	L26CPU-BT L26CPU-PBT	
Data transfer speed		100 or 10 Mbps					
	Communication mode		Full-duplex or half-duplex				
Transmission	Transmission meth	nod	Base band				
specifications	ons Maximum distance between hub and node		100 m				
	Maximum number of	10BASE-T		Cascade connection: Up to four			
	nodes/connection	100BASE-TX		Cascade connection: Up to two			
Number of	TCP/IP	Total of 16 for socket communications, MELSOFT connections, and MC protocol.*1		protocol.*1			
connections	UDP/IP	P One for FTP					
Connection	10BASE-T		0BASE-T Ethernet cable of category 3 or higher (STP/UTP cable)*3				
cable*2	100BASE-TX			Ethernet cable of categor	y 5 or higher (STP cable)		

- *1: Only the QnA-compatible 3E frame may be used.
 *2: Standard (straight type) cable. Also, when the CPU is connected directly with a GOT(HMI), a cross cable (category 5e or less) may be used.
- *3: The use of STP (Shielded Twisted Pair) cables is recommended in noisy environments.

■ Communication performance comparison (Comparison of LCPU with built-in Ethernet port and Ethernet interface module)

Communication performance comparison (comparison of Eor o with bank in Eulernet portains Eulernet interface mediale)			
Function/performance	LCPU with built-in Ethernet port	Ethernet interface module	
Communication speed	100 Mbps	100 Mbps	
MC protocol communication	● *4	•	
Socket communication	● *5	(Fixed buffer communication)	
Communications using a random access buffer	_	•	
E-mail function	_	•	
Communications using data link instructions	_	•	
File transfer (FTP server) function	● *6	•	
Web function	_	•	
MELSOFT products and GOT(HMI) connection	•	•	

- *4: QnA compatible 3E frame device memory access commands only. Refer to the relevant manual for details.
- *5: There are some differences regarding the fixed buffer communications function. Refer to the relevant manual for details.
- $^{\star}6$: The "quote cpuchg" command is not supported.

■ CPU built-in serial communication function specifications

Item	L02SCPU	
item	L02SCPU-P	
Communication mode Full duplex		
Synchronization method	Asynchronous method	
Transmission speed 9.6 kbps, 19.2 kbps, 38.4 kbps, 57.6 kbps, 115.2 kbps		
	Start bits: 1	
Data format	Data bits: 8	
Data format	Parity bits: Odd number	
	Stop bits: 1	
MC protocol format *7 (automatic judgment)	Formats 4 (ASCII)	
we protocol format / (automatic judgment)	Formats 5 (Binary)	
Frame *7	QnA compatible 3C frame	
Frame '	QnA compatible 4C frame	
Transmission control	DTR/DSR control	
Transmission distance (Overall distance) Maximum 15 m		

^{*7:} Information relevant to the MC protocol format and frame are shown below.

	•		●: Supported —: Not supported
F	unction	Formats 4	Formats 5
Communication with	QnA compatible 3C frame	•	_
ASCII code	QnA compatible 4C frame	•	_
Communication with binary code	QnA compatible 4C frame	•	•

■ How to read the product code

L 26 CPU - P BT - SET

Program memory capacity	
Capacity U6	
Number Item	
Communication interface Blank S Built-in Ethernet model Built-in RS-232 model Number Item Code Specification Type of module CPU CPU module Number Item Code Specification Built-in RS-232 model CPU module Specification Specification Specification Specification Specification Specification Sink type F Source type	
Communication interface S Built-in RS-232 model Number	
Number	
Type of module CPU CPU module Number Item Code Specification Built-in I/O output format Blank Blank Blank Blank Blank Format Sink type P Source type	
Number Item Code Specification Built-in I/O output format Blank Sink type P Source type	
Built-in I/O output format Blank Sink type P Source type	
6 format P Source type	
format P Source type	
Number Item Code Specification	
Built-in CC-Link function Blank Blank Blank	
BIT Built-in CC-Link function	
Number Item Code Specification	
Product set Blank —	
SET Set includes a power supply module (L61P) and display unit (L6DSPU)	

Branch/Extension Modules



■ Branch and extension module specifications

Item	L6EXB [Branch module]	L6EXE [Extension module]
5 V DC internal current consumption	0.08 A	0.08 A
Weight	0.12 kg	0.13 kg

■ Extension cable specifications

Item	LC06E	LC10E	LC30E
Cable length	0.6 m	1.0 m	3.0 m
Weight	0.19 kg	0.23 kg	0.45 kg

Power Supply Modules



■ Power supply module specifications

Item	L61P	L63P	L63SP
nput power supply	100240 V AC (-15%+10%)	24 V DC (-35%+30%)	
nput frequency	50/60 Hz (-5%+5%)	=	=
nput voltage distortion	≤ 5%	_	
Maximum input apparent power	130 VA	_	
Maximum input power	_	45	W
nrush current	20 A, ≤ 8 ms	100 A, ≤ 1 ms (24 V DC input)
Rated output current (5 V DC)		5 A	
Overcurrent protection (5 V DC)		≥ 5.5 A	
vervoltage protection 5.56.5 V		5.56.5 V	
Efficiency	≥ 70%		
Allowable momentary power failure time	≤ 10 ms	≤ 10 ms (24 V DC input)	
Vithstand voltage	2300 V AC per minute (altitude 02000 m) Between the combined "line input/LG terminals" and the "FG terminal and output".	510 V AC per minute (altitude 02000 m) Between the combined "line input/LG terminals" and the "FG terminal and output".	*1
nsulation resistance	Between the combined "line input/LG The line input	DC insulation resistance tester terminals" and the "FG terminal and output". t and LG terminals. minal and output.	_*1
Veight	0.32 kg	0.29 kg	0.19 kg

 $^{^{\}star}$ 1: There is no isolation between the primary side 24 V DC and secondary side 5 V DC.



RS-232 Adapter



L6ADP-R2

Transmission speed: 115.2 kbps GOT(HMI) connection MELSOFT⁻¹ connection Predefined protocol support function Serial communication function

MODBUS®

*1: Please refer to each MELSOFT product manual for details on the supported software

■ RS-232 adapter specifications

Item	Specification
Maximum data transmission speed	115.2 kbps
5 V DC internal current consumption	0.02 A
Weight	0.10 kg

RS-422/485 Adapter



L6ADP-R4

Transmission speed: 115.2 kbps GOT(HMI) connection Predefined protocol support function Serial Communication function

MODBUS®

■ RS-422/485 adapter specifications

Item	Specification
Maximum data transmission speed	115.2 kbps
5 V DC internal current consumption	0.15 A
Weight	0.12 kg

END Cover with Error Terminal



■ END cover with error terminal specifications

END COVER WITH CITOR CERTIFICATIONS								
	Item		Specification					
	Rated switching	voltage, current	24 V DC 0.5 A					
	Minimum switching load		5 V DC, 1 mA					
	Response time	OFF to ON	≤ 10 ms					
ERR. terminal	riesponse time	ON to OFF	≤ 12 ms					
ERR. terminal	Life	Mechanical	≥ 20 million times					
		Electrical	Rated switching voltage/current: 10 million times or more					
	Surge suppressor		1					
	Fuse		_					
Applicable wire :	size		0.32.0 mm² (AWG2214) (Twisted wire/Solid wire)					
External interfac	е		Spring clamp terminal block					
5 V DC internal	current consumption	on	0.06 A					
Weight			0.11 kg					

Display Unit

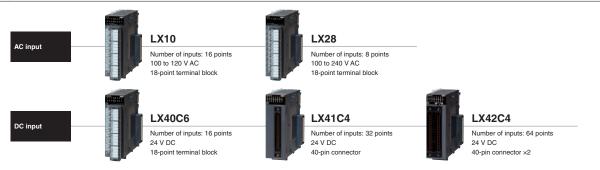


L6DSPU

■ Display Unit specifications

Display Offic specifications	
Item	Specification
Number of displayed characters	16 one-byte characters × 4 lines
	Alphanumeric (two-byte/one-byte character)
	 Japanese character Katakana (two-byte/one-byte character)
Displayed characters	 Japanese character Hiragana (two-byte character)
	 Chinese character (two-byte character)
	 Symbol (two-byte/one-byte character)
Language	Japanese/English
Backlight	Green (normal), red (error)
Weight	0.03 kg

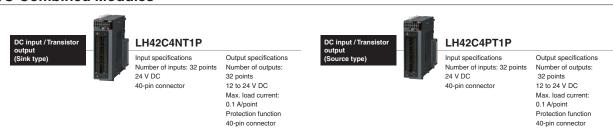
Input Modules



Output Modules



I/O Combined Modules



Spring clamp terminal block (push-in type): L6TE-18S

The screw terminal block of installed modules can be replaced with a push-in type spring clamp terminal block. This terminal block type helps to reduce the amount of wiring and maintenance time.

■ Push-in type for reduced wiring

Easier to wire just by inserting into the terminal block.



■ Simple to confirm signal integrity

Includes dedicated terminals for insertion of a test probe, for example.



5



■ Input module specifications AC input module

	Item	LX10	LX28			
Number of in	put points	16 points	8 points			
Rated input voltage, frequency Input voltage distortion		100120 V AC	100240 V AC			
		(+10%/-15%), 50/60Hz (±3 Hz)	(+10%/-15%), 50/60 Hz(±3 Hz)			
input voitage	distortion		16.4 mA (200 V AC, 60 Hz),			
Rated input current		8.2 mA (100 V AC, 60 Hz), 6.8 mA (100 V AC, 50 Hz)	13.7 mA (200 V AC, 50 Hz), 8.2 mA (100 V AC, 60 Hz), 6.8 mA (100 V AC, 50 Hz)			
Inrush current		Max. 200 mA ≤ 1 ms	Max. 950 mA ≤ 1 ms			
ON voltage/ON current		≥ 80 V AC /≥ 5 mA (50 Hz, 60 Hz)				
OFF voltage/	OFF current	≤ 30 V AC /≤ 1.7 mA (50 Hz, 60 Hz)				
Input resistar	nce	12.2 kΩ (60 Hz), 14.6 kΩ (50 Hz)				
Response	OFF to ON	≤ 15 ms (100 V AC 50 Hz, 60 Hz)	≤ 15 ms (100 V AC 50 Hz, 60 Hz) ≤ 10 ms (200 V AC 50 Hz, 60 Hz)			
time	ON to OFF	≤ 20 ms (100 V AC 50 Hz, 60 Hz)	≤ 20 ms (100/200 V AC 50 Hz, 60 Hz)			
Common tern	ninal arrangement	16 points/common	8 points/common			
Module size a	allocation		1			
Number of oc	ccupied I/O points	16 points (I/O assignment: input 16 points)				
External inter	face	18-point ter	minal block			
5 V DC interr consumption		90 mA (TYP. all points ON)	80 mA (TYP. all points ON)			
Weight		0.17 kg	0.15 kg			

DC input module

DC IIIput IIIodule							
Item	LX40C6	LX41C4	LX42C4				
Number of input points	16 points	32 points	64 points				
Rated input voltage	24 V DC (r	ripple rate: ≤ 5%) (allowable voltage range: 20.42	28.8 V DC)				
Rated input current	6.0 mA TYP. (at 24 V DC)	4.0 mA TYP.	(at 24 V DC)				
ON voltage/ON current	≥ 15 V DC /≥ 4 mA	≥ 19 V D	C/≥ 3 mA				
OFF voltage/OFF current	≤ 8 V DC /≤ 2 mA	≤ 9 V DC	/≤ 1.7 mA				
Input resistance	3.8 kΩ	5.7 kΩ					
Response time OFF to ON ON to OFF		1 ms, 5 ms, 10 ms, 20 ms, 70 ms or less Initial setting is 10 ms.					
Common terminal arrangement	16 points/common	32 points/common					
Module size allocation		1					
Number of occupied I/O points	16 points (I/O allocation: input 16 points)	32 points (I/O assignment: input 32 points)	64 points (I/O allocation: input 64 points)				
External interface	18-point terminal block	40-pin connector	40-pin connector x 2				
5 V DC internal current consumption	90 mA (TYP. all points ON)	100 mA (TYP. all points ON)	120 mA (TYP. all points ON)				
Weight	0.15 kg	0.11 kg	0.12 kg				

■ Output module specifications

Contact outp	out module				
	Item	LY10R2	LY18R2A NEW		
Number of output	points	16 points	8 points		
Rated switching v	roltage, current	24 V DC 2 A (resistive load)/point, 8 A/common 240 V AC 2 A (COSφ=1)/point, 8 A/common	24 V DC 2 A (resistive load)/point, 8 A/module 240 V AC 2 A (COS¢=1)/point, 8 A/module		
Minimum switchin	ng load	5 V D	C 1 mA		
Maximum switching load		264 V AC	125 V DC		
Response time OFF to ON		≤ 1) ms		
nesponse une	ON to OFF	≤ 1:	2 ms		
	Mechanical	≥ 20 mil	ion times		
		Usage environment	Switching life		
		Rated switching voltage/current, rate	d load 100 thousand times		
		200 V AC 1.5 A, 240 V AC 1 A (COSφ	= 0.7) 100 thousand times		
Life	Electrical	200 V AC 0.4 A, 240 V AC 0.3 A (COS	$\phi = 0.7$) 300 thousand times		
	Electrical	200 V AC 1 A, 240 V AC 0.5 A (COSφ	= 0.35) 100 thousand times		
		200 V AC 0.3 A, 240 V AC 0.15 A (CO	$S\phi = 0.35$) 300 thousand times		
		24 V DC 1 A, 100 V DC 0.1 A (L/R =	7 ms) 100 thousand times		
		24 V DC 0.3 A, 100 V DC 0.03 A (L/F	R = 7 ms) 300 thousand times		
Maximum switchin	ng frequency	3600 tir	nes/hour		
Surge suppressor	r	-	=		
Fuse		-	(a fuse is recommended to be installed for each external wirin point)		
Common terminal	l arrangement	16 points/common	No common (all points independent)		
Module size alloca	ation		1		
Number of occupi	ied I/O points	16 points (I/O assignr	nent: 16 output points)		
External interface		18-point te	minal block		
5 V DC internal cu	urrent consumption	460 mA (TYP. all points ON)	260 mA(TYP.all points ON)		
Weight		0.21 kg	0.18 kg		

■ Output module specifications Triac output

iiiao oatpat							
	Item	LY20S6	LY28S1A NEW				
Number of output po	ints	16 points	8 points				
Rated load voltage, f	requency	100240 V AC (+10%/-	-15%), 50/60 Hz(±3 Hz)				
Maximum load curre	nt	0.6 A/point, 4.8 A/common	1 A/point, 8 A/module				
Load voltage distortion	on ratio	≤ 5	5%				
Maximum load voltag	ge	264	V AC				
Minimum load voltag	e/current	24 V AC/100 mA, 100 V A	C/25 mA, 240 V AC/25 mA				
Maximum inrush curi	rent	≤ 20 A	/cycle				
Leakage current at C)FF	≤ 3 mA (at 240 V, 60 Hz), :	≤ 3 mA (at 240 V, 60 Hz), ≤ 1.5 mA (at 120 V, 60 Hz)				
Maximum voltage drop at ON		≤ 1.5 V (at load	≤ 1.5 V (at load current of 0.6 A)				
	OFF to ON	Total of 1 ms and	0.5 cycles or less				
Response time	ON to OFF	Total of 1 ms and 0.5 cycles or	Total of 1 ms and 0.5 cycles or less (rated load, resistive load)				
Surge suppressor		CR ab	CR absorber				
Fuse		None (Attaching a fuse to each e	external wiring is recommended.)				
Common terminal ar	rangement	16 points/common	No common (all points independent)				
Module size allocation	n	1					
Number of occupied I/O points		16 points (I/O assignn	nent: output 16 points)				
External interface		18-point ter	minal block				
5 V DC internal curre	ent consumption	300 mA (TYP. all points ON)	200 mA (TYP. all points ON)				
Weight		0.22 kg	0.19 kg				

Transistor output (Sink type)

ransistor output (Sink type)								
	Item	LY40NT5P	LY41NT1P	LY42NT1P				
Number of output poin	ts	16 points	32 points	64 points				
Rated load voltage			10.228.8 V DC					
Maximum load current		0.5 A/point, 5 A/common	0.1 A/point,	2 A/common				
Maximum inrush curre	nt	Curr	ent is limited by the overload protection fun	ction.				
Leakage current at OFF			≤ 0.1 mA					
Maximum voltage drop	at ON	0.2 V DC(TYP.) 0.5 A, 0.3 V DC(MAX.) 0.5 A		TYP.) 0.1 A, MAX.) 0.1 A				
B	OFF to ON		≤ 0.5 ms					
Response time	ON to OFF		≤ 1 ms (rated load, resistance load)					
Surge suppressor	'	Zener diode						
Fuse		_						
Voltage		12/24 V DC (ripple rate: ≤ 5%) (allowable voltage range: 10.228.8 V DC)						
External power supply	Current	9 mA (at 24 V DC)/common	13 mA (at 24 V DC)/common	9 mA (at 24 V DC)/common				
Common terminal arra	ngement	16 points/common	nmon 32 points/common					
Module size allocation		1						
Number of occupied I/0	O points	16 points (I/O assignment: 16 output points)	32 points (I/O assignment: 32 output points)	64 points (I/O assignment: 64 output points)				
Protection function	Overload protection	Limited current when detecting overcurrent (overload protection): 1.53.5 A/point. Activated in increments of 1 point.		rent (overload protection): 13 A/point.				
	Overheat protection		Activated in increments of 1 point					
External interface		18-point terminal block	40-pin connector	40-pin connector ×2				
5 V DC internal curren	t consumption	100 mA (TYP. all points ON)	140 mA (TYP. all points ON)	190 mA (TYP. all points ON)				
Weight		0.15 kg	0.11 kg	0.12 kg				

Transistor output (Source type)

Transistor output (Source type)								
	Item	LY40PT5P	LY41PT1P	LY42PT1P				
Number of output poir	nts	16 points	32 points	64 points				
Rated load voltage		10.228.8 V DC						
Maximum load current	t	0.5 A/point, 5 A/common	0.1 A/point,	2 A/common				
Maximum inrush current		Curre	ent is limited by the overload protection fund	ction.				
Leakage current at OF	-F		≤ 0.1 mA					
Maximum voltage dro	p at ON	0.2 V DC(TYP.)0.5 A, 0.3 V DC(MAX.)0.5 A						
Decree dine	OFF to ON	≤ 0.5 ms						
Response time	ON to OFF		≤ 1 ms (rated load, resistance load)					
Surge suppressor		Zener diode						
Fuse		_						
External power supply	Voltage	12/24 V DC (ripple rate: ≤ 5%) (allowable voltage range: 10.228.8 V DC)						
External power supply	Current	17 mA (at 24 V DC)/common	20 mA (at 24 V DC)/common					
Common terminal arra	angement	16 points/common	32 points	/common				
Module size allocation	1		1					
Number of occupied I/	/O points	16 points (I/O assignment: 16 output points)	32 points (I/O assignment: 32 output points)	64 points (I/O assignment: 64 output points)				
Protection function	Overload protection	Overcurrent detection: ≥ 1.5 A/point. Activated in increments of 1 point.		vercurrent (overload protection): v/point. ements of 1 point.				
	Overheat protection	Activated in increments of 1 point.	Activated in incre	ments of 2 points.				
External interface		18-point terminal block	40-pin connector	40-pin connector ×2				
5 V DC internal currer	nt consumption	100 mA (TYP. all points ON)	140 mA (TYP. all points ON)	190 mA (TYP. all points ON)				
Weight		0.15 kg	0.11 kg	0.12 kg				

5

MELSEG L series

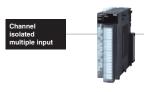
■ I/O combined module specifications DC input/transistor output combined module

Item		LH42C4NT1P	LH42C4PT1P				
■ Input specifications							
Number of input points		32 pc	pints				
Rated input voltage		24 V DC (ripple rate: ≤ 5%) (allowable voltage range: 20.428.8 V DC)					
Rated input current		4.0 mA TYP. (at 24 V DC)					
Input ON voltage/ON curi	rent	≥ 19 V DC	C/≥ 3 mA				
Input OFF voltage/OFF c	urrent	≤ 9 V DC/	'≤ 1.7 mA				
Input resistance		5.7	kΩ				
I	OFF to ON	1 ms, 5 ms, 10 ms, 2	0 ms, 70 ms or less				
Input response time	ON to OFF	(Initial setting	g is 10 ms)				
Input common terminal a	rrangement	32 points/	common				
■ Output specifications							
Output format		Transistor output combined module (Sink type)	Transistor output combined module (Source type)				
Number of output points		32 pc	pints				
Rated load voltage		10.228.8 V DC					
Maximum load current		0.1 A/point, 2 A/common					
Maximum inrush current		Current is limited by the overload protection function.					
Leakage current at OFF		≤ 0.1 mA					
Maximum voltage drop at	· ON	0.1 V DC (TYP.) 0.1 A,					
waximum voitage drop at	ON	0.2 V DC (MAX.) 0.1 A					
Output response time	OFF to ON	≤ 0.5	ms				
Output response time	ON to OFF	≤ 1 ms (rated load	, resistance load)				
Surge suppressor		Zener diode					
Fuse		_					
Protection function	Overload protection	Limited current when detecting overcurrent (overload pro	tection): 13 A/point, activated in increments of 1 point				
- Totection function	Overheat protection	Activated in increments of 1 point	Activated in increments of 2 points				
Output common terminal	arrangement	32 points/	common				
■ Common specifications	3						
External power supply	Voltage	12/24 V DC (ripple rate: ≤ 5%) (allowa	ble voltage range: 10.228.8 V DC)				
External power supply	Current	9 mA (at 24 V DC)/common	20 mA (at 24 V DC)/common				
Module size allocation		1					
Number of occupied I/O p	points	32 points (I/O assignment	t: input/output 32 points)				
External interface		40-pin con	nector ×2				
5 V DC internal current co	onsumption	160 mA (TYP. all points ON)	150 mA (TYP. all points ON)				
Weight		0.12	kg				

For inpu	ut mod	lule or o	utput m	odule			• For I/	O com	bined mod	dule														
L	Y 4 0			NT	5	P	L	Н	4	2	C4	N	T1	P										
	1	2	3	4	(5)	6		1	2	3	Input type ④ ⑤		tput type ④ ⑤	6										
Number		Item		Code					Specific	ation														
				Х					Inpu	ıt														
1	Mod	ule type		Υ					Outp	ut														
				Н					I/O com	bined														
Number		Item		Code		Input spe	cifications			(Output speci	ification	s											
vuilibei		пеш		Code	AC i	nput	DC input	t	Contact	output	Triac ou	tput	Transisto	or output										
2	Volta	Voltage specification		1	10012		_		24 V DC/24	40 V AC			_	_										
				2	10024	10 V AC	_				100240	VAC	_	_										
				4	_	_	24 V DC						1224	V DC										
Number		Item		Code	de Specification																			
				0		16 points																		
3	I/O n	oints		1	32 points																			
				2					64 poi															
	_			8					8 poir															
Number		Item		Code					Specific															
				Blank					AC in															
				С							ed commor	1)												
4	I/O ty	уре		NT		Transistor output module (Sink type)																		
				PT R	Transistor output module (Source type) Contact output																			
				S					Triac or															
														3					THAC O					
Number	per Item		r Item	per Item		ber Item		Code			cifications		Comtont		Output spec									
				1	AC i	nput _	DC input		Contact	output	Triac ou	•	Transisto 0.1											
				2					2 A				0.1											
(5)	Curr			4	_	_	4 mA			•	_			_										
	spec	ification		5	_	_	_				_		0.5	i A										
				6			6 mA				0.6	1												

Independent common

Multiple Input (Voltage/Current/Temperature) Module



L60MD4-G NEW

Number of inputs: 4 channels Input voltage: -10 to 10 V DC Input current: 0 to 20 mA DC

Input micro voltage: -100 to 100 mV
Input thermocouple: K, J, T, E, N, R, S, B, U, L, PL II, W5Re/W26Re

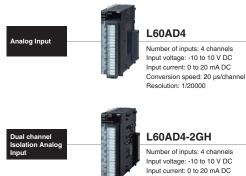
Input RTD: Pt1000, Pt100, JPt100, Pt50 Conversion speed: 50 ms/channel

Resolution

Voltage/Current/micro voltage: 1/20000
Thermocouple: B, R, S, N, PL II , W5Re/W26Re: 0.3°C,
K, E, J, T, U, L: 0.1°C

RTD: Pt100, JPt100: 0.03°C/0.1°C, Pt1000, Pt50: 0.1°C

Analog Input Modules



L60ADVL8 NEW

Number of inputs: 8 channels Input voltage: -10 to 10 V DC Input voltage: -10 to 10 V DC Conversion speed: 1 ms/channel



L60ADIL8 NEW

Number of inputs: 8 channels Input current: 0 to 20 mA DC Conversion speed: 1 ms/channel

Analog Output Module



L60DA4

Number of outputs: 4 channels Output voltage: -10 to 10 V DC Output current: 0 to 20 mA DC Conversion speed: 20 µs/channel Resolution: 1/20000

Conversion speed: 40 µs/2 channels Resolution: 1/32000

Analog I/O Module



L60AD2DA2

Analog input specifications Number of inputs: 2 channels Input voltage: -10 to 10 V DC Input current: 0 to 20 mA DC Conversion speed: 80 µs/channel Resolution: 1/12000

Analog output specifications Number of outputs: 2 channels Output voltage: -10 to 10 V DC Output current: 0 to 20 mA DC Conversion speed: 80 µs/channel Resolution: 1/12000

MELSEG L series

■ Multiple/analog input features

Function		Multiple input (voltage/ current/temperature) module		Analog in	out module		Analog I/O module	
i unction			L60MD4-G NEW	L60AD4	L60ADVL8 NEW	L60ADIL8	L60AD4-2GH	L60AD2DA2
Channel isolation			•	_	_	_	●*1	_
	Sampling p	rocessing	•	•	•	•	•	•
	Averaging processing	Time average	•	•	•	•	•	•
AD conversion method		Count average	•	•	•	•	•	•
		Moving average	•	•	•	•	•	•
Time lag filter function		_		_	_	•	_	
Digital filtering function	Digital filtering function		_	_	_	_	•	
Conversion speed switch	function		_	•	_	_	_	_
Input range extended mo	de function		•	●*2	•	•	•	•
Maximum value/minimun	n value hold f	unction	•	•	•	•	•	•
Disconnection detection	function		•	_	_	_	_	_
Input signal error detection			•	•	•	•	•	•
Input signal error detection	on extension	function	_	●*2	•	•	_	_
Warning output function	Process ala	ırm	•	•	•	•	•	
	Rate alarm		•	_	_	_	•	_
Scaling function		•	•	•	•	•	•	
Shift function		—,3	●*2	—*3	*3	•	*3	
Digital clipping function		—,3	•	*3	*3	•	*3	
Difference conversion function		_*3	●*2	*3	*3	•	*3	
Logging function		*4	●*2	*4	*4	•	•	
Flow amount integration			_	●*2	_	_	_	
Trigger conversion functi	on		_	_	_	_	•	_

■ Analog output features

	- - - - - -	Analog output module	Analog I/O module
i dilotion		L60DA4	L60AD2DA2
Analog output HOLD/	CLEAR function	•	•
Scaling function		•	•
Warning output function	Process alarm	•	•
Wave output function		●*5	•
	Wave output step action function	• '5	•

^{*5:} Supported by models whose first five serial number digits are "14041" or later.

^{*1:} Every two channels are isolated. (CH1 and CH2 are isolated from CH3 and CH4).
*2: Supported by models whose first five serial number digits are "13041" or later.
*3: Please use function blocks (FB) for the shift function, digital clipping function, and difference conversion function. The function blocks (FB) can be downloaded for free from the MELSOFT Library on the Mitsubishi Electric FA site.

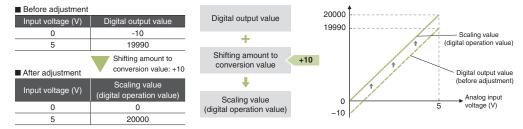
^{*4:} For logging, please use the data logging function of the CPU module.

Easily and finely adjust the system startup time with the shift function

Shift function

Using this function, the set shifting amount to conversion value can be added (shifted) to the digital output value. When the shifting amount to conversion value is changed, it is reflected to the scaling value (digital operation value) in real time. Therefore, fine adjustment can be easily performed when the system starts.

For L60AD4

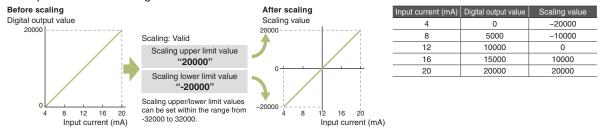


Reduce the time taken for programming

Scaling function

The scaling function converts values directly to easy-to-understand units without requiring any programming. Since a separate conversion program is not required, the number of overall programming steps can be reduced. Scaling settings example (L60AD4)

Normally an analog input of 4 to 20 mA is converted to a digital value from 0 to 20000. Using the scaling feature, the same input can result in a digital value of ±20000.



Digital filtering function

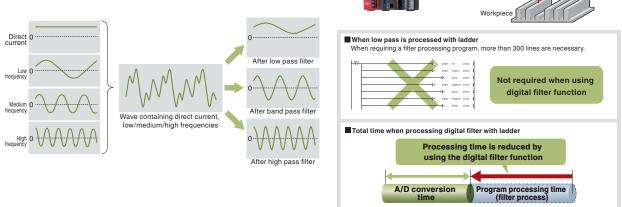
This function eliminates unnecessary frequency elements with simple parameter settings. Select from low pass filter, high pass filter or band pass filter.

Programming steps can be further reduced as extra ladder code is not required to achieve the filter processing.

The filtered A/D conversion program is available at the same time as conversion completion, reducing the overall conversion to filter process time.

Measurement of flatness

Sensor



First-delay filter function

The first-delay filter function constant outputs a digital value which filters out (smooths) the excessive noise.



Log data for up to 10,000 points

Logging function

Data is continuously collected at the set cycle and stored in the buffer memory.

Data stored in the buffer memory can be used for debugging, and to periodically confirm data variations.

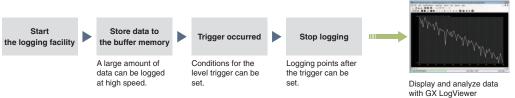
Description					
L60AD4	L60AD4-2GH	L60AD2DA2			
10	0000 points/chann	el			
Digital or	utput value or scal	ing value			
(digital operation value)					
8032767 μs	4032767 μs	8032767 μs			
132767 ms	132767 ms	132767 ms			
13600 s	13600 s	13600 s			
80 μs, or 1 ms	40 µs/2 channels	80 µs			
Above, Below, Pass Through					
110000					
	Digital or (di 8032767 μs 132767 ms 13600 s 80 μs, or 1 ms	10000 points/chann Digital output value or scal (digital operation valt 8032767 µs 4032767 µs 132767 ms 132767 ms 13600 s 13600 s 80 µs, or 1 ms 40 µs/2 channels Above, Below, Pass Th			

^{*1:} The actual logging cycle is "an integral multiple of the conversion cycle of each A/D conversion method".

Ex.) When using the sampling processing: Conversion cycle = conversion speed × number of channels in use.

When an error is detected in the digital value:

The logging data can be analyzed with the GX LogViewer.

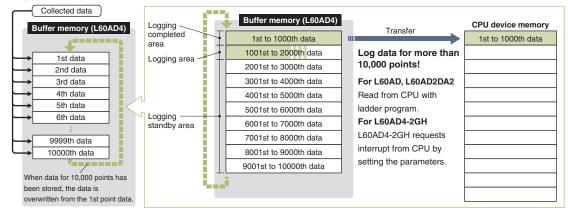


Logging data can be transferred to the CPU device memory while still logging.

Logging and data transmission can be executed simultaneously so the next logging session can be started right away.

Logging for 10,000 points and greater

When logging of 1001 - 2000 points of data commences, the first 1000 points (1 - 1000) are stored into the CPU device memory. By storing every 1000 points of data in the CPU, overall logging of total data larger than 1000 points can be logged.



Easily measure part thicknesses!

Difference conversion function

When the difference conversion starts, the scaling value (digital operation value) at that time is determined as the difference conversion reference value. The value acquired by subtracting the difference conversion reference value from the scaling value (digital operation value) is stored as the scaling value (digital operation value) after difference conversion.

For L60AD4 Scaling value (digital operation value) 20000 Difference conversion Scaling value reference value (digital operation value) 10000 7500 2500 Time Difference conversion No request (0) No request (0) Trigger request (1) trigge



Extend the detection method according to applications

Input signal error detection extension function

Using this function, the detection method of the input signal error detection function can be extended. Use this function to detect an input signal error only at the lower or upper limit, or to execute the disconnection detection.

Input range extension function

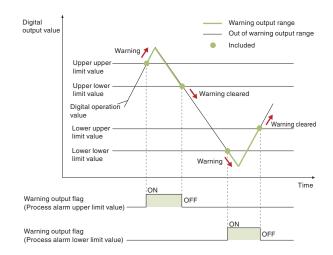
The input range can be extended. By combining this function with the input signal error detection function, simple disconnection detection can be executed.

Connected devices monitoring alarm

Warning output function

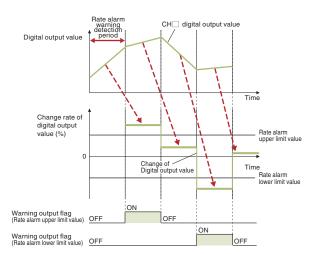
■ Process alarm

Outputs an alarm when the digital output value enters a preset alarm range.



■ Rate alarm

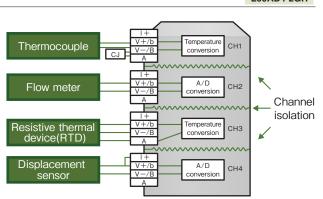
An alarm is generated if the digital output value's variation rate is larger than the rate alarm upper limit value, or if it is smaller than the rate alarm lower limit value.



Noise isolation for smoother system operation

Channel isolation

Each channel is isolated preventing any noise interference between channels resulting in more stable measurements.



L60AD4-2GH

0

MELSEG L series

A/D variable conversion timing

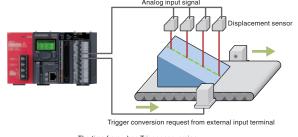
Trigger conversion function

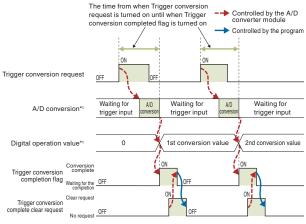
A/D conversion is processed at the rising edge of the trigger position timing.

This function enables easier use of the converter and enhances the overall program performance.

There are two types of trigger conversion request:

"External trigger conversion request (external input terminal)" or "internal trigger conversion request (buffer memory)".





 * 1: Carried out in order with combination of channel 1, channel 3 and channel 2, channel 4.

Quickly calculate and record flow amount

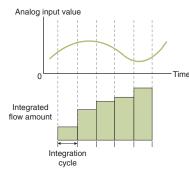
Flow amount integration function

This function performs the A/D conversion of analog input value (voltage or current) from a flow meter and others, and integrates the scaling value (digital operation value) by every integration cycle. In this function, integral processing is performed regarding the scaling value (digital operation value) as the instantaneous flow amount.

■ Concept of integral processing

With this function, integral processing is performed using the following formula.

Integrated flow amount =
$$\begin{pmatrix} Instantaneous \\ flow amount \end{pmatrix} \times \frac{\Delta T}{T} \times Unit scaling + Previous amount$$



Item		Description						
Integrated flow amount	Re	Result of integral processing						
Instantaneous flow amount	Ins	tantaneous flow amount	value output in analog from flow meter					
ΔΤ	Inte	egration cycle (ms)						
	Co	nversion value to convert	time unit of instantaneous flow amount to ms unit					
		Range of flow meter	Setting value to specify flow amount time unit	T (ms)				
Т		/s	0	1000				
		/min	1	60000				
		/h	2	3600000				
	Unit scaling for integrated flow amount							
	This is used when the value of instantaneous flow amount $\times \Delta T/T$ is 0 to 1.							
		Set	Unit scaling					
			1					
Unit scaling			10					
			100					
			1000					
			4	10000				
Previous amount	Sto	Stored integrated flow amount value before integral processing						

Realize fast and smooth continuous analog output

Wave output function

The industry's first*1 waveform output function is included.

This function enables control wave data that is faster than the program control to be directly registered in the D/A converter module and output the data at a set conversion cycle.

Therefore, the analog output value is not affected by the scan time of the CPU module resulting in faster and smoother analog control.

*1: Mitsubishi Electric survey dated April 2012.

Analog output from sequence program

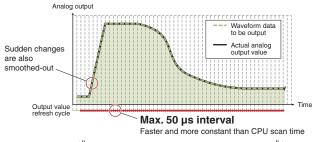
Analog values are output at each scan time. Analog output --- Waveform data to be output --- Actual analog output value

Output value refresh cycle

Varies depending on scan time

Analog output with waveform output function

Analog values are output at set interval.

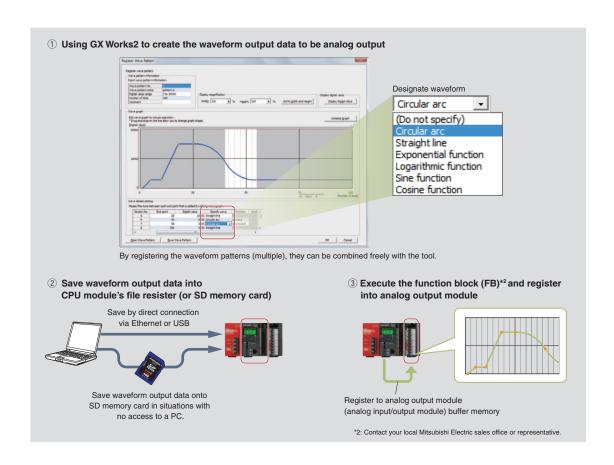


Register up to 50000 points of waveform output data

The actual waveform and the output waveform deviate.



The output waveform is closer to the actual waveform (less deviation).



0

CPU



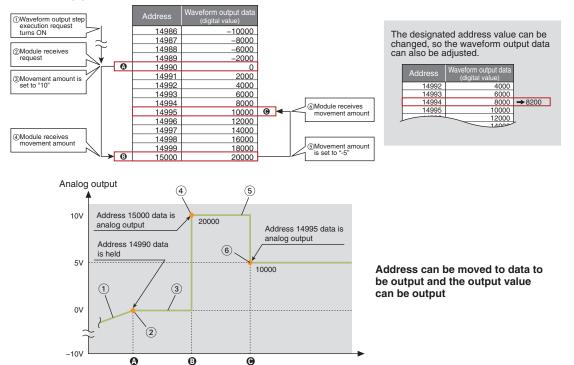
Easily adjust waveform output data

Wave output step action function

The waveform output data can be changed even when the analog output module is in conversion. This provides a good way of adjusting the waveform output while in operation.

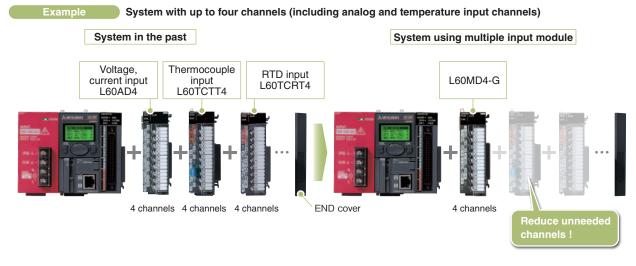
Analog output a designated buffer memory's address value

If current address is "14990" (4) the output range is set to -10 to 10V range and receives "waveform output step execution request", the address 15000 (6) and address 14995 (6) data is executed.



One module covering voltage, current, micro-voltage, thermocouples and RTD

For each channel, it is possible to select from voltage, current, micro-voltage, thermocouples or RTD. As a result, dedicated modules required for each type of sensor can now be integrated into a single module.



The multiple input module also supports the Pt50 and JPt100 sensors, which are compatible with the former JIS standards. Modules can be replaced without altering the already existing sensor equipment.

Thermocouple	K, J, T, E, N, R, S, B, U, L, PL II, W5Re/W26Re
Resistive thermal device	Pt1000, Pt100, JPt100, Pt50

■ Multiple input (voltage/current/temperature) module specifications

	Item					G NEW			
Number of a	nalog input channels				4 char				
	Voltage	-1010 V DC (Input resistance value 1 MΩ)							
	Current					sistance value 250 Ω)			
	micro voltage	-100100 mV DC							
Analog input	Thermocouple	Available type K, J, T, E, N, R, S, B, U, L, PL II, W5Re/W26Re							
		Cold junction compensation resistor					cold junction compensation	resistor (CJ)	
Resistive thermal device			ailable	,,		Pt1	000, Pt100, JPt100, Pt50		
				t method			3-wire system		
				micro voltage		-2048020479			
Digital outpu	t			mal device Pt100 (-20120°C)		-200020000: Value rounded off to two decimal places × 100 tir			
		Thermocouple, Resistive th			01(0)	4000 32000: Value	rounded off to one decimal p	laco v 10 timos	
	When using the scaling function	Thermocoupie, nesistive th	emai			32767	Tourided on to one decimal p	nace x 10 times	
	When using the scaning function		A I -		_		Daniel diese	1	
			$\overline{}$	g input range 10 V	<u> </u>	Digital output value 020000	Resolution 500 µV	•	
			0				'	-	
		Voltage	1		_	020000	250 μV 200 μV	1	
		Vollage	_	10 V		-2000020000	200 μV 500 μV	+	
			_	5 V (Extended mode)		-500022500	200 μV	-	
			_	20 mA		-300022300	1000 μV	-	
		Current	_	20 mA	1	020000	800 nA	_	
/O characte	ristics, resolution	Current	_	20 mA (Extended mode)		-500022500	800 nA	-	
		micro voltag	_	,		-2000020000	5 μV	1	
					B, R, S, N, PL II, W5Re/W26Re: 0.3°C		1		
		Thermocouple				K, E, J, T, U, L: 0.1°C			
						Pt100 (-20)120°C),	1	
		Reciptive the	armal o	device (RTD)		JPt100 (-20120°C) : 0.03°C			
		Tresistive the	siiiai C	device (NTD)		Pt100 (-200850°C),			
		JPt100 (-200600°C)), Pt1000, Pt50: 0.1°C]	
				Ambient temperature 26		Maximum value of the measurement]	
		Voltage/Curr	rent/	Ambient temperature 25		rar	nge× (± 0.3%)		
		micro voltag	е	Ambient temperature 0.		'C:	lue of the measurement		
				·		range× (± 0.9%)			
		Thermocoup	ole	Ambient temperature 25 ±		` '			
				Ambient temperature 055		` ′		_	
Accuracy*1*2				Temperature measured		alue: ≤ ± 1.0°C			
Accuracy		Cold junction	n	-100°C or higher Temperature measure		0.		-	
		compensation	on	-150°C100°		е.	≤ ± 2.0°C		
		resistor*4		Temperature measure		ie.		1	
				-200°C150°		≤ ± 3.0°C			
				(Accuracy) *5 = (Conv	versior	on accuracy) + (Temperature characteristics) ×			
		Resistive the device	ermai	(Ope	rating	ating ambient temperature change)			
		device		+ (Allowable diffe	erence	of resistance tempera	ature detector used)		
Conversion s	speed				50 m	s/ch			
Output curre	nt for temperature detection	Pt100, JPt100, Pt50: 1 mA, Pt1000: 0.2 mA							
Absolute ma	ximum input					Current: 30 mA ⁻⁶			
Isolation met	thod	Between I/O terminals and programmable controller power supply: photocoupler isolation Between input channels: transformer isolation							
Number of o	ccupied I/O points	16 points (I/O assignment: 16 points for intelligent)							
External inte		18-point terminal block							
5 V DC inter	nal current consumption				0.49	9 A			
Weight					0.19) kg			

^{*1:} Except when influenced by noise.

^{*4:} The following table shows the accuracy of the cold junction compensation for when the type "T" thermocouple or type "U" thermocouple is used.

Measured temperature	T Thermocouple	U Thermocouple
0°C or higher	± 1.0°C	
-100°C0°C	± 2.0°C	
-150°C100°C	± 3.0°C	
-200°C150°C	± 5.0°C	± 4.0°C

*5: The following table shows RTD types and values for each item.

-							
		Celsius		Fahrenheit			
RTD type	Measured temperature range	Conversion accuracy (operating ambient temperature: 25±5°C)	Temperature characteristics (for a change of 1°C in the operating ambient temperature)	Measured temperature range	Conversion accuracy (operating ambient temperature: 25±5°C)	Temperature characteristics (for a change of 1°C in the operating ambient temperature)	
Pt100	-20120°C	1°C	0.1°C	0200°F	1°F	0.1°F	
PIIOU	-200850°C	2°C	0.2°C	-3001500°F	3°F	0.3°F	
JPt100	-20120°C	1°C	0.1°C	0200°F	1°F	0.1°F	
JF1100	-200600°C	2°C	0.2°C	-3001100°F	3°F	0.3°F	
Pt1000	-200850°C	2°C	0.2°C	-3001500°F	3°F	0.3°F	
Pt50	-200650°C	2°C	0.2°C	-3001200°F	3°F	0.2°F	

• Allowable difference of Pt100 (JIS C 1604-1997, IEC 751 1983)

Class	Allowable difference			
A	± (0.15 + 0.002 ltl)°C			
В	± (0.3 + 0.005 t)°C			

Class	Allowable difference
0.15	± (0.15 + 0.0015 ltl)°C
0.2	± (0.15 + 0.002 ltl)°C
0.5	± (0.3 + 0.005 ltl)°C

The allowable difference of Pt1000 is not provided in the JIS standard, and therefore is not described here. Please contact your Mitsubishi Electric or local sales representative for further details

^{*2:} To acquire sufficient accuracy, a warm-up (conduction) for 15 minutes is required.

^{*3:} The accuracy for when the measured temperature of the type W5Re/W26Re thermocouple is 2000°C or higher is ±0.5%.

^{*6:} A momentary current value which does not cause damage to internal resistors of the module, although the maximum continuous input current is 24 mA.

MELSEG L series

■ Analog input module specifications

- 1	60	Λ	n	1

Item		L60AD4							
Number of analog input channels		4 channels							
Analog input	Voltage	-1010 V DC (Input resistance value 1 $M\Omega$)							
Analog input	Current	020 mA DC (Input resistance value 250 Ω)							
Digital		-2048020479							
output	When using the scaling function	-3276832767							
				Analog input range	Digital output value	Resolution			
				010 V		500 μV			
		Voltad		05 V	020000	250 μV			
			ltaga [15 V		200 μV			
		Voi	lage	-1010 V	-2000020000	500 μV			
I/O character	ristics, resolution			15 V (Extended mode)	-500022500	200 μV			
			Users range setting	-2000020000	307 μV ^{*1}				
				020 mA	020000	1000 nA			
		Cur	Current -	420 mA		800 nA			
		Cui	TI CITE	420 mA (Extended mode)	-500022500	800 nA			
				Users range setting	-2000020000	1230 nA*1			
Accuracy*2	Ambient temperature 25 ± 5°C	≤ ± 0.1% (± 20 digit)							
Accuracy -	Ambient temperature 055°C								
Conversion s	speed*3*4*5	High speed: 20 µs/channel Medium speed: 80 µs/channel Low speed: 1 ms/channel							
Absolute max	ximum input	Voltage: ± 15 V, Current: 30 mA ⁺⁶							
Isolation met	hod	Between I/O terminals and programmable controller power supply: photocoupler isolation							
isolation met	nod	Between input channels: no isolation							
Maximum number of modules specification		Counts as 1 module							
Number of od	ccupied I/O points	16 points (I/O assignment: 16 points for intelligent)							
External inter	rface	18-point terminal block							
5 V DC interr	nal current consumption	0.52 A							
Weight		0.19 kg							

L60ADVL8

	Item	L60ADVL8 NEW							
Number of ar	nalog input channels	8 channels							
Analog input	Voltage	-1010 V DC (Input resistance value 1 MΩ)							
Digital		-1638416383							
output	When using the scaling function	-3276832767							
			Analog input range	Digital output value	Resolution				
			010 V	016000	625 μV				
			05 V	0 0000	625 μV				
I/O characteristics, resolution		Valtage	15 V	08000	500 μV				
		Voltage	-1010 V	-1600016000	625 μV				
			15 V(Extended mode)	-20009000	500 μV				
			Users range setting	-80008000	414 μV ⁻¹				
	Ambient temperature 25 ± 5°C		≤ ± 0.2%						
Accuracy*2	Ambient temperature 055°C	≤ ± 1%							
Conversion s	peed*3*4*5	1 ms/ch							
Absolute max	kimum input	Voltage ± 15 V							
Isolation met	had	Between I/O terminals and programmable controller power supply: photocoupler isolation							
isolation meti	Tiou	Between input channels: no isolation							
Maximum nu	mber of modules specification	1							
Number of occupied I/O points		16 points(I/O assignment: 16 points for intelligent)							
External inter	rface	18-point terminal block							
5 V DC internal current consumption		0.20 A							
Weight		0.19 kg							

L60ADIL8

	Item	L60ADIL8 NEW							
Number of a	nalog input channels	8 channels							
Analog input	Current	020 mA DC (Input resistance value 250 Ω)							
Digital		-81928192							
output	When using the scaling function	-3276832767							
I/O characteristics, resolution				Analog input range	Digital output value	Resolution			
				020 mA	08000	2500 nA			
			Current	420 mA	06000	2000 nA			
			Current	420 mA(Extended mode)	-20009000	2000 nA			
				Users range setting	-80008000	1660 nA ⁻¹			
Accuracy*2	Ambient temperature 25 ± 5°C	≤ ± 0.2%							
	Ambient temperature 055°C			≤ ± 1%					
Conversion s	speed*3*4*5	1 ms/ch							
Absolute maximum input		Current 30 mA ^{*6}							
Isolation met	thod	Between I/O terminals and programmable controller power supply: photocoupler isolation							
130IALIOIT IIICI	niod	Between input channels: no isolation							
Maximum nu	imber of modules specification	1							
Number of o	ccupied I/O points	16 points (I/O assignment: 16 points for intelligent)							
External interface		18-point terminal block							
5 V DC inter	nal current consumption	0.21 A							
Weight		0.19 kg							
*1. Maximum	resolution in the user range setting								

^{*1:} Maximum resolution in the user range setting.
*2: Accuracy for the maximum value of the digital output value. Except when influenced by noise.
*3: The default value is 80 µs/channel.

^{*4:} The logging function can be used only in the middle speed (80 µs/channel) or low speed (1 ms/channel).

^{*5:} The flow amount integration function can be used only in the low speed (1 ms/channel).

^{*6:} A momentary current value which does not cause damage to internal resistors of the module, although the maximum continuous input current is 24 mA.

■ Dual channel isolation analog input module specifications

Item			L60AD4-2GH							
Number of analog input channels			4 channels							
Analog Voltage			-1010 V DC (Input resistance value 1 MΩ)							
input	Current		020 mA DC (Input resistance value 250 Ω)							
Di in I		-3200032000								
Digital output When using the scaling function			-3276832767							
				010 V	032000	312.5 μV				
				05 V		156 µV				
			Ve	oltono	15 V		125 µV			
			Voltage	-1010 V	-3200032000	312.5 μV				
I/O characterist	tics, resolution				15 V (Extended mode)	-800032000	125 µV			
					Users range setting (Bipolar: voltage)	-3200032000	200 μV*1			
					020 mA	032000	625 nA			
			C	urrent	420 mA		500 nA			
				420 mA (Extended mode)	-800032000	500 nA				
			L	Users range setting (Unipolar: Current)	032000	400 nA*1				
Accuracy*2	Reference accurac	cy*3	≤ ± 0.05% (± 16 digit)							
Accuracy -	Temperature coefficie	nt*4	≤ ± 40.1 ppm/°C							
Conversion speed			40 μs/2 channel							
Absolute maximum input			Voltage: ± 15 V, Current: 30 mA*5							
Isolation method			Between I/O terminals and programmable controller power supply: photocoupler isolation Between analog input channels: dual channel transformer isolation							
Maximum numl	ber of modules spe	ecification	Counts as 1 module							
Number of occi	upied I/O points		16 points (I/O assignment: 16 points for intelligent)							
External interfa	ce		18-point terminal block							
5 V DC internal	current consumpt	ion	0.76 A							
Weight			0.20 kg							
	Input points		1 point							
	Rated input	voltage		24 V DC (+ 20%/-15%, r	pple ratio: ≤ 5%)					
	Rated input	current		6.0 mA TYP. (at 24 V DC)						
External trigger	ON voltage/ON current		≥ 13 V, ≥ 3 mA							
input	OFF voltage/OFF current		≤ 8 V, ≤ 1.6 mA							
	Input resista	nce	$3.9\mathrm{k}\Omega$							
	Response	OFF to ON	40 µs							
	time	ON to OFF	40 µs							

0.05% + 0.00401%°C (temperature coefficient) \times 5°C (temperature change) = 0.070%

■ Analog output module specifications

Item		L60DA4								
Number of analog output channels		4 channels								
Digital input		-2048020479								
Digital input	When using the scaling function	-3276832767								
Analog	Voltage	-1010 V DC (External load resistance value 1 kΩ1 MΩ)								
output	Current	020 mA DC (External load resistance value 0 $\Omega600~\Omega$)								
			An	nalog output range	Digital value	Resolution				
				05 V	020000	250 μV				
			Voltage	15 V		200 μV				
I/O characteri	istics, resolution		Voltage	-1010 V	-2000020000	500 μV				
,, 0 0 1 1 1 1 1 1 1 1	1000, 1000, 100			Users range setting		333 µV [*] ⁵				
				020 mA	020000	1000 nA				
			Current	420 mA		800 nA				
				Users range setting	-2000020000	700 nA*6				
Accuracy*7	Ambient temperature 25 ± 5°C	≤ ± 0.1%								
Accuracy '	Ambient temperature 055°C	≤ ± 0.3%								
Conversion	Normal output mode	20 μs/channel								
speed	Wave output mode			50 μs/chani	nel 80 µs/channel					
Output short	protection	Protected								
		Between I/O terminals and programmable controller power supply: photocoupler isolation								
Isolation meth	hod	Between output channels: no isolation								
		Between external power supply and analog output: transformer isolation								
	mber of modules specification	Counts as 1 module								
	ccupied I/O points	16 points (I/O assignment: 16 points for intelligent)								
External inter	face	18-point terminal block								
		24 V DC (+ 20%/-15%)								
External now	or supply	Ripple, spike 500 mV _{p-p} or lower								
External power supply		Inrush current: 4.3 A, 1000 μs or shorter								
		Current consumption: 0.18 A								
5 V DC intern	al current consumption	0.16 A								
Weight		0.20 kg								
*6: Maximum	resolution in the user range setting	·	-		·					

^{*6:} Maximum resolution in the user range setting.

^{*1:} Maximum resolution in the user range setting.
*2: Accuracy for the maximum value of the digital output value. Except when influenced by noise.

^{*3:} Accuracy under the ambient temperature when the offset/gain setting is performed.

^{*4:} Accuracy when the temperature changes 1°C.

Example: Accuracy when the temperature changes from 25°C to 30°C

^{*5:} A momentary input current value which does not cause damage to internal resistors of the module. The maximum input current value for constant application is 24 mA.

^{*7:} Accuracy for the maximum value of analog output value. Except when influenced by noise. Warm up (power on) the module for 30 minutes to satisfy the accuracy shown in the table.

MELSEG L series

■ Analog input/output module specifications

= A/D	Item		L60	0AD2DA2			
A/D conve				ala a sa a d			
	analog input channels			channels	MO		
Analog	Voltage			ut resistance value 1			
nput	Current			ut resistance value 25	0 (2)		
Digital	When using the		-163	88416383			
output	scaling function		-327	'6832767			
		Ana	log input range	Digital output value	Resolution		
			010 V	016000	625 μV		
			05 V		416 μV		
			15 V	012000	333 µV		
		Voltage	-1010 V	-1600016000	625 μV		
O characteristics, resolution			15 V	-300013500	222.41		
			(Extended mode)	-300013500	333 µV		
			Users range setting	-1200012000	321 μV*1		
			020 mA	012000	1666 nA		
			420 mA	012000	1333 nA		
		Current	420 mA	-300013500	1333 nA		
			(Extended mode)				
			Users range setting	-1200012000	1287 nA*1		
		_Ana	log input range	Ambient temp			
		Alla		25 ± 5°C	055°C		
			010 V	≤ ± 0.2%	≤ ± 0.3%		
			-1010 V	/ 0			
		Voltage -	05 V	_			
ccuracy*2		""	15 V	-			
			15 V				
		<u> </u>	(Extended mode)	≤ ± 0.2%	≤ ±0.3%		
			020 mA	-			
		Current -	420 mA	-			
			420 mA				
````			(Extended mode)	us/shannal			
onversion				us/channel			
	aximum input		voitage: ± 15	V, Current: 30 mA*3			
	ersion part analog output channels		2	channels			
iuiiibei oi a	analog output charmers	-1638416383					
Digital input	When using the						
rigital ilipat	scaling function		-3276832767				
Analog	Voltage	-1010 V DC (External load resistance value 1k to 1M $\Omega$ )					
output	Current	020 mA DC (External load resistance value 0 to $600 \Omega$ )					
		Anal	og output range	Digital value	Resolution		
			05 V		416 μV		
			15 V	012000	333 μV		
		Voltage	-1010 V	-1600016000	625 μV		
O characte	eristics, resolution		Users range setting	-1200012000	319 µV*1		
			020 mA		1666 nA		
		Current	420 mA	012000	1333 nA		
			Users range setting	-1200012000	696 nA*1		
				Ambient temp			
		Anal	og output range	25 ± 5°C	055°C		
					- 000 0		
			05 V				
ocuraou*?		Voltage	05 V 15 V	≤ ± 0.2%	≤ ± 0.4%		
Accuracy*2		Voltage	15 V	≤ ± 0.2%			
Accuracy*2		Voltage	15 V -1010 V		≤ ± 0.4% ≤ ± 0.4%		
Accuracy*2		Voltage Current -	15 V -1010 V 020 mA	≤ ± 0.2%			
	l.		15 V -1010 V	≤ ± 0.2% ≤ ± 0.2%	≤ ± 0.4%		
onversion			15 V -1010 V 020 mA 420 mA	≤ ± 0.2% ≤ ± 0.2% ≤ ± 0.2%	≤ ± 0.4%		
Conversion	Wave output mode		15 V -1010 V 020 mA 420 mA	$\leq \pm 0.2\%$ $\leq \pm 0.2\%$ $\leq \pm 0.2\%$ $us/channel$	≤ ± 0.4%		
Conversion peed Output shor	Wave output mode		15 V -1010 V 020 mA 420 mA	≤ ± 0.2% ≤ ± 0.2% ≤ ± 0.2%	≤ ± 0.4%		
Conversion peed Output shor	Wave output mode	Current -	15 V -1010 V 020 mA 420 mA	≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  us/channel	≤ ± 0.4% ≤ ± 0.4%		
Conversion speed Dutput shor	Wave output mode t protection part	Current -	15 V -1010 V 020 mA 420 mA	≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  us/channel  rotected  e controller power sup	≤ ± 0.4%  ≤ ± 0.4%		
Conversion peed Dutput shor	Wave output mode t protection part	Current -	15 V -1010 V 020 mA 420 mA 80 µ P	≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  us/channel  rotected  e controller power sup	≤ ± 0.4%  ≤ ± 0.4%		
Conversion peed Dutput shor Common solation me	Wave output mode t protection part	Current -	15 V -1010 V 020 mA 420 mA  80 p P  Ils and programmable Between output ternal power supply a	≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  us/channel  rotected  e controller power sup t channels: no isolation and analog output: tra	≤ ± 0.4%  ≤ ± 0.4%		
Conversion speed Dutput shor Common solation me	Wave output mode t protection part ethod umber of modules	Current -	15 V -1010 V 020 mA 420 mA  80 p P  Ils and programmable Between output ternal power supply a	≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  us/channel  rotected  e controller power sup	≤ ± 0.4%  ≤ ± 0.4%		
Conversion speed Dutput shor Common solation me	Wave output mode t protection part  ethod  umber of modules	Between I/O termina Between ex	15 V -1010 V 020 mA 420 mA  80 p P  Ils and programmable Between output ternal power supply a	≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  us/channel  rotected  e controller power sup t channels: no isolation and analog output: tra s as 1 module	≤±0.4% ≤±0.4%		
Conversion speed Dutput shore Common solation me	Wave output mode It protection part ethod  umber of modules n occupied I/O points	Between I/O termina Between ex	15 V -1010 V 020 mA 420 mA  80 p  P  Ils and programmable Between output ternal power supply a  Counts 6 points (I/O assignn	≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  us/channel  rotected  e controller power sup t channels: no isolation and analog output: tra s as 1 module  nent: 16 points for interest.	≤±0.4% ≤±0.4%		
Conversion speed Dutput shore Common solation me	Wave output mode It protection part ethod  umber of modules n occupied I/O points	Between I/O termina Between ex	15 V -1010 V 020 mA 420 mA  80 p P ils and programmable Between output ternal power supply a Counts 6 points (I/O assignm	≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  us/channel  rotected  e controller power sup t channels: no isolation and analog output: tra s as 1 module ment: 16 points for intel t terminal block	≤±0.4% ≤±0.4%		
Conversion speed Output shor Common Isolation me Maximum n specification Number of a External interest	Wave output mode tt protection part  ethod  umber of modules n occupied I/O points erface	Between I/O termina Between ex	15 V -1010 V 020 mA 420 mA  80 µ P  Ils and programmable Between output ternal power supply a  Counts 6 points (I/O assignn 18-point 24 V DO	≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  s/channel  rotected  e controller power sup t channels: no isolation and analog output: tra s as 1 module  ment: 16 points for intel t terminal block c (+ 20%/-15%)	≤±0.4% ≤±0.4%		
Common  Isolation me  Maximum no specification	Wave output mode tt protection part  ethod  umber of modules n occupied I/O points erface	Between I/O termina Between ex	15 V -1010 V 020 mA 420 mA  80 µ  Ils and programmable Between output ternal power supply a  Counts 6 points (I/O assignn 18-point 24 V DC Ripple, spike	≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  sychannel  rotected  e controller power sup t channels: no isolation and analog output: tra s as 1 module ment: 16 points for inte t terminal block C (+ 20%/-15%) e 500 mV _{P-P} or lower	≤±0.4% ≤±0.4%		
Conversion speed Output shor Common Isolation me Maximum n specification Number of a External interest.	Wave output mode tt protection part  ethod  umber of modules n occupied I/O points erface	Between I/O termina Between ex	15 V -1010 V 020 mA 420 mA  80 µ  Ils and programmable Between output ternal power supply a Counts 6 points (I/O assignm 18-point) 24 V DC Ripple, spike Inrush current: 3	≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  sychannel  rotected  e controller power sup t channels: no isolation and analog output: tra s as 1 module nent: 16 points for inte t terminal block (+ 20%/-15%) e 500 mV _{P-P} or lower .5 A, 1000 µs or short	≤±0.4% ≤±0.4%		
Conversion speed Dutput shore Common Solation me Maximum nuspecification vumber of cexternal interest control of the Control of Cont	Wave output mode tt protection part  ethod  umber of modules n occupied I/O points erface	Between I/O termina Between ex	15 V -1010 V 020 mA 420 mA  80 µ P  Ils and programmable Between output ternal power supply a Counts 6 points (I/O assignm 18-point) 24 V DC Ripple, spike Inrush current: 3 Current course	≤ ± 0.2%  ≤ ± 0.2%  ≤ ± 0.2%  sychannel  rotected  e controller power sup t channels: no isolation and analog output: tra s as 1 module ment: 16 points for inte t terminal block C (+ 20%/-15%) e 500 mV _{P-P} or lower	≤±0.4% ≤±0.4%		

^{*1:} Maximum resolution in the user range setting.
*2: Accuracy for the maximum value of the digital /analog output value. Except when influenced by noise.

^{*3:} A momentary current value which does not cause damage to internal resistors of the module, although the maximum continuous input current 24 mA.

#### **Temperature Control Modules**



Function	L60TCTT4	L60TCTT4BW	L60TCRT4	L60TCRT4BW
Function	Thermoco	ouple input	RTD	input
Standard control	•	•	•	•
Heating-cooling control	•	•	•	•
Self-tuning function	•	•	•	•
Peak current suppression function	•	•	•	•
Simultaneous temperature rise function	•	•	•	•
Selectable sampling cycle	•	•	•	•
Temperature input mode	•	•	•	•
Temperature control mode	•	•	•	•
Heater disconnection detection function	_	•	_	•

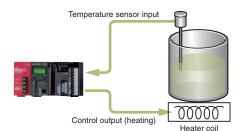
#### Highly stable temperature control

#### Standard control/heating and cooling control

Prevent overheating and overcooling in devices that require a high level of temperature stability, such as in an extrusion molding machine.

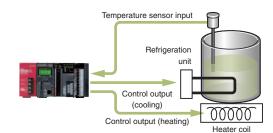
The following control methods can be selected according to the target device.

- Standard control (heating or cooling)
- Heating/cooling control (heating and cooling)
- Mix control (combination of standard control and heating-cooling control)
  - Example: Standard control (heating only)
    The temperature of the object is controlled by adjusting the heater output based on the PID calculations resulting from the temperature sensor input.



#### ■ Example: Heating-cooling control

(heating and cooling elements controlled simultaneously)
Heating is performed when the control object's temperature is lower than the target temperature, and cooling is performed when it is hotter or the humidity needs to be reduced.





#### Reduce running costs by taking advantage of the energy-saving effect

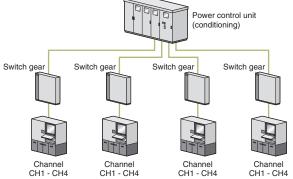
#### **Peak current control function**

The peak current control function reduces the peak current by automatically changing the upper-output limit value for each channel, while dividing the transistor output timing*1. The energy conserved by reducing the peak current, such as a reduction in system power capacity and reduction in contracted power, can help to reduce running costs.

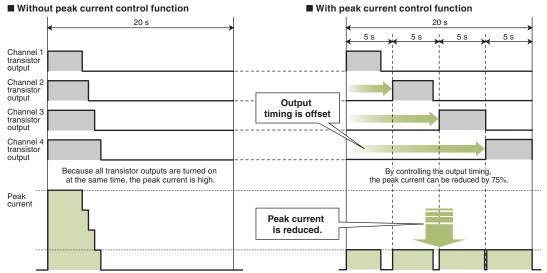
*1: The timing can be split between two to four outputs.

The maximum power supply capacity requirement is lowered.

We can save money on our electricity contract!



When two or more loads are being controlled, the peak current can be minimized by spreading the total load out over time.



It is possible to space the outputs out over a longer period of time.

#### **Ensures uniform temperature control**

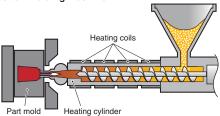
#### Simultaneous temperature rise function

Ensures uniform temperature control by synchronizing the temperature arrival times from multiple loops.

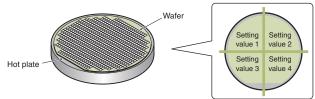
Perform a uniform temperature rise using two or more control loops without going over temperature or resulting in unexpected thermal expansion.

A "no idling" format increases energy efficiency and reduces running costs.

■ Example: Temperature control of injection molding machine

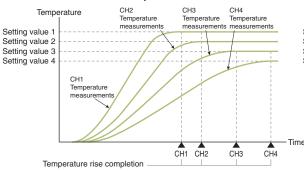


#### ■ Example: Wafer heating process for semiconductor manufacturing

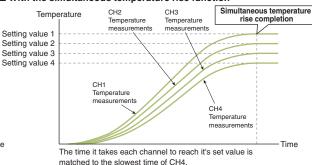


#### The running costs is reduced!

#### ■ Without the simultaneous temperature rise function



#### ■ With the simultaneous temperature rise function

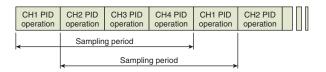


Using this function, it is possible to coordinate the control of two or more loops to reach their target values (SV) at the same time. Control the simultaneous rise in temperature of separate loops by setting a channel group (Max. 2 groups). This is an effective way to control applications where differing target temperature arrival times can result in undesirable temperature differentials.

#### Support a range of system requirements

#### Sampling cycle change function

Choose a sampling cycle of 250 ms/4 channels or 500 ms/4 channels.

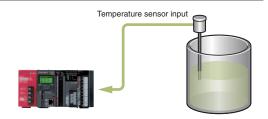


Sampling period: The time it takes to execute a PID operation for all channels (CHn) before beginning the PID operation of the present channel (CHn) again is called a sampling period.

#### Temperature input mode

This function allows the temperature control module to be used as a standard temperature input module.

Using the switch setting, it is possible to easily change the input mode.



MELSEG L series

#### ■ Specifications

		tem	L60TCTT4 L60TCTT4BW L60TCRT4 L60TCRT4BW						
Control outp			Transistor output						
Number of te	emperature input chann	els	4 channels						
Applicable to	emperature sensors	_	Thermocouple Resistive thermal device						
	Indication accuracy	Ambient temperature: 25 ± 5°C	Full scale × (± 0.3%)						
	indication accuracy	Ambient temperature: 055°C		Full scale	× (± 0.7%)				
	Cold junction temperature	Temperature process value (PV): -100°C or more	≤ ± .	1.0°C					
	compensation accuracy:	Temperature process value (PV): -150100°C	≤ ± 2	2.0°C	-	_			
	(ambient temperature: 055°C)	Temperature process value (PV): -200150°C	≤ ± 3	3.0°C					
Sampling cy	cle				channels channels				
Control outp	ut cycle			0.51	00.0 s				
Input impeda	ance			1 N	МΩ				
Input filter				0100 s (0: Ir	nput filter OFF)				
Sensor corre	ection value setting			-50.00	.50.00%				
Operation at	sensor input disconnec	etion		Upscale p	rocessing				
Temperature	control method			PID ON/OFF pulse of	r two-position control				
		PID constants setting		Can be set by	y auto tuning.				
DID .		Proportional band (P)	0.01000.0% (0: Two-position control)						
PID constan	ts range	Integral time (I)		03600 s (set 0 for P	control and PD control.)				
		Derivative time (D)		03600 s (set 0 for P	control and PI control.)				
Set value (S	V) setting range		Within the temperature range set in the thermocouple/platinum resistance thermometer to be used						
Dead band s	setting range		0.110.0%						
		Output signal	ON/OFF pulse						
		Rated load voltage	1030 V DC						
		Max. load current							
Transistor ou	utput	Max. inrush current	0.4 A 10 ms						
		Leakage current at OFF	≤ 0.1 mA						
		Max. voltage drop at ON							
		Response time	1.0 V DC (TYP) at 0.1 A 2.5 V DC (MAX) at 0.1 A  OFF→ON: ≤ 2 ms, ON→OFF: ≤ 2 ms						
Number of a	ccesses to non-volatile	memory	Max. 10 ¹² times						
Isolation me	thod		Between input ter	minal and programmable o	ontroller power supply: Tra s: Transformer isolation	ansformer isolation			
Heater disco		Current sensor	-	• CTL-12-S36-10 (0.0100.0 A)*2 • CTL-12-S56-10 (0.0100.0 A)*2 • CTL-6-P-H (0.0020.00 A)*2	-	• CTL-12-S36-10 (0.0100.0 A)*2 • CTL-12-S56-10 (0.0100.0 A)*2 • CTL-6-P-H (0.0020.00 A)*2			
		Input accuracy	1	Full scale × (± 1.0%)		Full scale × (± 1.0%)			
		Number of alert delay		3255		3255			
Maximum nu	umber of modules speci	fication	Counts as 1 module	Counts as 2 modules	Counts as 1 module	Counts as 2 modules			
	ccupied I/O points				ent: Intelligent 16 points)				
External inte			18-point terminal block	18-point terminal block × 2	18-point terminal block	18-point terminal block × 2			
	nal current consumption	1	0.30 A	0.33 A	0.31 A	0.35 A			
Weight	the second of the second	owing method (only when it is not affe	0.18 kg	0.33 kg	0.18 kg	0.33 kg			

^{*1:} Calculate the accuracy in the following method (only when it is not affected by noise).

 $\label{eq:accuracy} \mbox{Accuracy} \ (\mbox{`C}) = \mbox{full scale} \times \mbox{indication accuracy} + \mbox{cold junction temperature compensation accuracy}$ 

Ex.) Accuracy at the input range of 38 (-200.0 to 400.0 °C), the operating ambient temperature of 35 °C, and the temperature process value (PV) of 300 °C (Full scale) × (indication accuracy) + cold junction temperature compensation accuracy

= (400.0°C - (-200.0°C)) × (±0.007) + (±1.0°C)

 $= \pm 5.2$ °C

#### ■ Control mode

Control mode	Contents	Number of controllable loops
Standard control	Standard control Performs the standard control of four channels.	
Heating-cooling control (normal mode)	Performs the heating-cooling control. CH3 and CH4 cannot be used.	Heating-cooling control 2 loops
Heating-cooling control (expanded mode)	Performs the heating-cooling control. The number of loops is expanded using an output module and others in the system.	Heating-cooling control 4 loops
Mix control (normal mode)	Performs the standard control and the heating-cooling control. CH2 cannot be used.	Standard control 2 loops Heating-cooling control 1 loop
Mix control (expanded mode)	Performs the standard control and the heating-cooling control. The number of loops is expanded using an output module and others in the system.	Standard control 2 loops Heating-cooling control 2 loops

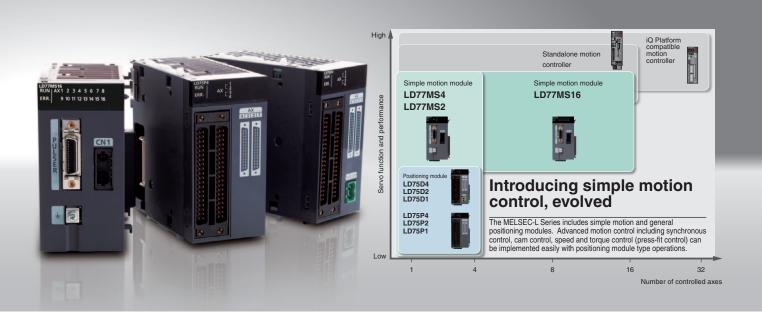
Control for each channel is as follows.

Channel	Standard control	Heating-co	oling control	Mix control		
Charmer	Standard Control	Normal mode	Expanded mode	Normal mode	Expanded mode	
CH1	Standard control	Heating-cooling control	Heating-cooling control	Heating-cooling control	Heating-cooling control	
CH2	Standard control	Heating-cooling control	Heating-cooling control	—*3	Heating-cooling control*4	
CH3	Standard control	*3	Heating-cooling control*4	Standard control	Standard control	
CH4	Standard control	*3	Heating-cooling control*4	Standard control	Standard control	

^{*3:} Only temperature measurement using a temperature input terminal can be performed.

^{*2:} U.R.D.Co., LTD. For more information, visit http://www.u-rd.com

^{*4:} Heating-cooling control is performed using an output module in the system.



#### **Simple Motion Modules**



*SSCNET(Servo System Controller NETwork)

Function		LD77MS2	LD77MS4	LD77MS16	
Positioning control to	function	•	•	•	
Speed/torque contr	ol function	•	•	•	
Linear interpolation		2 axes	2/3/4 axes	2/3/4 axes	
Circular interpolatio	n	2 axes	2 axes	2 axes	
0	External encoder	•	•	•	
Synchronous control function	Cam	•	•	•	
CONTROL IUNCTION	Phase compensation	•	•	•	
Manual pulse gener	rator operation function	•	•	•	
OPR control function	n	•	•	•	

#### Positioning Modules



Function	LD75P1	LD75P2	LD75P4	LD75D1	LD75D2	LD75D4		
Fullction	Open collector output				Differential output			
Positioning control function	•	•	•	•	•	•		
Speed control function	•	•	•	•	•	•		
Linear interpolation	_	2 axes	2/3/4 axes	_	2 axes	2/3/4 axes		
Circular interpolation	_	2 axes	2 axes	_	2 axes	2 axes		
OPR control function	•	•	•	•	•	•		

MELSEG L series

#### Countless applications are possible

LD77MS□

A variety of control types including positioning control, speed control, torque control, cam control and synchronous control can be implemented easily with simple parameter settings and a sequence program.

#### **Positioning control**

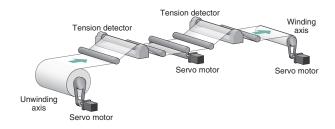
- Support for a multitude of applications thanks to a wide variety of control formats including linear interpolation control (up to 4 axes), 2-axis circular interpolation control, fixed feed control and continuous orbit control.
- Use a sequence program to set the positioning address, speed, etc. for easy automatic operation.
- Quickly implement powerful auxiliary functions such as step operation, target position change, M codes, and the skip function.

#### Speed control and torque control

- Tension control applications such as winding and rewinding are supported.
- Switch from positioning control, to speed and torque control, and back to positioning control.
   Because the present location is tracked even in speed and

Because the present location is tracked even in speed and torque control mode, it is possible to maintain the current absolute position when returning to positioning control.

# XY table 2-axis linear interpolation 2-axis circular interpolation 3-axis linear interpolation Continuous orbit control Continuous orbit control Continuous orbit control Continuous orbit control Linear/circular interpolation

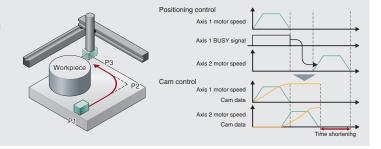


#### Synchronous control and cam control

• Cam control may be used alone or combined with synchronous control.

#### Example application for cam control:

To create a movement path around a workpiece using positioning control, axis 2 waits for axis 1 to complete the move from P1 to P2 before it begins moving from P2 to P3. By using cam control, axis 2 does not need to wait for axis 1 to complete its movement and the in position time can be shortened.



#### Many functions in a compact design

## LD77MS□

#### Use a synchronous encoder with synchronous control

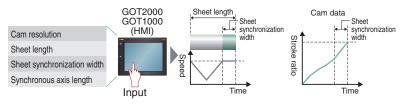
- Input pulses from a synchronous encoder can be used to perform synchronous control and cam control.
- The incremental synchronous encoder can be used by using the LD77MS built-in interface. An option unit is not required.
- To further improve the synchronization accuracy, the phase compensation function, designed to compensate for synchronous encoder delays, can be used.

#### Standard mark detection function

 The built-in mark detection signal interface allows these units to be used in packaging systems for example, without additional option modules.

#### Automatic cam data generation for rotary cutter

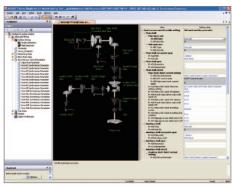
 Complicated cam data for rotary cutters can be automatically generated just by specifying a few parameters like the sheet length and synchronization width.



#### Perfect synchronous control is easy to achieve

Replace mechanical gears, shafts, speed change gears, cams, etc. and generate synchronous control operations using software.

- Complicated programs are unnecessary for synchronous control because it can be implemented easily using parameter settings.
- Start and stop synchronous control for each axis.
   Use the synchronous control axis and positioning control axis together.
- Convey the travel value of main shaft to the output axis via the clutch.



Synchronous Control Parameter Settings

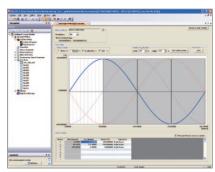
#### Cam control made simple

LD77MS□

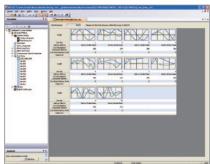
LD77MS□

Create cam data patterns easily.

- Create cam profiles unrestricted by existing concepts of electronic cam control.
- Change the acceleration, speed, stroke, and jerk while simultaneously seeing how it effects the profile.
- Easily check created cam data by viewing them as thumbnails.
- Import and export cam data in CSV format.



Cam Data



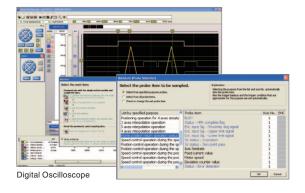
Cam Data List

#### Simplified debugging and commissioning

#### LD77MS□

#### Digital oscilloscope function

- Collection of data from the simple motion module is synchronized with the operation cycle and waveform displays to facilitate an efficient start up.
- The assistant function explains each step.
- Use the purpose-based probe setting to easily set frequentlyviewed data.
- Sample 16CH word and 16CH bit data and display 8CH words and 8CH bits in real time.



#### Monitor and test functions

- Complete the system installation and perform operational checks easily using powerful monitor and test functions.
- Select items to be displayed on the monitor using a wealth of information monitoring options.
- The test function can be used to check basic operations without a sequence program.



Monitor Positioning Test



	Ite	m	LD77MS2*1	LD77MS4	LD77MS1	6		
Number of control a	axes		2 axes	4 axes	16 axes	40		
Operation cycle			0.88	3 ms	0.88 ms/1.77	ms*2		
nterpolation function	on		Linear interpolation (2 axes), Circular interpolation (2 axes)	2-axis/3-axis/4-axis linear interpo		. ,		
Control system			torque control, speed	trol, path control (both linear and arc of- d-position switching control, position-sp	peed switching control	,		
acceleration/decele		SS	· · · · · · · · · · · · · · · · · · ·	eleration/deceleration, S-curve acceler				
Compensation func				compensation, Electronic gear, Near pa				
Synchronous contro	DI		External encoder, t	Cam, Phase Compensation, Cam gene	erated automatically			
Control unit Positioning data			600 data (positioning data No. 1 60	mm, inch, degree, pulse 00) / axis (Can be set with GX Works2	or programmable controll	ler program		
ackup				and block start data can be saved on f				
аскир	Machine O	PR control		d 1), Count method 2), Data set method				
PR control	Fast OPR		Troat point dog mounda, count mound	•	a, coale origin orginal deta	00001111100		
	Sub functio			OPR retry, OP shift				
		Linear control		xis linear interpolation control, 3-axis li plation control*3 (Composite speed, Re		,		
	Position	Fixed-feed control	·	s fixed-feed control, 3-axis fixed-feed o	· · · · · · · · · · · · · · · · · · ·	control		
	control	2-axis circular interpolation				COTILIOI		
		control	Sub	point designation, center point design	ation			
	Speed cont		1-axis speed control, 2	-axis speed control, 3-axis speed cont	rol. 4-axis speed control			
osition control	<u> </u>	tion switching control		INC mode, ABS mode	, эргээг эг			
		eed switching control		INC mode				
	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	Current value changing	Changing to a new current value using	ng the positioning data, Changing to a	new current value using	the start N		
	Other	NOP instruction	3 3 3 1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	•				
	control	JUMP instruction		Unconditional JUMP, Conditional JUM	P			
		LOOP, LEND		•				
ligh-level positionii	ng control		Block start, Cond	lition start, Wait start, Simultaneous sta	art, Repeated start			
	JOG opera	tion		•				
Manual control	Inching ope	ration		•				
	Manual pul	se generator operation	Possible to connect 1	I module (Incremental) Unit magnifica	tion (110000 times)			
xpansion control	Speed-torq	ue control	Speed control withou	ut positioning loops, Torque control with	nout positioning loops			
bsolute position sy	ystem		Connect a b	pattery to the servo amplifier to ensure	compatibility			
synchronous encod	der interface		Up to 4 channels (Total of the internal interface, interface via servo amplifier, and interface via the PLC CPU)					
	Internal interface		1 channel (Incremental)					
	Speed limit function		Speed limit value, JOG speed limit value					
unctions that limit	Torque limit function		Torque limit va	lue_same setting, torque limit value_ir	ndividual setting			
ontrol	Forced stop function			Valid/invalid setting				
	_	roke limit function	Movable range check with	current feed value, movable range che	eck with machine feed val	lue		
	Hardware stroke limit function		•					
	Speed change function		•					
unctions that	Override fu		•					
change control		n/deceleration time change	•					
letails	function	and franction	•					
	Torque change function		•					
	Target position change function  M code output function		Target position address and target position speed are changeable					
	Step function		Deceleration unit step, Data No. unit step					
Other functions	Skip function		Via sequence CPU, Via external command signal					
	Teaching fu		Vid Si	equence CFO, via external command				
	Todorning It	HOUGH	Mark detection mode (Continuous I	Detection mode, Specified Number of	Detections mode Ring Ri	uffer mode		
Mark detection	Mark detec	tion signal	actorion mode (continuous t	4 points		o. mode		
unction	Mark detec		4	1	16			
Optional data monit		<u> </u>		4 points/axis	1			
Master-slave opera				•				
mplifier-less opera				•				
Digital oscilloscope			Bit data: 8 channels, V	Vord data: 4 channels	Bit data: 16 chann Word data: 16 cha			
			1-axis linear control					
			1-axis speed control					
				ation control (Composite speed)	]			
				(Reference axis speed)	]			
			2-axis circular interpo	olation control	ļ l			
starting time*5			2-axis speed control		0.88 ms			
				ation control (Composite speed)	-			
				ation control (Reference axis speed)				
			3-axis speed control	ation control				
			4-axis linear interpola	alion control				
			4-axis speed control					
				100 m				
faximum distance	between sta	tions [m (ft.)]						
		- ' ',-		Counts as 2 modules				
/laximum number o	of modules s	- ' ',-	32 p		pints)			
Maximum number of occupied Servo amplifier con	of modules s d I/O points nection syste	pecification		Counts as 2 modules points (I/O assignment: Intelligent 32 possible SSCNET III/H-compatible (1 system)				
Maximum distance Maximum number of Number of occupier Servo amplifier con S V DC internal curi	of modules s d I/O points nection syste	pecification	32 p	Counts as 2 modules points (I/O assignment: Intelligent 32 possible SSCNET III/H-compatible (1 system)				

^{*1:} The maximum number of control axes for LD77MS2 is two axes. Use LD77MS4 or LD77MS16 to control three or more axes.

^{*2:} Default value is 1.77 ms. If necessary, check the operation time and change to 0.88 ms. *3: 4-axis linear interpolation control is enabled only at the reference axis speed.

^{*4: 8}CH word data and 8CH bit data can be displayed in real time.

 $[\]ensuremath{^\star} 5$  . The starting time varies with conditions. For details, refer to the manual.

	incations	Item	LD75P1/LD75D1 ⁻¹	LD75P2/LD75D2*1	LD75P4/LD75D4 ⁻¹			
Number of control axes		5	1 axis	2 axes	4 axes			
Interpolation function			_	2-axis linear interpolation 2-axis circular interpolation	2-axis/3-axis/4-axis linear interpolation 2-axis circular interpolation			
			PTP (Point To I	Point) control, path control (both linear and				
Control sy	/stem			ed-position switching control, position-spec				
Control ur	nit			mm, inch, degree, pulse	3			
Docitionin	a data			600 data (positioning data No.1600) /axi	is			
Positionin	ig data		· · · · · · · · · · · · · · · · · · ·	e set with peripheral device or sequence p				
Backup			Parameters, positioning data	a, and block start data can be saved on flas	sh ROM (battery-less backup)			
	Positioning	PTP*2 control	Increment system, absolute system					
	control	Speed-position switching control		Increment system, absolute system*3				
	system	Position-speed switching control	Increment system					
		Path control		Increment system, absolute system				
				-214748364.8214748364.7 (μm) -21474.8364821474.83647 (inch)				
		In absolute system		0359.99999 (degree)				
				-21474836482147483647 (pulse)				
				-214748364.8214748364.7 (µm)				
		I		-21474.8364821474.83647 (inch)				
	Positioning	In increment system		-21474.8364821474.83647 (degree)				
	range			-21474836482147483647 (pulse)				
Positioning	Tarigo	In speed-position switching		0214748364.7 (µm)				
control		control (INC mode)/		021474.83647 (inch)				
		position-speed switching control		021474.83647 (degree)				
			02147483647 (pulse)					
		In speed-position switching control (ABS mode)*3		0359.99999 (degree)				
		,	0.0120000000.00 (mm/min)					
	Speed command		0.0012000000.000 (inch/min)					
			0.0012000000.000 (degree/min)					
				14000000 (pulse/s)				
	Acceleration/deceleration system selection		Trapezoidal acceleration/deceleration, S-curve acceleration/deceleration					
	Acceleration/deceleration time		18388608 ms  Four patterns can be set for each of acceleration time and deceleration time					
	Sudden stor	deceleration time	18388608 ms					
OPR meth			6 types					
			1-axis linear contro		1.5 ms			
			1-axis speed contr		1.5 ms			
			•	olation control (Composite speed)	1.5 ms			
				ol (Reference axis speed)	1.5 ms			
			2-axis circular inte	` ' '	2.0 ms			
Starting ti	me*4		2-axis speed contr	ol	1.5 ms			
			3-axis linear interp	olation control (Composite speed)	1.7 ms			
			3-axis linear interp	olation control (Reference axis speed)	1.7 ms			
			3-axis speed contr	ol	1.7 ms			
			4-axis linear interp	olation control	1.8 ms			
			4-axis speed contr	rol	1.8 ms			
Aovies	output mul-	LD75P□		200 kpulse/s				
viaximum	output pulse	LD75D□		4 Mpulse/s				
Maximum c	connection	LD75P□		2 m				
	etween drive uni			10 m				
/laximum	number of m	nodules specification		Counts as 2 modules				
	of occupied I/0	· · · · · · · · · · · · · · · · · · ·	32	2 points (I/O assignment: Intelligent 32 poir	nts)			
External i	<u> </u>			onnector	40-pin connector ×2			
		t LD75P□	0.44 A	0.48 A	0.55 A			
_		LD75D□	0.51 A	0.62 A	0.76 A			
consumpt	Weight		0.51 A 0.62 A 0.76 A 0.78 kg					

weight

*1: LD75P□ refers to the open collector output type, and LD75D□ refers to the differential driver output type.

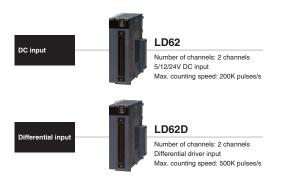
*2: The abbreviation for Point To Point, referring to position control.

*3: In speed-position switching control (ABS mode), "degree" is the only control unit available.

*4: Starting times may vary depending on conditions. For details, refer to the manual.

# MELSEG L series

#### **High-Speed Counter Modules**



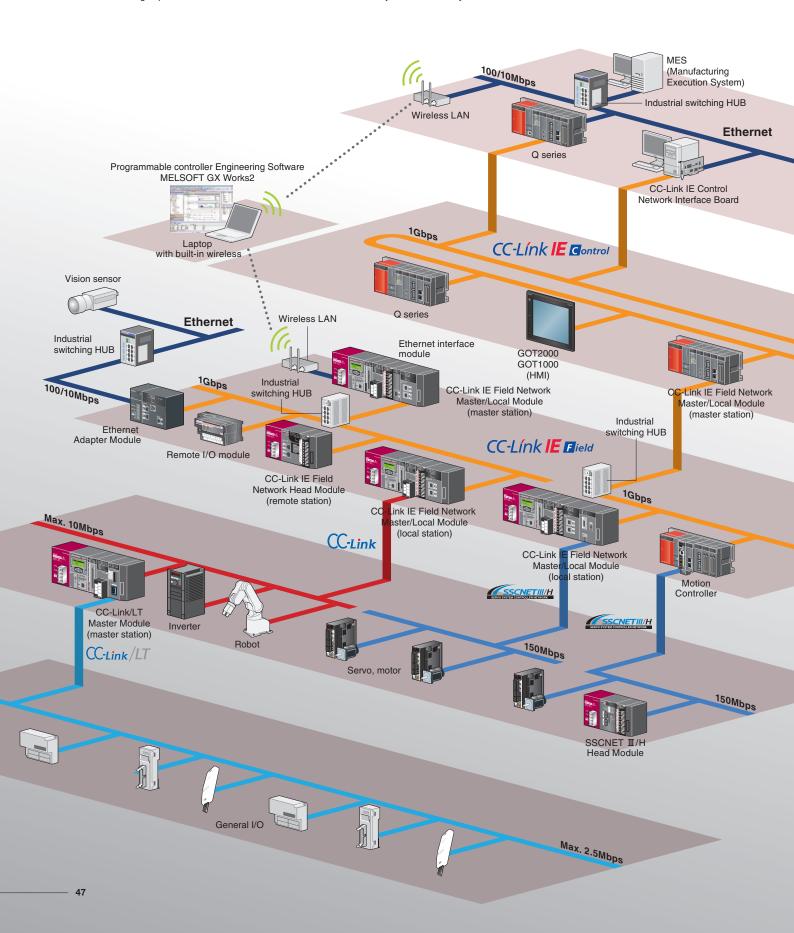
Function	LD62	LD62D
Fullction	DC input	Differential input
Linear counter function	•	•
Ring counter function	•	•
Coincidence output function	•	•
Preset function	•	•
Disable count function	•	•
Latch counter function	•	•
Sampling counter function	•	•
Periodic pulse counter function	•	•

	Item		LD62 [DC input]	LD62D [Differential input]				
Number of c	hannels		2 channels					
Counting sp	eed switch setting		10K pulses/s, 100K pulses/s, 200K pulses/s 10K pulses/s, 100K pulses/s, 200K pulses/s, 500K pulses/s					
Count input	Phase		1-phase input (multiple of 1/2), CW/C	CCW, 2-phase input (multiple of 1/2/4)				
signal	Signal level (A, B)		5/12/24 V DC 25 mA	EIA Standard RS-422-A differential type line driver level (Equivalent with AM26LS31 (manufactured by Texas Instruments Japan Limited))				
	Maximum counting speed	*1	200K pulses/s	500K pulses/s				
	Counting range		-2147483648.	2147483647				
	Туре		UP/DOWN preset counter	and ring counter functions				
			10K pulses/s 50 μs	10K pulses/s 50 μs				
	Minimum count pulse wide	th	100K pulses/s 5 μs	100K pulses/s 5 µs				
Counter	(Duty ratio 50%)		200K pulses/s 2.5 μs	200K pulses/s 2.5 µs				
				500K pulses/s 1 μs				
			10K pulses/s 25 μs	10K pulses/s 25 μs				
	Minimum phase differentia	al for	100K pulses/s 2.5 μs	100K pulses/s 2.5 μs				
	2-phase input		200K pulses/s 1.25 μs	200K pulses/s 1.25 μs				
				500K pulses/s 0.5 μs				
Coincidence	Comparison range		Binary with 32-bit code (-21474836482147483647)					
output	Comparison result		Set value < Count value Set value = Count value Set value > Count value					
	Preset			5/12/24 V DC 25 mA (Differential type line drivers				
External	Function start		5/12/24 V DC 25 mA conforming to EIA standard RS-422-A are also applicable					
input	Minimum input	OFF to ON	Function s	tart: 0.5 ms				
	response time	ON to OFF	Function	start: 1 ms				
	Coincidence output		2 points	s/channel				
External	Output voltage/current		1224 V DC 0.5 A					
output	Output response time	OFF to ON	< 0.1 ms (rated to	and resistive lead				
	Output response time	ON to OFF	≤ 0.1 ms (rated load, resistive load)					
Maximum nu	umber of modules specifica	ition	Counts as 1 module					
	ccupied I/O points			ent: Intelligent 16 points)				
External inte				connector				
	nal current consumption		0.31 A	0.36 A				
Weight			0.1	3 kg				

^{*1:} The counting speed is affected by the rising/falling pulse speed. For details, refer to the corresponding manual.

#### Seamless integration of multiple networks

The MELSEC L Series is part of a family of products all interconnected across various levels of automation. Based on the seamless message protocol (SLMP*1), data flows transparently between the sensor level and the management level across multiple industry-standard automation networks. CC-Link IE, Asia's No. 1 industrial network, realizes fast gigabit data transmission speeds, further optimizing the manufacturing cycle. In addition, the SSCNET 3/H high-speed motion control network further enhance the factory-wide connectivity solution.



0

# MELSEG L series

#### **Seamless communication**

Seamless data communication through Ethernet, CC-Link IE Control, CC-Link IE Field, and CC-Link networks allow easy access to information, no matter where it resides on the network. Through this technology, it is possible to "drill down" from the Enterprise or IT layer through multiple networks accessing programming controllers using GX Works2 programming or other related software.

In addition, many devices supporting SLMP*1 such as vision sensors and RFID controllers may be connected to the CC-Link IE Field Network.

*1: SLMP (SeamLess Message Protocol) is a protocol advocated by the CC-Link Partner Association.



## CC-Línk IE Gontrol

CC-Link IE Control is a high-reliability distributed control network designed to handle very large data communications (128K word) over a high-speed (1 Gbps) dual-loop optical cable topology.

*: L Series does not support the CC-Link IE Control Network.

## CC-Línk IE Flield

CC-Link IE Field is a versatile gigabit Ethernet-based network integrating controller, I/O control, safety control, and motion control in a flexible wiring topology supporting star, ring, and line configurations.

*: Compatible modules: LJ71GF11-T2, LJ72GF15-T2

## CC-Link

CC-Link is a high-speed and high-reliable deterministic I/O control network which realizes reduced wiring whilst offering multi-vendor compatible products. This open field network is a global standard originating from Japan and Asia.

*: Compatible modules: L26CPU-BT, L26CPU-PBT, LJ61BT11



SSCNETIII/H is a dedicated high-speed, high-performance, and highly reliable servo system control network that offers flexible long distance wiring capabilities based on optical fiber cable topology.

*: Compatible modules: LD77MS2, LD77MS4, LD77MS16, LJ72MS15

## CC-Link/LT

CC-Link/LT is a wire-saving sensor level network which is designed for use in panels between simple discrete devices. Its wiring system is based on reducing incorrect wiring and is based on CC-Link realizing high-speed and robust noise resistance features.

*: Compatible module: LJ61CL12

#### **MODBUS®**

L-Series is now supporting the MODBUS® protocol network, realizing easy communication, with various MODBUS® slave devices compatible with Ethernet MODBUS®/TCP or RS-232/422/485 serial communication.

- *: Module supporting MODBUS®/TCP: L02CPU(-P), L06CPU(-P), L26CPU(-P),
- L26CPU-(P)BT, LJ71E71-100 (master only)
  *: Modules supporting MODBUS®: L6ADP(-R2/R4), LJ71C24(-R2) (master only)

#### BACnet™

This network supports the communication protocol standard BACnet[™] client function. This network is mainly used to monitor and control airconditioning, lighting and fire detection, etc. in building automation system applications.

*: Compatible modules: L02CPU(-P), L06CPU(-P), L26CPU(-P), L26CPU-(P)BT, LJ71E71-100 (client only)

	Application	Enterprise level network	Control level network		Device level network		Sensor level network
Network		Information communication	Controller distributed control	I/O control	Safety control	Motion control	Control
Ethernet		•					
CC-Link IE Control			•				
CC-Link IE Field			•	•	•	•	
CC-Link				•			
CC-Link/LT							•
SSCNETII/H						•	
BACnet™		•					
MODBUS®/TCP			•				
MODBUS®				•			

#### **CC-Link IE Field Network Master/Local Module**





#### Easy to configure settings

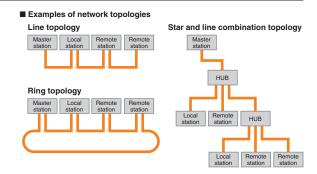
Network parameters are configured using the engineering tool, GX Works2. Only the master station needs to be configured, thereby greatly simplifying the network setup. Updating the system configuration is a breeze.



#### Flexible network topology

Various network topologies are supported including star, line, star and line combination, and ring. When hubs*1 are used, new equipment can be added and machine layouts can be changed easily.

*1: Hubs cannot be used in a ring configuration.



Item			LJ71GF11-T2
Transmission speed			1 Gbps
Maximum overall cable distance (Maximum transmission distance)		Line topology	12000 m (when cables are connected to 1 master station and 120 slave stations)
		Star topology	Depends on the system configuration
		Ring topology	12100 m (when cables are connected to 1 master station and 120 slave stations)
Maximum number of o	Maximum number of connected		1 station (Up to 120 slave stations can be connected to the master station)
stations		Local station	120 stations
		Remote register (RWw)	8192 points, 16 KB
Maximum link points	nor etation	Remote register (RWr)	8192 points, 16 KB
Maximum illik politis	per station	Remote input (RX)	16384 points, 2 KB
		Remote output (RY)	16384 points, 2 KB
		Remote register (RWw)	8192 points, 16 KB
	Master station	Remote register (RWr)	8192 points, 16 KB
		Remote input (RX)	16384 points, 2 KB
Maximum link		Remote output (RY)	16384 points, 2 KB
points per station	Local	Remote register (RWw)	8192 points, 16 KB (also including the send range of own station)
		Remote register (RWr)	8192 points, 16 KB
	station	Remote input (RX)	16384 points, 2 KB
		Remote output (RY)	16384 points, 2 KB (also including the send range of own station)
Network topology			Line topology, star topology (Coexistence of line topology and star topology is possible.),
Network topology			and ring topology
Communication met	hod		Token passing method
Communication por	<u> </u>		CC-Link IE Field Network port x 2
RAS function			Automatic return, Slave station disconnection, Loopback function
Connection cable*2			Ethernet cable of category 5e or higher (Double shielded cable) which satisfies 1000BASE-T standard
Maximum number of modules specification			Counts as 2 modules
Number of occupied			32 points (I/O assignment: Intelligent 32 points)
5 V DC internal current consumption			0.89 A
Weight			0.27 kg

^{*2:} Standard (straight type) cable

# MELSEG L series

#### **CC-Link IE Field Network Head Module**



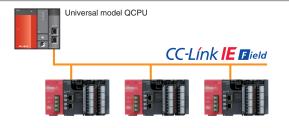
#### LJ72GF15-T2

CC-Link IE Field Intelligent device station Communication speed: 1 Gbps Remote I/O: 2048 points Remote register: 1024 words RAS function *: END cover is included.



#### CC-Link IE Field Network remote I/O station

L Series I/O and intelligent function modules can be connected to the remote I/O head module without a dedicated CPU. There are many benefits to using intelligent device stations including reduced CPU and wiring costs, great flexibility in selecting I/O and intelligent function modules, and compact unit size.

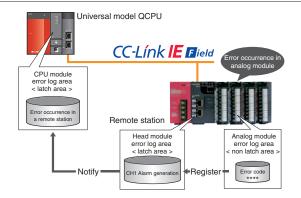


Modules compatible with the CC-Link IE Field Network head module

Item			
I/O module	Input, output, I/O combined		
Analog module	Analog input, analog output, analog input/output		
Temperature control module			
Simple motion module			
Positioning module			
High-speed counter module			
Network module	CC-Link, CC-Link/LT, serial communication		
AnyWireASLINK master module			

#### RAS (Reliability, Availability, Serviceability) functions

One feature of RAS is to store all remote station error histories in the master station's latched memory. This preserves the error information in one place in the event of power loss and allows for easy troubleshooting. Other RAS features include network event logging, unit error logging, and testing and monitoring capabilities.



Item		LJ72GF15-T2		
Transmission speed		1 Gbps		
Maximum overall cable	Line network topology	12000 m (with 1 master and 120 slaves connected)		
distance (Maximum transmission distance)	Star network topology	Depends on the system configuration		
uistarice)	Ring network topology	12100 m (with 1 master and 120 slaves connected)		
Transmission path		Line, star, line and star mixed, or ring topology		
Communication method		Deterministic (token passing)		
Maximum number of modu	les specification*1	10		
Communication port		CC-Link IE Field Network port x 2		
RAS function		Network event logging, unit error logging, testing, monitoring, and error history preservation function		
Connection cable*2		Ethernet cable of category 5e or higher (Double shielded cable) which satisfies 1000 BASE-T standard		
5 V DC internal current consumption		1.00 A		
Weight		0.23 kg		

^{*1:} The total number of modules that can be mounted to a CC-Link IE Field Network head module. (END cover and power supply module are not included.)

^{*2:} Standard (straight type) cable.

#### **CC-Link Master/Local Module**

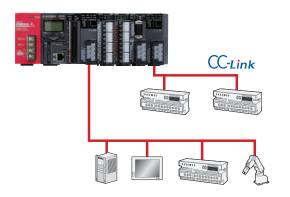




# Connect with a huge selection of device types using CC-Link

With such a large selection of CC-Link open network compatible devices, constructing a control system is easy.

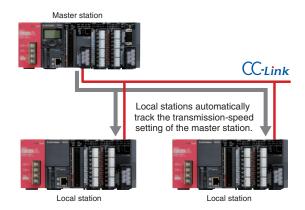
Even applications requiring vast amounts of data transmissions can be satisfied because CC-Link Ver.2.0 is supported.



# Local stations do not require transmission speed settings

#### Transmission speed auto-tracking function

When used as a local station, no transmission speed setting is required; the setting is made through automatic detection of the master station setting. The current transmission speed is indicated by an LED on the front surface of the module.



<ul><li>Specifications</li></ul>				
Item		LJ61BT11		
Transmission speed		156 kbps/625 kbps/2.5 Mbps/5 Mbps/10 Mbps		
Maximum overall cable distance (Maximum transmission distance)		1200 m (without repeater, varies according to the transmission speed)		
Maximum number of connec	ted stations (master station)	64		
Number of occupied station	ns (local station)	14 stations (The number of stations can be switched using the GX Works2 parameter setting)		
	Remote I/O (RX, RY)	2048 points		
Maximum number of link points per system*2	Remote register (RWw)	256 points (master station → remote device station/local station/intelligent device station/standby master station)		
ilik politis per system	Remote register (RWr)	256 points (remote device station/local station/intelligent device station/standby master station → master station)		
	Remote I/O (RX, RY)	32 points (local station is 30 points)		
Number of link points per station*2	Remote register (RWw)	4 points (master station → remote device station/local station/intelligent device station/standby master station)		
station	Remote register (RWr)	4 points (remote device station/local station/intelligent device station/standby master station → master stati		
Communication method		Broadcast polling method		
Synchronous method		Frame synchronization method		
Encoding method		NRZI method		
Transmission path		Bus (RS-485)		
Transmission format		Conforms to HDLC		
Error control system		CRC (X16+X12+X5+1)		
		Automatic return function		
RAS function		Slave station cut-off function		
		Error detection via link special relay/register		
Connection cable		CC-Link dedicated cables compatible with Ver.1.10		
Maximum number of modules specification		Counts as 1 module		
Number of occupied I/O pe	oints	32 points (I/O assignment: Intelligent 32 points)		
5 V DC internal current consumption		0.46 A		
Weight		0.15 kg		

^{*2:} Indicates the number of link points for Remote net Ver.1 mode.

# MELSEG L series

#### **CC-Link/LT Master Module**

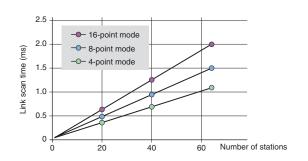




#### High speed equipment response

CC-Link/LT has an excellent response time. With 64 stations and a transmission speed of 2.5 Mbps, the maximum link scan time is just 1.2 ms. According to the transmission distance required, it is possible to select speeds of 2.5 Mbps, 625 kbps, or 156 kbps.

#### ■ CC-Link/LT link scan time (using a transmission speed of 2.5 Mbps)



#### Simple networking that 'just works'

There are no confusing parameters settings to make, and with remote I/O, only the master station needs to set the transmission speed.

Specifications Item				LJ61CL12			
Point mode				4-point mode	8-point mode	16-point mode	
	Maximum link points			256 points	512 points	1024 points	
	(the same I/O address used)			(512 points)	(1024 points)	(2048 points)	
	Link points per station			4 points	8 points	16 points	
	(the same I/O address used)			(8 points)	(16 points)	(32 points)	
			Points	128 points	256 points	512 points	
Control		32 stations	2.5 Mbps	0.7 ms	0.8 ms	1.0 ms	
specifications		connected	625 kbps	2.2 ms	2.7 ms	3.8 ms	
	Link scan		156 kbps	8.0 ms	10.0 ms	14.1 ms	
	time		Points	256 points	512 points	1024 points	
		64 stations	2.5 Mbps	1.2 ms	1.5 ms	2.0 ms	
		connected	625 kbps	4.3 ms	5.4 ms	7.4 ms	
			156 kbps	15.6 ms	20.0 ms	27.8 ms	
	Transmission speed			2.5 Mbps/625 kbps/156 kbps			
	Communication method			BITR method (Broadcast polling + Interval Timed Response)			
	Network topology				T-branch type		
0	Error control system				CRC		
Communication specifications	Number of connectable modules				64		
specifications	Remote station number				164		
	Installation position of master station			End of a trunk line			
	RAS function	n		Network diagnostics, internal loopback diagnostics, slave station cutoff function, automatic return function			
	Connection	cable*2		Dedicated flat cable (0.75 mm ² × 4)* ³ , VCTF cable* ⁴ , flexible cable* ³			
Maximum nu	mber of mod	ules specifica	ition	Counts as 1 module			
Number of o	ccupied I/O p	oints*5		16, 32, 48, 64, 128, 256, 512, or 1024 points (I/O assignment: Intelli.)			
5 V DC internal current consumption				0.16 A			
		Voltage			20.428.8 V DC		
24 V DC pow	ver supply*6	Current cons	sumption	0.03 A			
		Current on s	startup		0.07 A		
Weight					0.12 kg		

^{*2:} When the cables other than dedicated flat cables, VCTF cables, and flexible cables are used, performance of CCLink/LT is not guaranteed.

^{*3:} Use the dedicated flat cables and flexible cables accredited by CC-Link Partner Association. CC-Link Partner Association website: http://www.cc-link.org

 $^{^{\}star}4:$  Refer to the manual for details regarding VCTF cable specifications.

^{*5:} Set the number of occupied I/O points using the operation setting switch. Refer to the manual for details.

 $^{^{\}star}$ 6: 24 V DC power supply is supplied through the dedicated power supply or power supply adapter.

#### SSCNET II/H Head Module



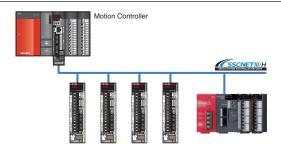


#### SSCNET **II**/H remote station

The SSCNET  $\mathbb{I}/H$  head module is used to connect the MELSEC-L Series I/O and intelligent function modules to the SSCNET  $\mathbb{I}/H$  network.

Functioning as the motion controller's remote station, flexible system configuration can be achieved while realizing reduced system wiring and a smaller footprint.

In addition, modules installed on the SSCNET  $\rm I\!I/H$  head module can be used as a motion controller input/output using cyclic transmission.



#### ■ SSCNET II/H Head Module compatible modules

Product					
I/O module Input, Output, I/O Combined					
i/O module	Analog input, analog output,				
Analog module	analog I/O combined				
High-speed counter modules					

#### ■ Compatible motion controller

Category	Model
Motion CPU	Q172DSCPU
Motion CPU	Q173DSCPU
Standalone motion controller	Q170MSCPU

Specifications					
Item		LJ72MS15			
Maximum link points per RWr, RX		256 bytes			
network	RWw, RY	256 bytes			
Maximum link points per	RWr, RX	64 bytes			
station	RWw, RY	64 bytes			
Communication speed		150 Mbps			
	Communication cycle: 888 µs	4			
Maximum connectable stations per network*1	Communication cycle: 444 µs	2			
	Communication cycle: 222 µs	1			
Maximum station-to-station of	listance	POF type: 20 m, H-PCF type: 50 m			
Connection method		Daisy chain connection (Regenerative relay system with a servo amplifier)			
Synchronous method		Synchronization of the control cycle and communication cycle that synchronize with the data transmission of the motion controller			
Communication cycle		222 µs/444 µs/888 µs			
Maximum number of modules specification*2		10			
Communication port		SSCNET II/H port x2			
Connection cable		SSCNET I cable (optical fiber cable)			
5 V DC internal current consumption		0.55 A			
Weight		0.20 kg			

^{*1:} This number includes only head modules. Servo amplifiers are not included.

^{*2:} Total number of occupied modules that can be mounted on SSCNET III/H head module. (Does not include the END cover or power supply module.)

Write communication protocol



#### **Ethernet Interface Module**



#### BACnet™ **MODBUS®/TCP**

#### Modify/collect CPU data from other devices

#### SLMP (MC protocol) communication*1

SLMP (Seamless Message Protocol) realizes seamless communication across devices on Ethernet that support the SLMP protocol.

*1: This function can be used with modules with first five serial number digits are "15042" or later.



#### **MELSOFT** connection

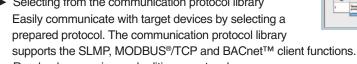
The MELSOFT connection feature realizes the connection to various MELSOFT products including the GX Works2 programming tool. In addition, by using together with the MX Component communication support tool (optional product), custom communications programs can be created, without having to consider any dedicated protocol (send/ receive procedure).

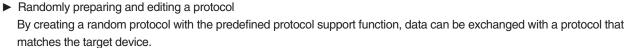
#### Easily connect to BACnet[™] and MODBUS®/TCP

#### **Predefined Protocol support function**

Use the GX Works2 Predefined Protocol support function to easily set the required protocol for communicating with other devices.

► Selecting from the communication protocol library Easily communicate with target devices by selecting a prepared protocol. The communication protocol library





#### ■ Specifications

Item			LJ71E71-100		
Standard			100 BASE-TX	10 BASE-T	
	Data transmission speed		100 Mbps	10 Mbps	
	Interface		RJ45 (AUTO MDI/MDI-X)		
Transmission	Communication m	iode	Full duplex/Half duplex	Half duplex	
specifications	Transmission met	hod	Base	band	
	Maximum segment length		100 m (length between a hub and node)*2		
	Maximum number of cascade connections		Cascade connection (maximum of 2 levels)*3	Cascade connection (maximum of 4 levels)*3	
	Number of simultaneous open connections		16 connections (Connections usable on a program)		
Sending/	Fixed buffer		1K word × 16		
receiving data storage	Random access buffer		6K words × 1		
memory	E-mail	Attachment	6K words × 1		
memory	E-maii	Main text	960 wc	rds x 1	
Maximum number of modules specification			Counts as 1 module		
Number of occupied I/O points			32 points (I/O assignment: Intelligent 32 points)		
5 V DC internal current consumption		ption	0.60 A		
Weight			0.18 kg		

^{*2:} For the maximum segment length (a length between hubs), consult with the manufacturer of the switching hub used.

High:

^{*3:} This applies when a repeater hub is used. For the number of levels that can be constructed when a switching hub is used, consult with the manufacturer of the switching hub used.

#### **Serial Communication Modules**



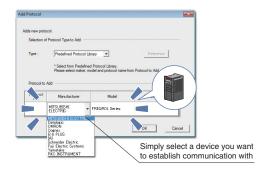




**MODBUS®** 

## Quick connection using predefined protocols

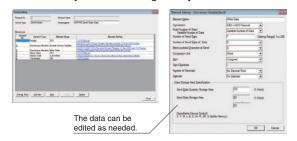
The predefined protocol enables easy setup of protocols to communicate with external devices using GX Works2. Connections are quickly setup by selecting the target device from the communications protocol library.



#### Easy to create/edit of predefined protocols

Easily create or edit predefined protocols from within the communications library.

Even if the target device protocol is not listed, it can be added easily to the existing library.



Item		LJ71C24	LJ71C24-R2		I-R2		
Interface	CH 1	RS-232 compliant (D-Sub 9P female)		RS-232 compliant (D	-Sub 9P female)		
interiace	CH 2	RS-422/485 compliant (2-piece terminal block)					
	Line	Full-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-duplex/half-d	luplex communica	tions			
	MC protocol	Half-duplex	communications				
Communication	Predefined protocol						
system	Nonprocedural protocol	Full-duplex/half-duplex communications					
	Bidirectional protocol						
Synchronization me	ethod	Asynchr	onous method				
		50 bps/300 bps/600 bps/1200 bps/			/		
		19.2 kbps/28.8 kbps/38.4 kbp					
Transmission spee	d	Transmission speed 230.4 k					
		Total transmission speed of two i					
		Total transmission speed of two interfaces is available up to 11	5.2 kbps when the	e communication data	monitoring function is used.		
	Start bits		1				
Data format	Data bits		7 or 8	8			
Data format	Parity bits	1 (vertical parity) or none					
	Stop bits	1 or 2					
	Parity check	All protocols and when ODD/EVEN is selected by parameter.					
Error detection		MC protocol/bidirectional protocol selected by parameter.					
Lifer detection	Sum check code	For the predefined protocol, whether or not a sum			elected protocol.		
		Nonprocedural protocol selected by user frame.					
			RS-232	RS-422/485			
		DTR/DSR (ER/DR) control	Enabled	Disabled			
		RS/CS control	Enabled	Disabled			
Transmission contr	ol	CD signal control	Enabled	Disabled			
		DC1/DC3 (Xon/Xoff) control DC2/DC4 control	Enabled	Enabled			
		DTR/DSR signal control and DC code control are selected by the user.					
Maximum number of modules specification		Counts as 1 module					
Number of occupied I/O points		32 points (I/O assignment: Intelligent 32 points)					
5 V DC internal cur	rent consumption	0.39 A		0.26	Α		
Weight		0.17 kg 0.14 kg		g			

CPU



#### **AnyWireASLINK Master Module**



#### **AnyWireASLINK**

#### Linking the sensor I/O with the programmable controller

The AnyWireASLINK master module links the sensor inputs and outputs to the programmable controller.

The module enables flexible layout of miniature sensors with 512 I/O points.

The sensor power can be supplied to the AnyWireASLINK transmission line (2-wire) for communication, allowing sensors to be added easily.

With the MELSEC-Q/L/F Series, faulty sensors can be detected and the slave module settings can be managed at once by GX Works2 engineering environment, further reducing the engineering time.

#### ■ Basic configuration

Either the 2-wire type or 4-wire slave device can be selected according to the load current for AnyWireASLINK. In addition to the 2-wire type, a 4-wire type can also be used by supplying the local power.

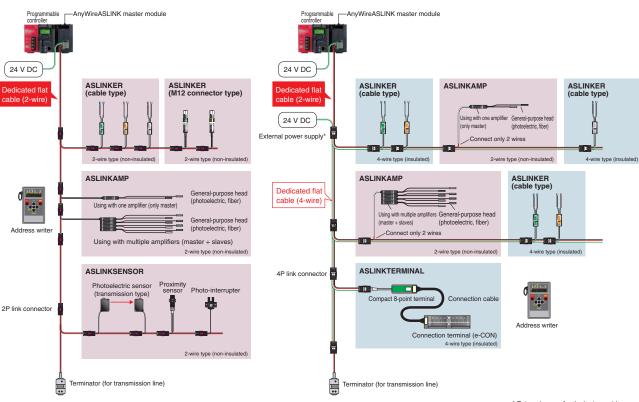
#### 2-wire type

If the load current is low, 2-wire type (non-insulated) slave devices can be used without an external power supply.

#### 4-wire type

The 4-wire type (insulated) slave devices require an external 24 V DC power supply to satisfy large load current applications, for example.

#### Configuration with 2-wire type (with no local power feed) Configuration with 2-wire/4-wire type (with local power feed)

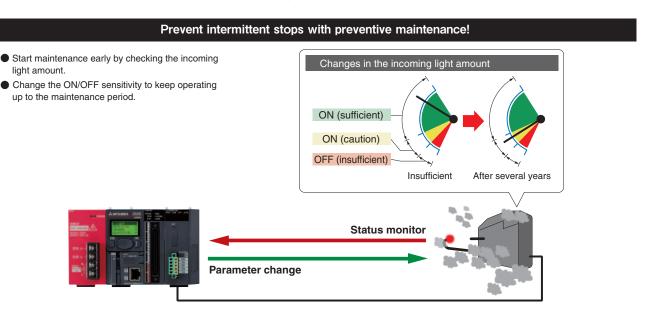


* External power for 4-wire type wiring.

56

#### **Preventing intermittent operation stops**

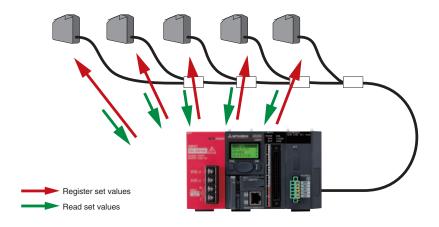
AnyWireASLINK can be used to monitor and save the sensor information within the programmable controller. Parameter settings of the AnyWireASLINK can also be changed via the programmable controller. Perform "Preventive maintenance" with this function to prevent intermittent stops before they happen.



#### Reducing the setup time, and providing the traceability

AnyWireASLINK enables the set value to be registered at once to multiple sensors via a GOT (HMI) or personal computer. Also, the initial set values can be re-confirmed easily without having to read each sensor individually.

• Register set values to multiple sensors, and automatically read the initial set values.



Item	LJ51AW12AL DB	
Transmission clock	27.0 kHz	
Maximum transmission distance (overall length)	200 m ^{⋆1}	
Transmission method	DC power superimposed total frame cyclic method	
Connection style	Bus type (multi-drop method, T-branch method, tree branch method)	
Transmission protocol	Dedicated protocol (AnyWireASLINK)	
Error control	Checksum, double verification method	
Number of connected I/O points	Max. 512 points (256 input points/256 output points)	
Number of connected modules	Max. 128 modules (varies according to each slave module's current consumption)	
RAS function	Transmission cable break position detection function, transmission cable short-circuit detection function, transmission power drop detection function	
Transmission cable (DP, DN)	<ul> <li>UL compatible universal 2-wire cable (VCTF, VCT 1.25 mm², 0.75 mm², rated temperature 70°C or more)</li> <li>UL compatible universal cable (1.25 mm², 0.75 mm², rated temperature 70°C or more)</li> <li>Dedicated flat cable (1.25 mm², 0.75 mm², rated temperature 90°C)</li> </ul>	
Power cable (24 V, 0 V)	<ul> <li>* UL compatible universal 2-wire cable (VCTF, VCT 0.75 mm²2.0 mm², rated temperature 70°C or more)</li> <li>* UL compatible universal cable (0.75 mm²2.0 mm², rated temperature 70°C or more)</li> <li>* Dedicated flat cable (1.25 mm², 0.75 mm², rated temperature 90°C)</li> </ul>	
Transmission cable supply current*2	Using 1.25 mm² cable: Max. 2 A Using 0.75 mm² cable: Max. 1 A	
Maximum number of modules specification	Counts as 1 module	
Number of occupied I/O points	32 points (I/O assignment: 32 intelligent points)	
External power supply	Voltage: 21.627.6 V DC (24 V DC -10+15%), ripple voltage 0.5 Vp-p or less Recommended voltage: 26.4 V DC (24 V DC +10%) Module current consumption: 0.1 A Transmission cable current supply: Max. 2 A*1	
5 V DC internal current consumption	Max. 0.2 A	
Weight	0.2 kg	

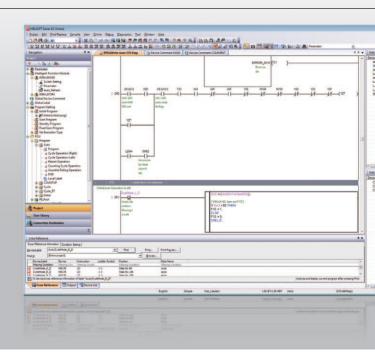
^{*1:} With the slave module having an integrated transmission cable (DP, DN) and module, the length of the transmission cable (DP, DN) is included in the overall length.

*2: Refer to the manual for the relation of the overall length, transmission cable (DP, DN) wire diameter and transmission cable current supply. In some slave modules with cables, the wire diameter of the transmission cable (DP, DN) integrated with the module may be 0.75 mm² or less.

# Increase productivity and lower the total cost of ownership

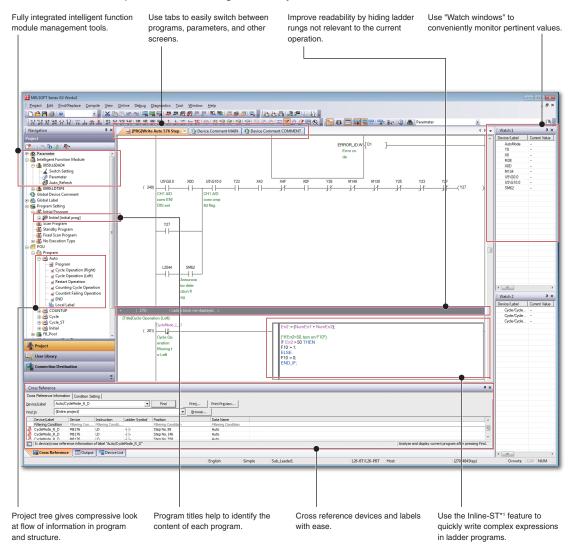
# GX Works2

GX Works2 focuses on driving down total cost by including features that speed up commissioning, reduce downtime, improve programming productivity, and provide strong security.



#### User interface that is "easy to use" by design

The programming tool GX Works2 has been developed from the ground up to be intuitive for all users and allow anyone to begin programming easily. The user interface and other functions provide a comfortable programming environment that enables improvements in design efficiency.

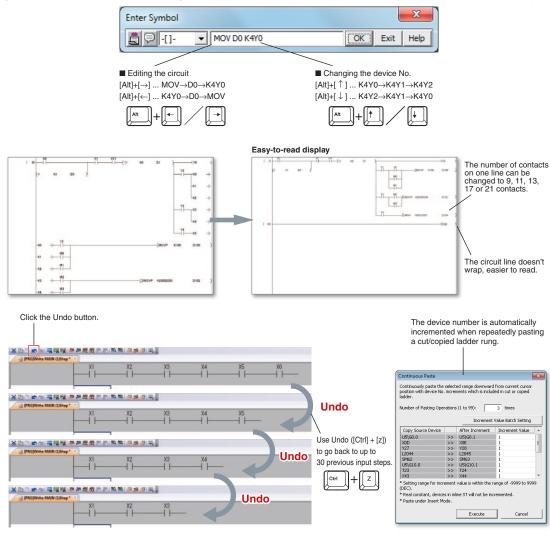


*1: In-line ST can be only be created in projects that use labels.



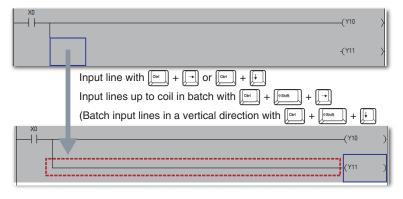
#### Easily create circuits with few key inputs

The program can be easily modified using the keyboard shortcut [Alt] + [  $\leftarrow$  ] / [  $\rightarrow$  ] or [Alt] + [  $\uparrow$  ] / [  $\downarrow$  ] keys.



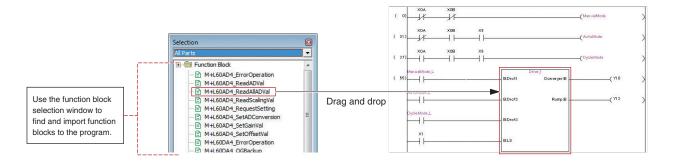
#### Efficiently edit lines with keyboard

Ladder rungs can be easily modified just by using the various keyboard shortcut keys, eliminating the need to switch to editing mode.



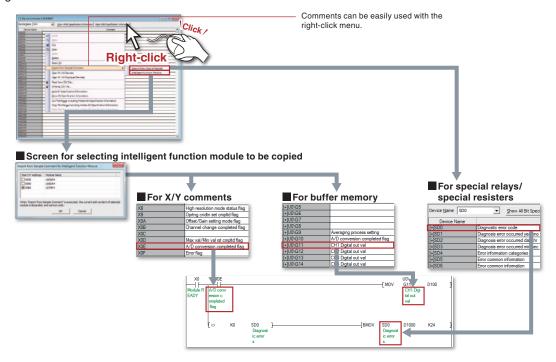
#### Use function blocks for common operations

Function blocks allow selections of commonly used code to be easily reused and shared among projects. Shared or created function blocks can be added to a program using simple drag and drop operation. Using function blocks effectively results in faster development times with fewer programming mistakes.



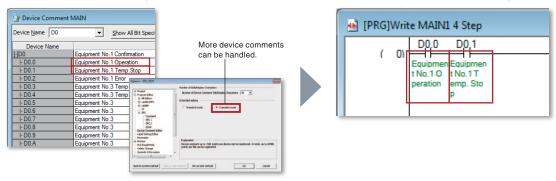
#### Use sample comments to eliminate the need to input comments

Sample comments are provided for the CPU's special relays/registers and the intelligent function module's buffer memory/XY signals. These can be copied into the project's comments thus greatly reducing the time required for entering device comments.



#### Quickly identify similar devices

Word device comments can be registered per bit with the contents displayed directly on the ladder rung.

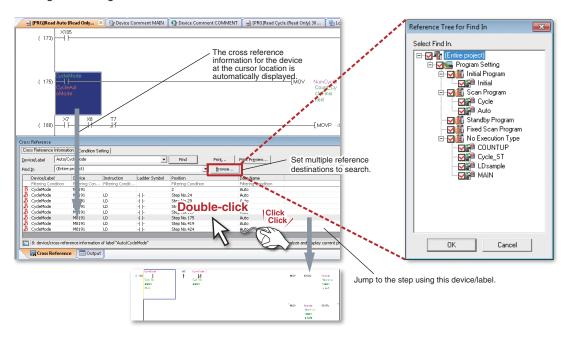


Function



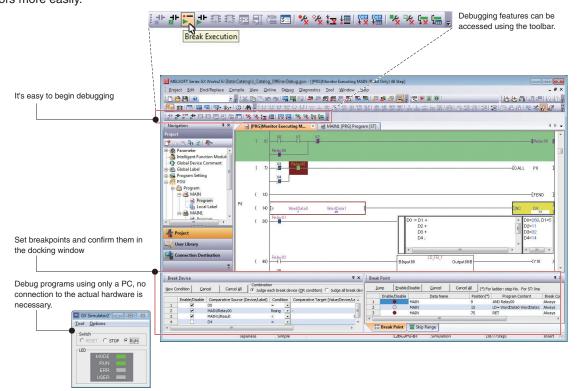
#### Cross referencing interlinked with circuit displays

Relevant devices and labels can be searched within the contents of the program by using the cross reference tool. The results are immediately displayed in the cross reference dialog box conveniently besides the actual program view screen. It is then very easy to check where the relevant device is actually used within the program, just by double clicking on the target device.



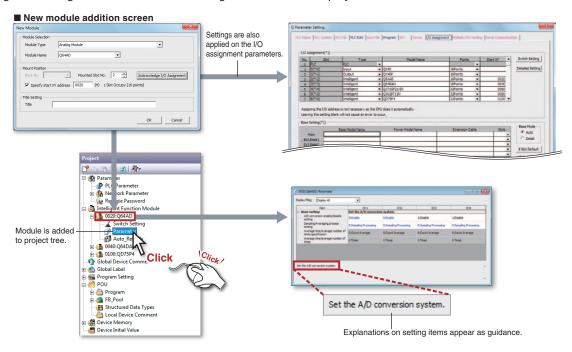
#### Offline debug without physical hardware

The simulation function is now integrated. The program can be executed in a step-by-step method, finding program errors more easily.



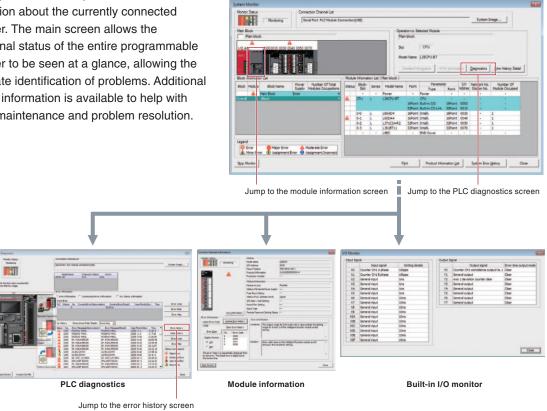
#### Integrating the intelligent function module setting tool (GX Configurator)

The intelligent function module's setting functions have been unified with GX Works2. Manage the intelligent function module's setting with a GX Works2 project.



#### Advanced PLC diagnostics

The diagnostics screen provides a wealth of information about the currently connected controller. The main screen allows the operational status of the entire programmable controller to be seen at a glance, allowing the immediate identification of problems. Additional detailed information is available to help with routine maintenance and problem resolution.

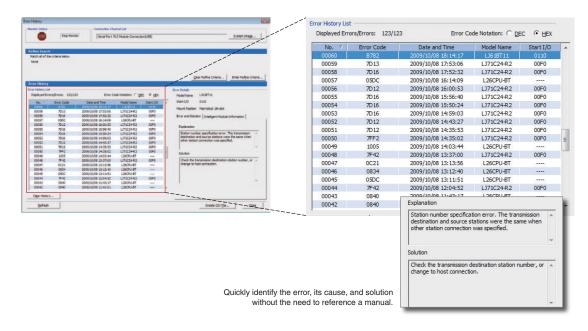


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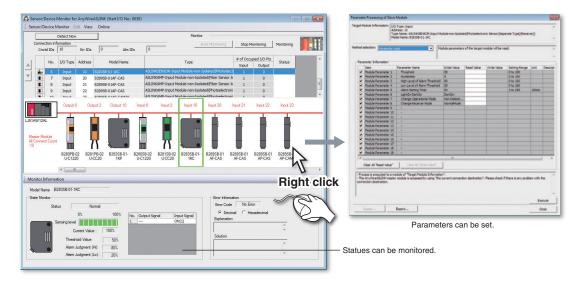
#### Time-stamped error history list

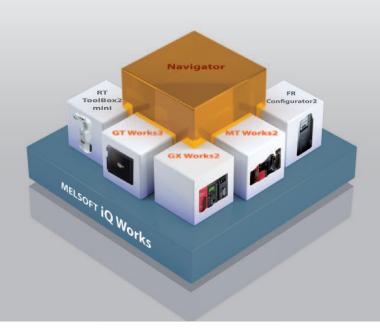
Simplify troubleshooting with a combined, time-stamped, error history list for the CPU and all expansion modules. The details section provides explanations of error codes and suggested solutions.



#### Set parameters and monitor the sensor

Parameter settings and monitoring can be performed on the third-party partner products, which support the iQ Sensor Solution (iQSS). Sensor connection and current values can be checked visually, allowing the user to act faster in case of a trouble.







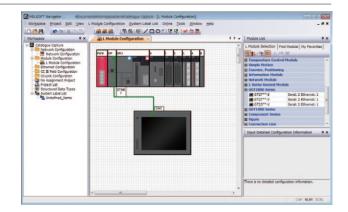
MELSOFT iQ Works is an integrated software suite consisting of GX Works3, MT Works2, GT Works3, RT ToolBox2 mini and FR Configurator2, which are programming software for each respective product.

#### **Graphic-based project management**

The entire control system is represented using the "Network Configuration" and "Module Configuration" windows.

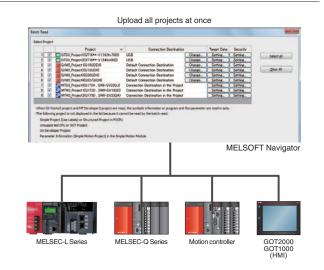
System components are easily added using a drag & drop interface and the validity of the system can be confirmed using the check function to ensure parameters are configured correctly, the power supply is sufficient, etc.

Different project types can be grouped together (for example by factory, line, and cell) for central management.



#### Read project data for multiple devices in a batch

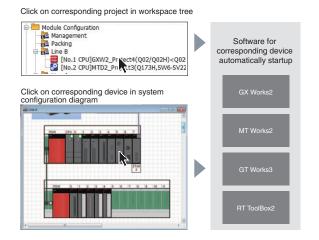
Multiple projects can be read as a block just by having one connection to the programmable controller. If there are multiple devices such as other CPU or GOT(HMI) on the same network as the target master programmable controller, it is possible to upload all projects to each target device without having to individually connect to each device.





#### Automatically startup the relevant maintenance software with a single click

Just click on the corresponding project in the system configuration diagram or workspace tree to automatically startup the software relevant for that device. Maintenance can be efficiently performed without having to know and startup each relevant software manually.

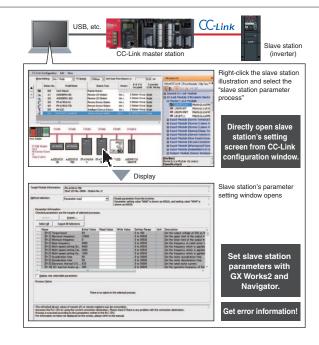


#### **Setup CC-Link slave stations**

There's no need to prepare a dedicated tool to check or change the parameter settings for the CC-Link slave station on-site.

The latest version of iQ Works includes CC-Link slave station setting utility. Therefore, it is possible to directly confirm the inverter parameters or change the settings for changing the speed directly from the CC-Link configuration window, for example.

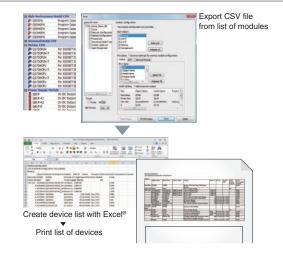
In addition, error information can also be read easily.

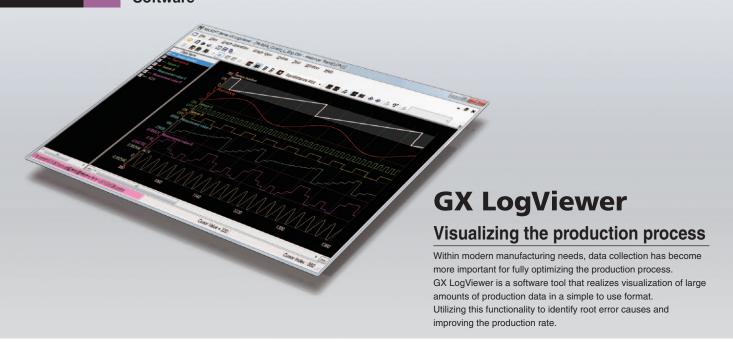


#### Prepare a device from the system configuration diagram with no manual inputs

A list of modules used can be exported as a CSV file from the system configuration diagram.

This is particularly useful when utilizing data for creating a bill of materials (BOM) in Excel®, etc.

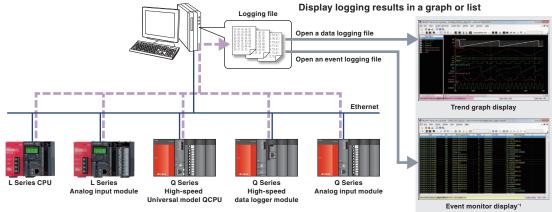




#### Easily display and analyze large amounts of collected logging data

This tool is used when large amounts of data need to be visualized and collected from the MELSEC-Q Series or MELSEC-L Series.

The connection settings and checking of log files are the same as GX Works2 enabling individual connections to each module.

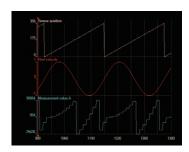


*1: The event monitor display is supported only with the Q Series high-speed logger module.

#### Easily adjust graphs without referring to the setup manual

#### Arranging graphs

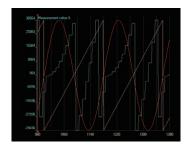
Able to arrange each graph so as not to overlap each other. It is easier to display the graphs as each graph is evenly spaced out.



#### Overlapping graphs

With this it is possible to overlap each graph over one another.

Multiple graphs can be compared enabling easier data analysis and comparison.



#### Automatically adjusting graphs

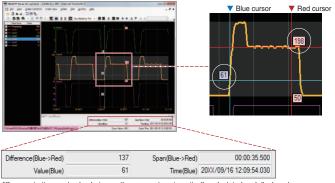
Various attributes of the graph are automatically adjusted (max/min values) as to display the upper and lower limit values better.





#### Easily confirm changes in data with dual cursors

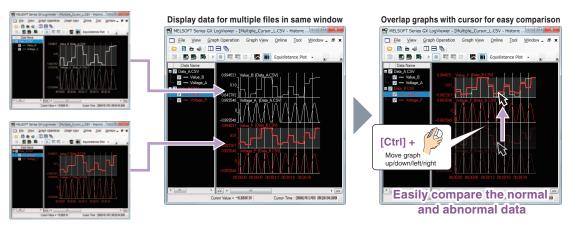
Data changes within a designated time frame can be quickly checked with user-friendly dual cursors (multi-cursors). When the cursors are moved to the point at which changes are to be confirmed, the difference in time and value between those points will appear.



The difference in time and value between the cursors is automatically calculated and displayed.

#### Display data for multiple files within one graph area for easy comparison

Data for multiple files are displayed with the same time units in the same graph area. The display position within a file can be moved easily. This allows the differences of data within multiple files to be confirmed easily.



#### Quickly jump cursor to designated position

#### **Cursor jump**

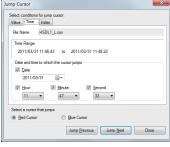
Confirm data values by quickly moving the cursor to a designated value, time or index position in the trend graph.





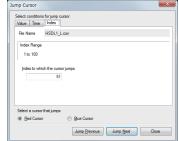
#### Value search

Values are searched, and the cursor jumps to the position where the conditions match.



#### Time designation

The cursor jumps to the designated time.



#### Index designation

The cursor jumps to the designated index.



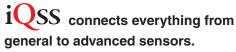
iQ Sensor Solution

## A tool for connecting! Visualizing! For a more seamless sensor control!

Sensors used on the manufacturing floor are becoming more intelligent and complex, requiring even more maintenance of equipment and the overall management of various configuration setup software. With iQSS, the intelligent sensor solution provided by Mitsubishi Electric, configuration and maintenance of sensors are further simplified with the connectivity to other components such as automation controllers, HMIs, and engineering software even further enhanced reducing the overall TCO*. * Total Cost of Ownership

For further details, please refer to the "iQ Sensor Solution Catalog".







CC-Línk | Future release



**Ethernet** 

**AnyWireASLINK** 





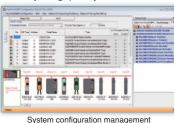






#### System design

To manage projects simply, we provide a workspace tree that enables projects to be managed in a single location, and a system configuration chart that depicts the entire system graphically.



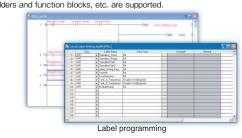
### Implementation

Functions are provided that allow monitoring from a single screen based on the system configuration chart so that the causes of problems can be identified quickly. This also shortens the time taken to adjust sections involving multiple devices.



#### **Programming**

The labels used by PLCs can also be used by HMIs and sensors. This takes all the bother out of label setting. GOT sample screen libraries, sample ladders and function blocks, etc. are supported.



#### **Operation & maintenance**

To make backups less laborious, batch read/write functions are provided for PLC, HMI and sensor settings



Further simplifying the management of sensors in the control system



**Vision Solution** 

# COGNEX® machine vision system and Mitsubishi Electric FA Devices

# Innovating your production with this integral power.

Functioning as devices that "watch" instead of human eyes, COGNEX machine vision systems have continued to reform automation of production lines. Mitsubishi Electric FA devices, such as programmable controllers, lead the future of automation.

The possibilities of vision system solutions, created in the integration of this spirit of innovation, have continued to increase.



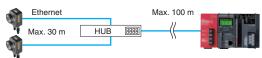
For further details. please refer to the "Vision System & **Factory Automation** Solution Catalog".

COGNEX In-Sight EZ Series	iQSS ready!	Device partner
• Entry model		EZ-700
Standard model		EZ-720
High-speed processing model		EZ-740
High resolution model		EZ-742

#### Simple connection

#### **Directly connect with Ethernet**

The "In-Sight EZ" can be directly connected to the Ethernet port provided on the "MELSEC-Q Series universal model" and "MELSEC-L" programmable controller, and to the Ethernet module on the MELSEC-F. By using a switching hub, a multi-unit vision system having units installed as far as 100 m away can be created.



No additional network module is required.

#### Simple communication with SLMP

Now that "In-Sight EZ" supports SLMP, data can be easily written from the vision system to the programmable controller. Communication is easily configured with "EasyBuilder". Just select the connected device and SLMP, set the programmable controller device used for communication and select the communication data from the list. With the SLMP scanner mode, a trigger can be applied on the vision system via SLMP.

#### Simple control with function blocks (FB)

Intuitively setup the vision control system from the GX Works2 programming tool utilizing dedicated vision function blocks without having to develop specific programming code.

#### COGNEX DataMan® Barcode Reader Device partner

- Fixed DataMan 50/60/300 • Hand-held DataMan ..........DataMan 8050/8100/8500
- DataMan active in various industries









Automotive

components

#### ●Fixed DataMan 50/60

- ▶ Unmatched read rate performance with Hotbars™
- ▶ Proprietary Hotbars™ technology
- Solid state design with no moving parts
- Easy setup with three position adjustable lens and integrated lighting aimer
- ▶ IP65-rated housing (DataMan 50)
- ▶ Supports SLMP (DataMan 60)

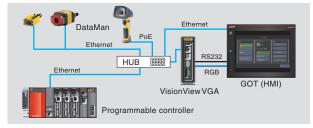
DataMan 50

DataMan 60

#### ●Fixed DataMan 300 Series

- ▶ Unprecedented read rate with Hotbars™
- ▶ Reads the most difficult-to-read 2-D Direct Part Mark (DPM) codes
- Liquid lens with automatic variable focus
- ▶ Intelligent tuning
- Integrated lighting module
- ▶ Supports SLMP





#### ●Hand-held DataMan 8050/8100/8500 Series

- ▶ UltraLight®: Two types of lighting enable optimum reading*1
- Newly developed body enhances sturdiness
- ▶ Standard automatic focus adjustment function*2
- ▶ Supports SLMP
- ▶ Cordless capability (up to 30 m communication range)
- ▶ Unprecedented read rate with Hotbars™
- *1: DataMan 8500
- *2: DataMan 8100 and 8500





# Combination with GOT for all scenes from startup to maintenance

The GOT2000 boasts advanced functionality, acts as a seamless gateway to other industrial automation devices, all while increasing productivity and

The high quality display is designed to optimize operator control and monitoring of device and line statuses. If you are looking for an intuitive operation terminal, the new tablet-like operability and the higher functionality of operation terminal makes the GOT2000 the ideal choice.

Incorporate the GOT2000 to bring forth flexibility, productivity, and quality on a global scale.

For further details, please refer to the "Mitsubishi Graphic Operation Terminal GOT2000 Series Catalog"

GOT2000 series/GOT1000 series

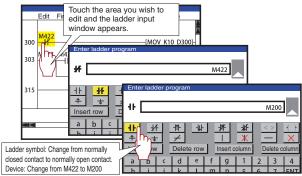


L(NA)08270ENG

#### **Graphic Operation Terminal**

Ladder programs can easily be edited on the GOT Sequence Program Monitor (Ladder Editor)..... GT27/GT25/GT16/GT15

Sequence programs can be edited in a circuit diagram (ladder format). To quickly change contacts in an emergency, sequence programs can be edited in ladder format without using a personal computer.



- Supported by XGA / SVGA / VGA models excluding the 5.7-inch type
- * Process CPUs, redundant CPUs are not supported.

#### Program debugging can be performed without opening the control panel

#### FA Transparent All models

Connected with a PC, the GOT acts as a transparent gateway to enable programming, start up, and adjustment of equipment using GX Works2 or GX LogViewer. Users do not have to bother with opening the control panel or changing cable connections.

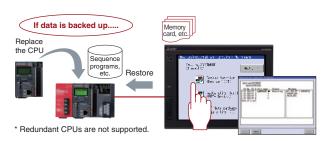


(On the GT23, GT21, or GT10 Series, the FA transparent function can be used via the interface on the rear side.)

#### Programmable Controller can be recovered promptly in case of emergency

#### Backup/Restore.....gtz/gtz5/gtz3/gtz1/gt16/gt15/gt14/gt12

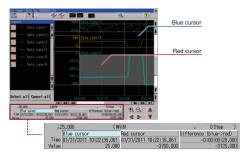
Sequence programs and parameters can be backed up to the memory card or USB memory in the GOT. Users can perform batch operation to restore the data to the PLC CPU or motion controller. Make a data backup in case of a problem such as a dead battery in a PLC CPU to quickly replace the faulty device and restore the system without using a personal computer.



#### View logging data without a PC

Log Viewer.....GT27/GT25/GT16

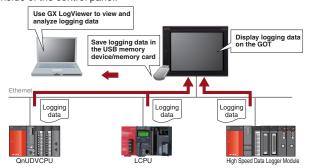
Logging data can be confirmed with the GOT even if a PC is not available on-site, allowing problems to be troubleshooted quickly. Changes in the data can be quickly confirmed with the dual cursors (multi-cursors) that are displayed similar to GX LogViewer.



#### Logging data can be collected without opening the control panel

Log Viewer...... GT27/GT25/GT16

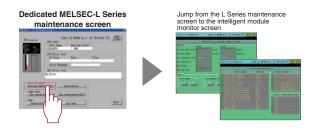
In a USB memory device attached to the USB interface on the front of the GOT, the logging data can be saved. The logging data can easily be collected without removing the SD card from the CPU inside of the control panel.



#### Various functions of GOT support your maintenance work

#### MELSEC-L Troubleshooting.....gtz/GT25/GT16

Just one touch to jump to the functions such as the intelligent module monitor to quickly perform troubleshooting at the worksite.





# Man, machine and environment in perfect harmony

# MELSERVO-J4 — trusted technology makes an evolutionary leap forward.

Introducing the MELSERVO-J4 series. Offering more than just improved performance, these servos are designed to drive the industries of tomorrow. Backed by Mitsubishi leadership in all-digital technology, MELSERVO has become one of the most globally respected names in factory automation. And now — with the safety, ease of use, and energy-efficient design of the new MELSERVO-J4 series man, machine and environment can at last work together in perfect harmony.

For further details, please refer to the "MELSERVO-J4" catalog.



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MITSUBISHI SERVO AMPLIFIERS & MOTORS OF LOCAL PROPERTY OF LOCAL PR



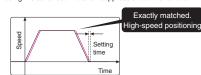


# The leading edge in drive control

- Industry-leading level of basic performance
- · High-resolution absolute position encoder
- Advanced one-touch tuning
- $\bullet$  Advanced vibration suppression control  ${\rm I\hspace{-.1em}I}$
- Robust filter

# [Advanced one-touch tuning]

Servo gains including vibration suppression control and robust filter are adjusted just by turning on the one-touch tuning function. Machine performance is utilized to the fullest using the advanced vibration suppression control function



# Man

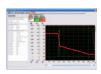
# Safety and convenience

- Equipped with the safety observation function (IEC/EN 61800-5-2)
- · Tough drive function
- · Large capacity drive recorder
- Machine diagnosis function
- MR Configurator2

# [Large capacity drive recorder]

Servo data (motor current, etc.) before and after the alarm occurrence are stored in non-volatile memory. Waveforms can be checked in graph. This enables guick and accurate identification of the cause of the alarm.





# The Environment

Eco-friendly design that's winning acclaim worldwide

- Multi-axis servo amplifier
- · Power monitor function
- · Compatible with power regeneration common converter
- Energy-conservation achieved by improved performance

# [Power monitor function]

Power consumption is calculated from the data in the servo amplifier such as speed and current, and then displayed, enabling energy-conserving system examination



# Lineup

# **Servo Amplifiers**





**Servo Motors** 

MR-J4-B SSCNET II/H compatible servo amplifier

# MR-J4W2-B

SSCNET II/H compatible 3-axis servo amplifier

With the SSCNET III/H compatible servo amplifier, a synchronous system can be configured using high-speed serial optical communication. Servo system performance and functions are utilized to the fullest when the servo amplifier is combined

# CC-Línk | F | Field



MR-J4-B-RJ010 + MR-J3-T10 CC-Link IE Field Network servo amplifier with Motion

The CC-Link IE Field Network interface servo amplifier with Motion is compatible with the Motion control in the Ethernet-based open network



MR-J4-A

General-purpose interface compatible servo amplifier

The general-purpose interface compatible servo amplifier enables position control by pulse train command and speed/torque control by analog voltage command.

# Rotary servo motor



HG-KR Series



Small capacity, **HG-MR** Series

Capacity: 50 to 750 W



Medium capacity, medium inertia **HG-SR** Series Capacity: 0.5 to 7 kW



Medium/large capacity, **HG-JR** Series Capacity: 0.5 to 55 kW



Medium capacity, **HG-RR** Series Capacity: 1 to 5 kW



Medium capacity, flat type **HG-UR** Series Capacity: 0.75 to 5 kW

# Linear servo motor



LM-H3 Series Rating: 70 to 960 N

Core type with magnetic

attraction counter-force

LM-K2 Series

Rating: 120 to 2400 N



(natural/liquid cooling) LM-F Series



Coreless type LM-U2 Series Rating: 50 to 800 N

# Direct drive motor



TM-RFM Series Rating: 2 to 240 N·m



# Inverter

Inverter

# Achieving higher drive performance and energy conservation with inverters

The inverter is a variable frequency power device that can easily and freely change the speed of a 3-phase induction motor.

The Mitsubishi inverter is high-performance and environment-conscious, and complies with global standards.

Select a model from our diverse lineup to match your needs.

# Answering various needs with the best choices Frequency Inverter



# FR-700 Series E700, F700PJ, D700 FR-A800 New advanced functionality and high-performance inverter FR-F800 New Energy-saving premium inverter for fans and pumps FR-F700PJ Air conditioning inverter FR-F700PJ Air conditioning inverter FR-D700 Simple and compact inverter

# **Control inverter with CC-Link communication**

The inverter can be controlled to a programmable controller with CC-Link. 11

This function is supported with CC-Link Ver. 1.1 and Ver. 2.0.

The inverter can be operated and monitored, and the parameters set from the programmable controller.



*1: The inverter option card (FR-A8NC) is required.

Please refer to the relevant catalog for additional information.

# Easy synchronous operation with SSCNET II connection

-- A800, F800

Connect to a motion controller with SSCNET II ². SSCNET II uses the high-speed synchronous serial communication method (high-speed, high-accuracy, high-reliability optical communication), and is perfect for synchronous operation.

(SSCNET: Servo System Controller Network)

Capacity (kW) =



*2: The inverter option card (FR-A7NS) is required.



# **Diverse variations** to respond to all situations

The Mitsubishi Electric Contactors and Motor Starters MS-T and MS-N series and DC interface contactor SD-Q series products are equipped with an environment and global compliance, compact size, ease-of-use and safety. Certification to various international standards, this highly reliable magnetic contactor is suitable for a variety of applications from panels to systems.





L(NA)02030

L(NA)74109218

For further details, please refer to the "Magnetic Motor Starters and Contactors MS-T/N series Catalog".

# Transistor output Triac output Relay output DC interface contractor SD-Q DC interface module Motor Motor Starter MSO-T Motor

# **Direct drive with Programmable Controller**

The SD-Q Series has a small coil VA and can be driven by the programmable controller without adding an amplifying relay. By adding the DC interface module, the MS-T/N Series can be used with a wide range of motor capacities.

		Programmable controller output module type			
		Transistor output	Contact output	Triac output	
DC interface contactor SD-Q Series	DC operation	•	•	_	
Magnetic contactor MS-T Series	AC operation	(Using DC interface module)	•	•	
Magnetic contactor	AC operation	(Using DC interface module)	•	•	
MS-N Series	DC operation	Δ	_	_	

^{*:} This table shows the relation of the programmable controller output module type and operation interface. There may be restrictions according to the type of frame size, etc., that can be used. Refer to the MS-T/N Series Catalog, or contact a Mitsubishi dealer or Sales Office for details on the types of magnetic switches and models that can be used.

# **SD-Q** series

Direct drive is possible with the programmable controller's transistor output. Since a relay and interface module are not required, the number of parts can be reduced, and space can be saved.

# Standard surge absorber

Prevent adverse effects onto the peripheral equipment.

# Standard terminal cover

A terminal cover with finger protection function is installed as a standard.

This cover answers to user's needs for safety.

# MS-T series (10A to 32A)

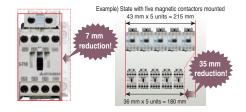
Mitsubishi Electric's main series is equipped with a small size, ease-of-use, safety and international compliance. This series greatly contributes to smaller panels, easier selection and compliance with international standards.

# 10A frame model is just 36 mm wide!!

The industry's smallest width has been realized for the general-purpose magnetic contactor.

The other rated products have also been downsized to help you reduce your panel size.

*: 10A frame general-purpose magnetic contactor (Mitsubishi Electric survey as of Oct. 2014)



# Wide range of operation coil ratings!!

The wider operation coil rating ranges allow us to consolidate the number of coil types from 14 types (N Series) to 7 types.

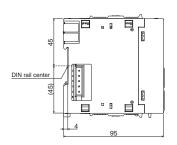
This helps reduce stock and makes it easier to select the required type.

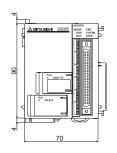
# Standard terminal cover!!

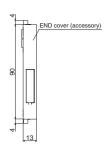
The standard terminal cover improves the safety in the panel, and simplifies ordering as a separate model no longer needs to be specified.

# CPU modules

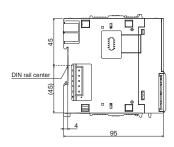
L02SCPU, L02SCPU-P

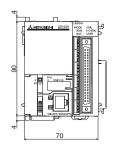


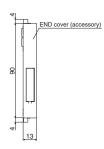




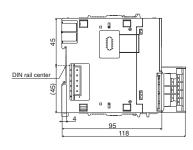
L02CPU, L02CPU-P, L06CPU, L06CPU-P, L26CPU, L26CPU-P

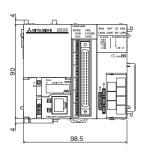


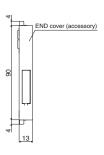




L26CPU-BT, L26CPU-PBT

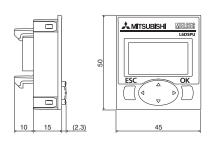






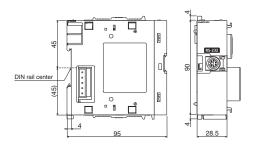
# Display unit

L6DSPU



# RS-232 adapter

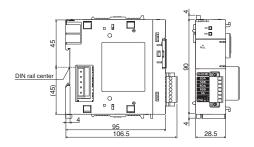
L6ADP-R2





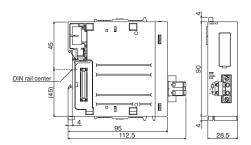
# RS-422/485 adapter

# L6ADP-R4



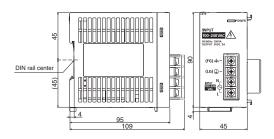
# END cover with error terminal

L6EC-ET

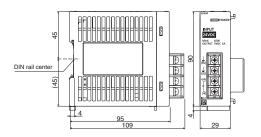


# Power supply modules

L61P, L63P

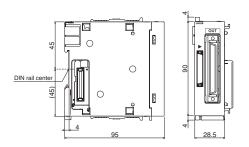


L63SP



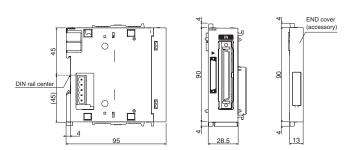
# Branch module

# L6EXB



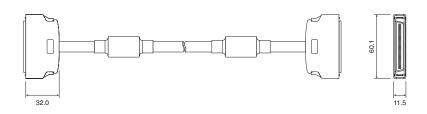
# **Extension module**

# L6EXE



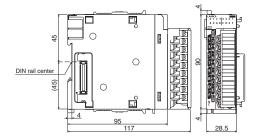
# Extension cable

LC06E, LC10E, LC30E

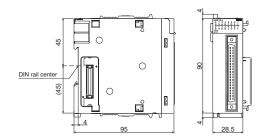


# Input/Output/I/O combined modules

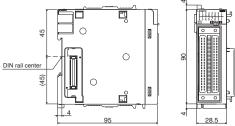
LX10, LX28, LX40C6, LY10R2, LY18R2A NEW LY20S6, LY28S1A NEW , LY40NT5P, LY40PT5P



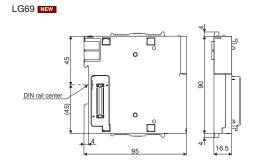
LX41C4, LY41NT1P, LY41PT1P



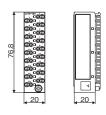
LX42C4, LY42NT1P, LY42PT1P LH42C4NT1P, LH42C4PT1P



LH42C4NTTP, LH42C4PTTP

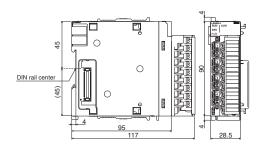


L6TE-18S NEW



# Multiple input (voltage/current/temperature)/Analog input/output/I/O module

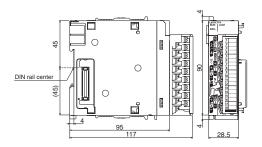
L60MD4-G NEW, L60AD4, L60DA4, L60ADVL8 NEW, L60ADIL8 NEW, L60AD4-2GH, L60AD2DA2



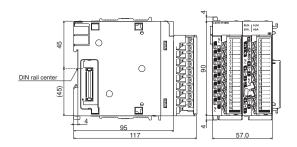


# **Temperature control modules**

L60TCTT4, L60TCRT4

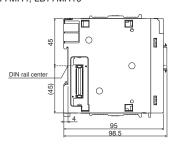


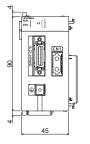
# L60TCTT4BW, L60TCRT4BW



# Simple motion module

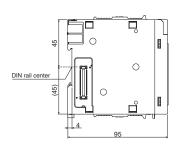
LD77MS2, LD77MS4, LD77MS16, LD77MH4, LD77MH16

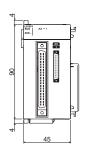




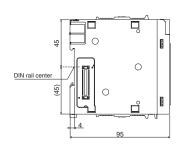
# **Positioning modules**

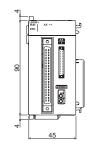
LD75P1, LD75P2



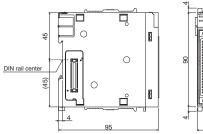


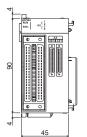
LD75D1, LD75D2



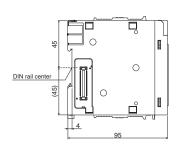


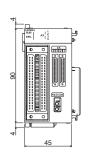
LD75P4





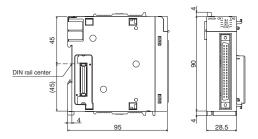
LD75D4





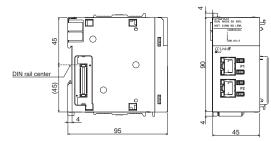
# High-speed counter module

LD62, LD62D



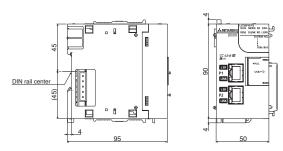
# CC-Link IE Field Network master/local module

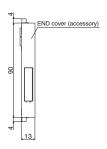
LJ71GF11-T2



# CC-Link IE Field Network head module

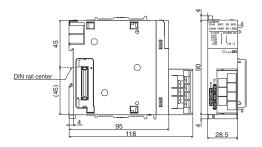
LJ72GF15-T2





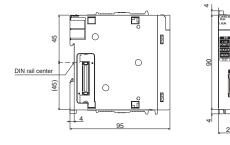
# CC-Link master/local module

LJ61BT11



# CC-Link/LT master module

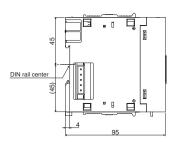
LJ61CL12

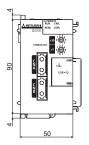


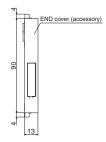


# SSCNET II/H head module

# LJ72MS15

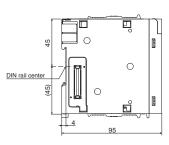


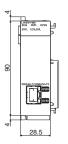




# Ethernet interface module

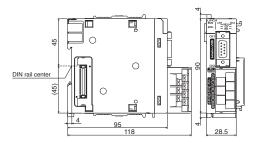
LJ71E71-100



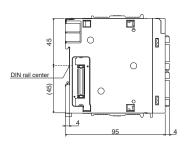


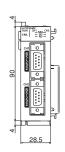
# Serial communication modules

LJ71C24



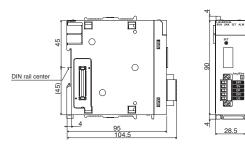
LJ71C24-R2





# AnyWireASLINK master module

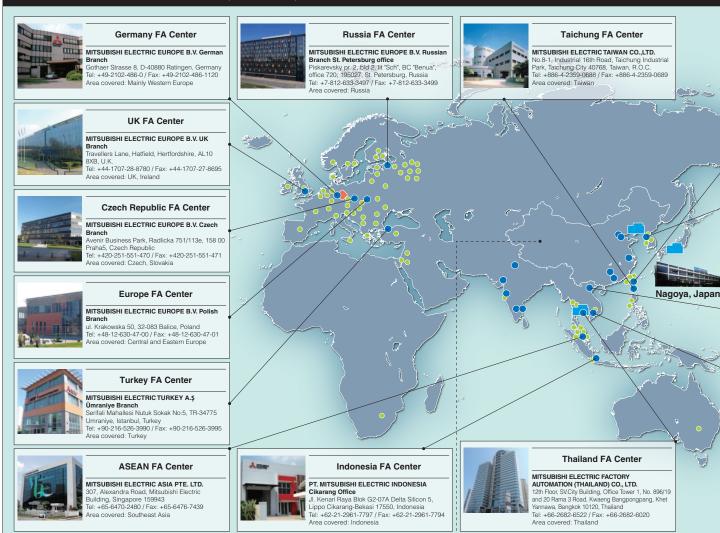
LJ51AW12AL DB



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Mitsubishi Electric Global FA centers have been established in various countries around the world to cover the Americas, Europe and Asia. FA centers help to ensure compliance with the certifications and regulations of different regions, initiate product development in response to local demands and provide full-time, professional customer service.





# **Beijing FA Center**

MITSUBISHI ELECTRIC AUTOMATION (CHINA)

Unit 901, 9F, Office Tower 1, Henderson Centre, 18 Jianguomennei Avenue, Dongcheng District, Beijing, China Tel: +86-10-6518-8830 / Fax: +86-10-6518-2938

Area covered: China

# Tianjin FA Center

MITSUBISHI ELECTRIC AUTOMATION

MITSUBISH ELECT HIC AUTOMATION (CHINA) LTD. Tianjin Branch
Room 2003 City Tower, No.35, Youyi Road,
Hexi District, Tianjin, China
Tei: +86-22-2813-1015 / Fax: +86-22-2813-1017
Area covered: China



# Guangzhou FA Center

MITSUBISHI ELECTRIC AUTOMATION

(CHINA) LTD. Guangzhou Branch Room 1609, North Tower, The Hub Center No. 1068, Xingang East Road, Haizhu District, Guangzhou, China Tel: +86-20-8923-6730 / Fax: +86-20-8923-6715

# China (including Hong Kong area) Changchun Xiangyang Shanghai Chengdu Wuhang. Fuzhou Taipei Taichung Shenzher Hong Kong

# Local factory in China

Mitsubishi Electric Dalian Industrial Products Co., Ltd.

# Local factory in China

Mitsubishi Electric Automation Manufacturing (Changshu) Co., Ltd.

No.706 Southeast Building, Chengahu Southeast Economic Development Zone of Jiangsu, 215500

China
Tel: +86-512-5213-3077 / Fax: +86-512-5213-3088

# Shanghai FA Center

## MITSUBISHI ELECTRIC AUTOMATION (CHINA) LTD.

(CHINA) LTD. No.1386 Hongqiao Road, Mitsubishi Electric Automation Center, Shanghai, China Tel: +86-21-2322-3030 / Fax: +86-21-2322-3000 Area covered: China

# help whenever needed.



# **Product List**

Please refer to the product user manuals for information about compatible modules, restrictions, etc., before using the products.

Please visit the Mitsubishi Electric FA site or contact your nearest branch for the latest information on the MELSOFT versions and compatible OS.

[ Legend ] DB : Double brand product (Note) NEW : Recently released product SOON : Product available soon

# MELSEC-L series

MILLOLO L	Туре	Model	Outline
,,,,,		L02SCPU	Number of I/O points: 1024 points, Number of I/O device points: 8192 points, Program capacity: 20K steps, Basic operation processing speed (LD instruction): 60 ns, Program memory capacity: 80 KB, Peripheral connection ports: USB and RS-232 (Predefined protocol support function), Memory card I/F: None, Built-in I/O functions (General-purpose input: 16 points, General purpose output (Sink type): 8 points,
		L02SCPU-P	Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included  Number of I/O points: 1024 points, Number of I/O device points: 8192 points, Program capacity: 20K steps, Basic operation processing speed (LD instruction): 60 ns, Program memory capacity: 80 KB, Peripheral connection ports: USB and RS-232 (Predefined protocol support function), Memory card I/F: None, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Source type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
		L02CPU	Number of I/O points: 1024 points, Number of I/O device points: 8192 points, Program capacity: 20K steps, Basic operation processing speed (LD instruction): 40 ns, Program memory capacity: 80 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Sink type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
		L02CPU-P	Number of I/O points: 1024 points, Number of I/O device points: 8192 points, Program capacity: 20K steps, Basic operation processing speed (LD instruction): 40 ns, Program memory capacity: 80 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Source type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
		L06CPU	Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 60K steps, Basic operation processing speed (LD instruction): 9.5 ns, Program memory capacity: 240 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Sink type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
CPU		L06CPU-P	Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 60K steps, Basic operation processing speed (LD instruction): 9.5 ns, Program memory capacity: 240 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Source type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
		L26CPU	Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 260K steps, Basic operation processing speed (LD instruction): 9.5 ns, Program memory capacity: 1040 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Sink type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
		L26CPU-P	Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 260K steps, Basic operation processing speed (LD instruction): 9.5 ns, Program memory capacity: 1040 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Source type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), END cover included
		L26CPU-BT	Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 260K steps, Basic operation processing speed (LD instruction): 9.5 ns, Program memory capacity: 1040 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Sink type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), CC-Link master/local station function, END cover included
		L26CPU-PBT	Number of I/O points: 4096 points, Number of I/O device points: 8192 points, Program capacity: 260K steps, Basic operation processing speed (LD instruction): 9.5 ns, Program memory capacity: 1040 KB, Peripheral connection ports: USB and Ethernet (Predefined protocol support function), Memory card I/F: SD Memory Card, Built-in I/O functions (General-purpose input: 16 points, General-purpose output (Source type): 8 points, Interrupt input, Pulse catch, Positioning, High-speed counter), CC-Link master/local station function, END cover included
		L02CPU-SET	CPU module (L02CPU), Display unit (L6DSPU), and Power supply module (L61P) set
		L02CPU-P-SET	CPU module (L02CPU-P), Display unit (L6DSPU), and Power supply module (L61P) set
		L06CPU-SET	CPU module (L06CPU), Display unit (L6DSPU), and Power supply module (L61P) set
CPU packages		L06CPU-P-SET	CPU module (L06CPU-P), Display unit (L6DSPU), and Power supply module (L61P) set
or o packages		L26CPU-SET	CPU module (L26CPU), Display unit (L6DSPU), and Power supply module (L61P) set
		L26CPU-P-SET	CPU module (L26CPU-P), Display unit (L6DSPU), and Power supply module (L61P) set
		L26CPU-BT-SET	CPU module (L26CPU-BT), Display unit (L6DSPU), and Power supply module (L61P) set
	Disalance	L26CPU-PBT-SET	CPU module (L26CPU-PBT), Display unit (L6DSPU), and Power supply module (L61P) set
	Display unit	L6DSPU	STN black-and-white LCD, 16 characters x4 lines
	Battery	Q6BAT Q7BAT-SET	Replacement battery High capacity battery with a battery holder for CPU installation
	Dattery	Q7BAT-SET	High capacity replacement battery
		L1MEM-2GBSD*1	2GB SD Memory Card
CPU options	SD Memory Card	L1MEM-4GBSD*1	4GB SD Memory Card
2 36.0.0		L TWILINI TODOD	For GOT(HMI) connection, 1 x RS-232 channel, maximum transmission speed: 115.2Kpbs, MELSOFT
	RS-232 adapter	L6ADP-R2	MODBUS® RTU master function (using predefined protocol support function)
	RS-422/485 adapter	L6ADP-R4	For GOT(HMI) connection, 1 x RS-422/485 channel, maximum transmission speed: 115.2Kpbs
	·		MODBUS® RTU master function (using predefined protocol support function)
END cover wit	h error terminal	L6EC-ET	END cover with error terminal

END cover with error terminal

*1: Mitsubishi Electric does not guarantee the operation of non-Mitsubishi Electric products.

Note: General specifications and product guarantee conditions of jointly developed products are different from those of MELSEC products. For more information, please refer to the product manuals or contact your local Mitsubishi representative for details.

# MELSEC-L series

	Туре		Model	Outline
			L61P	Input voltage: 100240 V AC, Output voltage: 5 V DC, Output current: 5 A
Power supply			L63P	Input voltage: 24 V DC, Output voltage: 5 V DC, Output current: 5 A
Slim type Power supply		Power supply	L63SP	Input voltage: 24 V DC, Output voltage: 5 V DC, Output current: 5 A, No isolation
Duanala / Estan	-1		L6EXB	Branch module
Branch / Exten	sion module	•	L6EXE	Extension module with END cover
			LC06E	0.6-m cable for connecting branch and extension modules
	Extension	cable	LC10E	1.0-m cable for connecting branch and extension modules
			LC30E	3.0-m cable for connecting branch and extension modules
			LX10	16 points, 100120 V AC, Response time: 20 ms or less, 16 points/common, 18-point terminal block
		AC input	LX28	8 points, 100240 V AC, Response time: 20 ms or less, 8 points/common, 18-point terminal block
			1,7,4000	16 points, 24 V DC, Response time: 1/5/10/20/70 ms or less,
	lt		LX40C6	16 points/common, Positive/Negative common, 18-point terminal block
	Input	DO immed	1.7/44.04	32 points, 24 V DC, Response time: 1/5/10/20/70 ms or less,
		DC input	LX41C4	32 points/common, Positive/Negative common, 40-pin connector
			LX42C4	64 points, 24 V DC, Response time: 1/5/10/20/70 ms or less,
			LX42U4	32 points/common, Positive/Negative common, 40-pin connector x2
			LY10R2	16 points, 24 V DC/240 V AC, 2 A/point, 8 A/common, Response time: 12 ms or less,
		Relay	LY IURZ	16 points/common, 18-point terminal block
		nelay	LY18R2A NEW	8 points, 24 V DC/240 V AC, 2 A/point, 8 A/module, Response time: 12 ms or less,
			LI IONZA NEW	No common (all points independent), 18-point terminal block
			LY20S6	16 points, 100240 V AC, 0.6 A/point, 4.8 A/common, Response time: 1 ms + 0.5 cycles or less,
		Triac	L12050	16 points/common, 18-point terminal block
			LY28S1A NEW	8 points, 100240 V DC, 1 A/point, 8 A/module, Response time: 1 ms + 0.5 cycles or less,
				No common (all points independent), 18-point terminal block
		Transistor	LY40NT5P	16 points, 1224 V DC, 0.5 A/point, 5 A/common, Response time: 1 ms or less, 16 points/common,
	Output			18-point terminal block, overload protection function, overheat protection function, surge suppression
	Output		LY41NT1P	32 points, 1224 V DC, 0.1 A/point, 2 A/common, Response time: 1 ms or less, 32 points/common,
I/O module		(Sink)	LITINITIF	Sink type, 40-pin connector, overload protection function, overheat protection function, surge suppression
			LY42NT1P	64 points, 1224 V DC, 0.1 A/point, 2 A/common, Response time: 1 ms or less, 32 points/common,
				Sink type, 40-pin connector x2, overload protection function, overheat protection function, surge suppression
			LY40PT5P	16 points, 1224 V DC, 0.5 A/point, 5 A/common, Response time: 1 ms or less, 16 points/common,
				18-point terminal block, overload protection function, overheat protection function, surge suppression
		Transistor	LY41PT1P	32 points, 1224 V DC, 0.1 A/point, 2 A/common, Response time: 1 ms or less, 32 points/common,
		(Source)		40-pin connector, overload protection function, overheat protection function, surge suppression
			LY42PT1P	64 points, 1224 V DC, 0.1 A/point, 2 A/common, Response time: 1 ms or less, 32 points/common,
				40-pin connector x2, overload protection function, overheat protection function, surge suppression
				Input specifications : 32 points, 24 V DC, Response time: 1/5/10/20/70 ms or less, 32 points/common, Positive/Negative common
		DC input/transistor		Output specifications: 32 points, 1224 V DC, 0.1 A/point, 2 A/common, Response time: 1 ms or less,
		output (sink)	LH42C4NT1P	32 points/common, overload protection function, overheat protection function,
I/O combined	output (onit)		surge suppression	
	1/0			40-pin connector x2
	combined			Input specifications : 32 points, 24 V DC, Response time: 1/5/10/20/70 ms or less,
				32 points/common, Positive/Negative common
		DC input/transistor	LH42C4PT1P	Output specifications: 32 points, 1224 V DC, 0.1 A/point, 2 A/common, Response time: 1 ms or less,
		output (source)	L117204F11F	32 points/common, overload protection function, overheat protection function,
				surge suppression
				40-pin connector x2
Space module			LG69 NEW	Space module for AnS module replacement
Spring clamp to	erminal bloc	k	L6TE-18S NEW	Alternative to a 18-point screw terminal block, 0.31.0 mm² (AWG2218), push-in type

# **MELSEC-L** series

Тур	oe .	Model	Outline
Multiple input (voltage/current/temperature) modules		L60MD4-G NEW	4 channels, Input: -1010 V DC, 020 mA DC, micro voltage-100100 mV DC, Thermocouple (K, J, T, E, N, R, S, B, U, L, PL II, W5Re/W26Re), RTD (Pt1000, Pt100, JPt100, Pt50), Output (resolution): 020000, -2000020000, (with voltage, current, micro voltage input) Conversion speed: 50 ms/channels, 18-point terminal block, Channel isolated
		L60AD4	4 channels, Input: -1010 V DC, 020 mA DC, Output (resolution): 020000, -2000020000, Conversion speed: 20 μs, 80 μs, 1 ms/channel, 18-point terminal block
	Analaniana	L60ADVL8 NEW	8 channels, Input: -1010 V, Output (resolution)-1600016000, Conversion speed: 1 ms/channels 18-point terminal block
	Analog input	L60ADIL8 NEW	8 channels, Input: 020 mA DC, Output (resolution): 08000, Conversion speed: 1 ms/channels 18-point terminal block
Analog I/O madula		L60AD4-2GH	4 channels, Input: -1010 V DC, 020 mA DC, Output (resolution): 032000, -3200032000, Conversion speed: 40 µs/2 channels, 18-point terminal block, Dual channel isolation
Analog I/O module	Analog output	L60DA4	4 channels, Input (resolution): 020000, -2000020000, Output: -1010 V DC, 020 mA DC, Conversion speed: 20 µs/channel, 18-point terminal block
	Analog I/O	L60AD2DA2	Input specifications : 2 channels, Input: -1010 V DC, 020 mA DC, Output (resolution): 012000, -1600016000, Conversion speed: 80 µs/channel, Output specifications : 2 channels, Input (resolution): 012000, -1600016000, Output: -1010 V DC, 020 mA DC, Conversion speed: 80 µs/channel, 18-point terminal block
	Thermocouple	L60TCTT4	4 channels (normal mode) /2 channels (heating-cooling control), Thermocouple (K, J, T, B, S, E, R, N, U, L, PL II, W5Re/W26Re), No Heater disconnection detection function, sampling cycle: 250 ms/4 channels, 500 ms/4 channels, Channel isolated, 18 point terminal block
Temperature Control	Thermocouple	L60TCTT4BW	4 channels (normal mode) /2 channels (heating-cooling control), Thermocouple (K, J, T, B, S, E, R, N, U, L, PL II, W5Re/W26Re), Heater disconnection detection function, Sampling cycle: 250 ms/4 channels, 500 ms/4 channels, Channel isolated, 18 point terminal block x2
module	RTD	L60TCRT4	4 channels (normal mode) /2 channels (heating-cooling control), Platinum type resistive temperature device(Pt100, JPt100), No Heater disconnection detection function, Sampling cycle: 250 ms/4 channels, 500 ms/4 channels, Channel isolated, 18 point terminal block
		L60TCRT4BW	4 channels (normal mode) /2 channels (heating-cooling control), Platinum type resistive temperature device (Pt100, JPt100), Heater disconnection detection function, Sampling cycle: 250 ms/4 channels, 500 ms/4 channels, Channel isolated, 18 point terminal block x2
		LD77MS2*1	2 axes, 2-axis linear interpolation, 2-axis circular interpolation, synchronous control, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, SSCNET II/H connectivity
	SSCNET II/H	LD77MS4*1	4 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, synchronous control, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, SSCNET II/H connectivity
Simple motion module		LD77MS16*1	16 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, synchronous control, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, SSCNET II/H connectivity
	SSCNET II	LD77MH4*1	4 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, synchronous control, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, SSCNET
	33CNLT III	LD77MH16*1	16 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, synchronous control, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, SSCNET Ⅲ connectivity
		LD75P1	1 axis, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: 200 kpps, 40-pin connector
	Open collector	LD75P2	2 axes, 2-axis linear interpolation, 2-axis circular interpolation, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: 200 kpps, 40-pin connector
Positioning module		LD75P4	4 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: 200 kpps, 40-pin connector x2
		LD75D1	1 axis, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: 4 Mpps, 40-pin connector
	Differential driver	LD75D2	2 axes, 2-axis linear interpolation, 2-axis circular interpolation, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: 4 Mpps, 40-pin connector
		LD75D4	4 axes, 2-/3-/4-axis linear interpolation, 2-axis circular interpolation, Control unit: mm, inch, degree, pulse, Number of positioning data: 600 data/axis, Maximum output pulse: 4 Mpps, 40-pin connector x2
		LD62	2 channels, 200/100/10 kpps, Count input signal: 5/12/24 V DC, External input: 5/12/24 V DC, Coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector
High-speed counter module		LD62D	2 channels, 500/200/100/10 kpps, Count input signal: EIA standards RS-422-A (Differential line driver level), External input: 5/12/24 V DC, Coincidence output: transistor (sink), 12/24 V DC, 0.5 A/point, 2 A/common, 40-pin connector

^{*1:} The connector is not appended. Please obtain an LD77MHIOCON separately.

# MELSEC-L series

MILEOLO-L SCITES			
Ту	Type		Outline
	CC-Link IE Field	LJ71GF11-T2	Master/Local station
	Network	LJ72GF15-T2*1	Remote station (Head module with END cover)
	CC-Link	LJ61BT11	Master/Local station, CC-Link Ver.2.0 compatible
	CC-Link/LT	LJ61CL12	Master station, CC-Link/LT system compatible
	SSCNET II/H	LJ72MS15*2	Remote station (Head module with END cover)
Network module	Ethernet interface	LJ71E71-100	10BASE-T/100BASE-TX
	Ethernet interiace		BACnet™ client function, MODBUS® TCP master function (using predefined protocol support function)
		LJ71C24	RS-232: 1 channel, RS-422/485: 1 channel, Total transmission speed of 2 channels: 230.4 kbps
	Serial communication		MODBUS® RTU master function (using predefined protocol support function)
		LJ71C24-R2	RS-232: 2 channels, Total transmission speed of 2 channels: 230.4 kbps
		1071024-112	MODBUS® RTU master function (using predefined protocol support function)
Digital link sensor		LJ51AW12AL DB	AnyWireASLINK system compatible master module

- *1: The CPU module, branch and extension module, display unit, RS-232 adapter, CC-Link IE Field Network master/local module and Ethernet interface module cannot be mounted on a system using LJ72GF-T2.
- *2: The CPU module, branch and extension module, display unit, RS-232 adapter, temperature control module, simple motion module, positioning module, CC-Link IE Field Network master/local module, CC-Link IE Field network head module, CC-Link master/local module, CC-Link/LT master module, Ethernet interface module, serial communication module, and AnyWireASLINK master module cannot be mounted on a system using LJ72MS15.

# Compatible module for each protocol

Compatible protocol	Compatible module	Model	Outline
SLMP (MC protocol)	CPU (Built-in Ethernet)	L02CPU(-P) L06CPU(-P) L26CPU(-P) L26CPU-(P)BT	SLMP server function (only MC protocol QnA compatible 3E frame) SLMP client function (using predefined protocol support function)
	Ethernet interface module	LJ71E71-100	SLMP server function (including MC protocol) SLMP client function (using predefined protocol support function)
BACnet™	CPU (Built-in Ethernet)	L02CPU(-P) L06CPU(-P) L26CPU(-P) L26CPU-(P)BT	Compatible BACnet™ object: Analog Input (AI), Binary Input (BI), Binary Output (BO), Accumulator (AC) (using predefined protocol support function)
	Ethernet interface module	LJ71E71-100	
MODBUS®/TCP	CPU (Built-in Ethernet)	L02CPU(-P) L06CPU(-P) L26CPU(-P) L26CPU-(P)BT	MODBUS®/TCP communication master function (using predefined protocol support function)
	Ethernet interface module	LJ71E71-100	
MODBUS®	CPU (Built-in RS-232)	L02SCPU(-P)	
	RS-232 adapter	L6ADP-R2	MODBUS®RTU communication master function
	RS-422/485 adapter	L6ADP-R4	(using predefined protocol support function)
	Serial Communication Modules	LJ71C24(-R2)	

# **Options**

Type	Model	Outline
	A6CON1*3*4	Soldering type 32-point connector (40-pin connector)
Connector	A6CON2*3 *4	Crimp contact type 32-point connector (40-pin connector)
Connector	A6CON3*3 *5	Flat cable pressure welding type 32-point connector (40-pin connector)
	A6CON4*3*4	Soldering type 32-point connector (40-pin connector, cable connectable in bidirection)
Connector/terminal block converter module	A6TBXY36*6*7*8	For positive common type input module and sink type output module (Standard type)
	A6TBXY54*6*7*8	For positive common type input module and sink type output module (2-wire type)
	A6TBX70*6*9	For positive common type input module (3-wire type)

- *3: Available for L02CPU, L02CPU-P, L06CPU, L06CPU-P, L26CPU, L26CPU-P, L26CPU-BT, L26CPU-BT, LX41C4, LX42C4, LY41NT1P, LY42NT1P, LY41PT1P, LY42PT1P, LH42C4NT1P and LH42C4PT1P.
- *4: Available for LD75P1, LD75P2, LD75P4, LD75D1, LD75D2, LD75D4, LD62 and LD62D.
  *5: When used with L02CPU, L02CPU-P, L06CPU, L06CPU-P, L26CPU, L26CPU-P, L26CPU-BT, L26CPU-PBT, only when all points are general-purpose I/O.
- *6: Available for LX41C4 and LX42C4. (Positive common only)
- *7: Available for LY41NT1P, LY42NT1P, LY41PT1P and LY42PT1P.
- *8: Available for LH42C4NT1P and LH42C4PT1P. (Input side only when using plus common.)
- *9: Available for LH42C4NT1P and LH42C4PT1P. (Input side only when using plus common. Output side is not usable.)

# **Ethernet related products**

	Туре	Model	Outline
	U.S.A.	NZ2WL-US*10*11 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards
\A(:	Europe	NZ2WL-EU*10*11 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards
Wireless LAN Adapter	China	NZ2WL-CN*10*11 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards
·	Korea	NZ2WL-KR*10*11 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards
	Taiwan	NZ2WL-TW*10*11 DB	Conforms to IEEE 802.11a, IEEE 802.11b, IEEE 802.11g standards
Industrial switching HUB		NZ2EHG-T8 DB	10 Mbps/100 Mbps/1 Gbps AUTO-MDIX, DIN rail mountable, 8 ports
		NZ2EHF-T8 DB	10 Mbps/100 Mbps AUTO-MDIX, DIN rail mountable, 8 ports
CC-Link IE Field Network Ethernet Adapter NZ2		NZ2GF-ETB	100 Mbps/1 Gbps compatible station for expanding CC-Link IE Field Networks

^{*10:} Each product is usable only in the respective country.

^{*11:} Both access points and stations are supported, and can be switched with the settings.

# MELSOFT*1 — Programming Tool

Туре	Model	Outline
MELSOFT GX Works2	SW1DNC-GXW2-E	Programmable controller engineering software (Functions integrated software: Programming, simulation, module settings, and monitoring)
		FA engineering software*2
		System Management Software: MELSOFT Navigator     MELSOFT Navigator is a comprehensive system configuration solution that serves as a launching pad for the other software packages.
		Controller Programming Software: MELSOFT GX Works3, GX Works2, GX Developer The next generation configuration, programming, and simulation software for FX, L, and Q Series controllers.
MELSOFT iQ Works	SW2DND-IQWK-E (DVD-ROM edition)	Motion Programming Software: MELSOFT MT Works2     Design and maintenance tool for motion controllers.
		HMI Programming Software: MELSOFT GT Works3     GOT configuration, screen design, and maintenance tool.
		Robot Programing Software: MELSOFT RT ToolBox2 mini Programming and total engineering tool for robots
		Inverter Setup Software: MELSOFT FR Configurator2 Simulation, setting, and monitoring tool for inverters.
MELSOFT MX Component	SW4DNC-ACT-E	ActiveX® library for communication
MELSOFT MX Sheet	SW2DNC-SHEET-E*3	Excel® communication support tool

^{*1:} For details on the software versions compatible with each module, refer to the manual for each product.

# Compliance with international quality assurance standards

All of Mitsubishi Electric's FA products have acquired the international quality assurance "ISO9001" and environment management system standard "ISO14001" certification. Mitsubishi Electric's products also comply with various safety standards, including UL standards.

*For jointly developed and partner products, guaranteed quality standards may differ. Please refer to the product manuals for details.

# **Safety Standards**





Please contact your local Mitsubishi Electric sales office or representative for the latest information about MELSOFT software versions and compatible operating systems.

^{*2:} For detailed information about supported modules, refer to the manuals of the relevant software package.

^{*3:} MX Component is required to use MX Sheet.

# **FA Products**

# НМ

# Graphic Operation Terminal GOT2000 Series GT27 Mode



To the top of HMIs with further user-friendly, satisfactory standard features.

- ©Comfortable screen operation even if high-load processing (e.g. logging, device data transfer) is running. (Monitoring performance is twice faster than GT16)
- OActual usable space without using a SD card is expanded to 128MB for more flexible screen design.
- OMulti-touch features, two-point press, and scroll operations for more user-friendliness.
- Outline font and PNG images for clear, beautiful screen display.





# **Product Specifications**

Screen size	15", 12.1", 10.4", 8.4"
Resolution	XGA, SVGA, VGA
Intensity adjustment	32-step adjustment
Touch panel type	Analog resistive film
Built-in interface	RS-232, RS-422/485, Ethernet, USB, SD card
Applicable software	GT Works3
Input power supply voltage	100 to 240VAC (+10%, -15%), 24VDC (+25%, -20%)

# Inverter

# FR-A800 Series



# High-functionality, high-performance inverter

- Realize even higher responsiveness during real sensor-less vector control or vector control, and achieve faster operating frequencies.
- The latest automatic tuning function supports various induction motors and also sensor-less PM motors.
- The standard model is compatible with EU Safety Standards STO (PLd, SIL2). Add options to support higher level safety standards.
- ©Control and monitor inverters via CC-Link/CC-Link IE Field Network (option interface).



# Product Specifications

Inverter capacity	200V class: 0.4kW to 90kW, 400V class: 0.4kW to 500kW
Control method	High-carrier frequency PWM control (Select from V/F, advanced magnetic flux vector,
	real sensorless vector or PM sensorless vector control), vector control (when using options)
Output frequency range	0.2 to 590Hz (upper limit is 400Hz when using advanced magnetic flux vector control,
	real sensorless vector control, vector control or PM sensorless vector control)
Regenerative braking torque	200V class: 0.4K to 1.5K (150% at 3%ED) 2.2K/3.7K (100% at 3%ED) 5.5K/7.5K (100% at 2%ED)
(Maximum allowable duty)	11K to 55K (20% continuous) 75K or more (10% continuous), 400V class: 0.4K to 7.5K (100% at 2%ED)
	11K to 55K (20% continuous) 75K or more (10% continuous)
Starting torque	200% 0.3Hz (3.7K or less), 150% 0.3Hz (5.5K or more) (when using real sensorless vector, vector control)

# AC Servo

# Mitsubishi General-Purpose AC Servo MELSERVO-J4 Series



# Industry-leading level of high performance servo

- Olndustry-leading level of basic performance: Speed frequency response (2.5kHz), 4,000,000 (4,194,304p/rev) encoder
- $\bigcirc$  Advanced one-touch tuning function achieves the one-touch adjustment of advanced vibration suppression control  $\mathbb{I}$ , etc.
- ©Equipped with large capacity drive recorder and machine diagnosis function for easy maintenance.
- ©2-axis and 3-axis servo amplifiers are available for energy-conservative, space-saving, and low-cost machines.

# Product Specifications

Power supply specifications	1-phase/3-phase 200V AC, 1-phase 100V AC, 3-phase 400V AC
Command interface	SSCNET III/H, SSCNET III (compatible in J3 compatibility mode), CC-Link IE Field
	Network interface with Motion, pulse train, analog
Control mode	Position/Speed/Torque/Fully closed loop
Speed frequency response	2.5kHz
Tuning function	Advanced one-touch tuning, advanced vibration suppression control II, robust filter, etc.
Safety function	STO, SS1
	SS2, SOS, SLS, SBC, SSM (compatible when combined with motion controller)
Compatible servo motor	Rotary servo motor (rated output: 0.05 to 22kW), linear servo motor (continuous
	thrust 50 to 3000N), direct drive motor (rated torque: 2 to 240N·m)

# Magnetic Starter

# MS-T Series



Exceed your expectations.

- ◎10A frame model is over 16% smaller with a width of just 36mm!!
- ONew integrated terminal covers.
- ©Reduce your coil inventory by up to 50%.
- $\tilde{\mathbb{Q}}$  Be certified to the highest international levels while work is ongoing to gain other country.

# Product specifications

Frame	10 A to 32 A
Applicable standards	Certification to various standards including IEC, JIS, CE, UL, TÜV, CCC.
Terminal cover	Standard terminal cover improves safety, simplifies ordering, and reduces inventory, etc.
Improved wiring	Wiring and operability are improved with streamlining wiring terminal BC specifications.
Operation coil rating	Wide range of operation coil ratings reduces number of coil types from 14 (N Series) to 7 types and simplifies selection.
Option units	Diverse lineup includes Auxiliary Contact Block, Operation Coil Surge Absorber Unit, Mechanical Interlock Unit.

# Low-voltage switch

# Mitsubishi Motor Circuit Breaker MMP-T Series



# Introducing a Motor Circuit Breaker from Mitsubishi Electric!

- ODesign smaller panels by using the Motor Circuit Breaker, various options and MS-T Series Magnetic Contactor.
- ©Prevent secondary damage with Motor Circuit Breaker and Magnetic Contactor combination.
- OStreamlined wiring terminal BC specifications (option) contribute to improving your productivity.
- ©Supports your overseas business with compliance to various International Standards as well as the UL Type E/F combination.

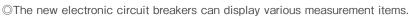
# Product specifications

Rated current	0.16 A to 32 A (15 types)
Applicable (compliant) standards	Standard product compliant with various International Standards including IEC, JIS, CCC, TÜV and UL (certified)
Wiring types	Bare wire, rod terminal, Y crimp and round crimp supported
Improvement of wiring	Wiring and operability are improved with connection conductor unit and streamlined wiring terminal BC specifications (option)
Optional units	Auxiliary/Alarm Contact Unit, Short-Circuit Indicator Unit, Line Side Terminal Adapter, Connection Conductor Unit, etc., available
DIN rail mounting	Standard product mountable on rail
Finger protection support	Standard product compliant with IP20 from front side of terminals
Application in North America	Type E/F combination certification acquired. Compatible up to maximum SCCR value 50 kA

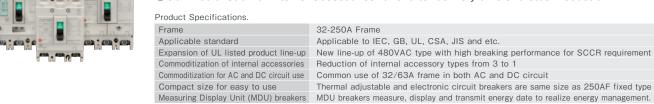
# Low Voltage Circuit Breakers

# Mitsubishi WS-V Series Molded Case Circuit Breakers, Earth Leakage Circuit Breakers





- Olmprovement of breaking performance with new breaking technology "Expanded ISTAC".
- ©Compliance with global standard for panel and machine export.
- ©Commoditization of internal accessories for shorter delivery time and stock reduction.



# Robot



High speed, high precision and high reliability industrial robot

- Ocompact body and slim arm design, allowing operating area to be expanded and load capacity increased.
- The fastest in its class using high performance motors and unique driver control technology.
- Olmproved flexibility for robot layout design considerations.
- Optimal motor control tuning set automatically based on operating position, posture, and load conditions.

# Product Specifications

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Degrees of freedom	Vertical:6 Horizontal:4
Installation	Vertical:Floor-mount, ceiling mount, wall mount (Range of motion for J1 is limited) Horizontal:Floor-mount
Maximum load capacity	Vertical:2-20kg Horizontal:3-20kg
Maximum reach radius	Vertical:504-1503mm Horizontal:350-1,000mm

# MITSUBISHI CNC M70V Series

A global standard model that offers both high speed and accuracy.

- ©Permits commands in 0.1 µm increments and internal interpolation control in 1 nm increments for smooth, high-accuracy machining.
- Olntuitive operation and display of hierarchical screens, with an Ethernet I/F (standard feature) for easy program management.
- Offers a more compact control panel by integrating the display and control.

# Product specifications

Maximum number of control axes (NC axes + spindles + PLC axes)	Type A: 11 axes Type B: 9 axes
Maximum number of part systems	Type A: 2 systems Type B: 1 system
Least command increment	0.1μm
Least control increment	1nm
Maximum program capacity	Type A: 2,000 KB (5,120 m) Type B: 500 KB (1,280 m)
Maximum PLC program capacity	Type A: 32,000 steps Type B: 20,000 steps
Main functions (for machining center)	OMR-DD control (high-speed synchronous tapping), High-speed & high-accuracy control, Tool center point control, Inclined surface machining, etc.
Main functions (for lathes)	Milling interpolation, 2-system simultaneous thread cutting, Control axis synchronization across part systems, Control axis superimposition, Mixed control, etc.



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Country/Region Sales office Tel/Fax MITSUBISHI ELECTRIC AUTOMATION, INC. Tel: +1-847-478-2100 USA 500 Corporate Woods Parkway, Vernon Hills, IL 60061, U.S.A. Fax: +1-847-478-2253 MITSUBISHI ELECTRIC AUTOMATION, INC. Mexico Branch Tel: +52-55-3067-7500 Mexico Mariano Escobedo #69, Col. Zona Industrial, Tlalnepantla Edo, C.P.54030, Mexico MITSUBISHI ELECTRIC DO BRASIL COMÉRCIO E SERVIÇOS LTDA. Tel: +55-11-4689-3000 Brazil Rua Jussara, 1750-Bloco B Anexo, Jardim Santa Cecilia, CEP 06465-070, Barueri-SP, Brasil Fax: +55-11-4689-3016 MITSUBISHI ELECTRIC EUROPE B.V. German Branch Tel: +49-2102-486-0 Germany Gothaer Strasse 8, D-40880 Ratingen, Germany Fax: +49-2102-486-1120 MITSUBISHI ELECTRIC EUROPE B.V. UK Branch Tel: +44-1707-28-8780 UK Travellers Lane, Hatfield, Hertfordshire, AL10 8XB, U.K. Fax: +44-1707-27-8695 Ireland MITSUBISHI ELECTRIC EUROPE B.V. Irish Branch Tel: +353-1-4198800 Westgate Business Park, Ballymount, IRL-Dublin 24, Ireland Fax: +353-1-4198890 MITSUBISHI ELECTRIC EUROPE B.V. Italian Branch Italy Tel: +39-039-60531 Centro Direzionale Colleoni-Palazzo Sirio Viale Colleoni 7, 20864 Agrate Brianza(Milano) Italy Fax: +39-039-6053-312 MITSUBISHI ELECTRIC EUROPE, B.V. Spanish Branch Spain Tel: +34-935-65-3131 Carretera de Rubí, 76-80-Apdo. 420, 08173 Sant Cugat del Vallés (Barcelona), Spain Fax: +34-935-89-1579 MITSUBISHI ELECTRIC EUROPE B.V. French Branch Tel: +33-1-55-68-55-68 France 25. Boulevard des Bouvets, F-92741 Nanterre Cedex, France Fax: +33-1-55-68-57-57 MITSUBISHI ELECTRIC EUROPE B.V. Czech Branch Czech Republic Tel: +420-251-551-470 Avenir Business Park, Radlicka 751/113e, 158 00 Praha5, Czech Republic Fax: +420-251-551-471 MITSUBISHI ELECTRIC EUROPE B.V. Polish Branch Poland Tel: +48-12-630-47-00 ul. Krakowska 50, 32-083 Balice, Poland Fax: +48-12-630-47-01 MITSUBISHI ELECTRIC EUROPE B.V. (Scandinavia) Tel: +46-8-625-10-00 Sweden Fjelievägen 8, SE-22736 Lund, Sweden Fax: +46-46-39-70-18 Russia MITSUBISHI ELECTRIC EUROPE B.V. Russian Branch St. Petersburg office Tel: +7-812-633-3497 Piskarevsky pr. 2, bld 2, lit "Sch", BC "Benua", office 720; RU-195027 Št. Petersburg, Russia Fax: +7-812-633-3499 Turkey MITSUBISHI ELECTRIC TURKEY A.Ş Ümraniye Branch Tel: +90-216-526-3990 Serifali Mahallesi Nutuk Sokak No:5, TR-34775 Umraniye, Istanbul, Turkey Fax: +90 -216-526-3995 MITSUBISHI ELECTRIC EUROPE B.V. Dubai Branch Dubai Tel: +971-4-3724716 Dubai Silicon Oasis, P.O.BOX 341241, Dubai, U.A.E. Fax: +971-4-3724721 ADROIT TECHNOLOGIES Tel: +27-11-658-8100 South Africa 20 Waterford Office Park, 189 Witkoppen Road, Fourways, Johannesburg, South Africa Fax: +27-11-658-8101 China MITSUBISHI ELECTRIC AUTOMATION (CHINA) LTD. Tel: +86-21-2322-3030 No.1386 Hongqiao Road, Mitsubishi Electric Automation Center, Shanghai, China Fax: +86-21-2322-3000 SETSUYO ENTERPRISE CO., LTD. Tel: +886-2-2299-2499 Taiwan 6F, No.105, Wugong 3rd Road, Wugu District, New Taipei City 24889, Taiwan, R.O.C. Fax: +886-2-2299-2509 MITSUBISHI ELECTRIC AUTOMATION KOREA CO., LTD. Korea Tel: +82-2-3660-9530 7F-9F, Gangseo Hangang Xi-tower A, 401, Yangcheon-ro, Gangseo-Gu, Seoul 157-801, Korea Fax: +82-2-3664-8372 Singapore MITSUBISHI ELECTRIC ASIA PTE. LTD. Tel: +65-6473-2308 307, Alexandra Road, Mitsubishi Electric Building, Singapore 159943 Fax: +65-6476-7439 Thailand MITSUBISHI ELECTRIC FACTORY AUTOMATION (THAILAND) CO., LTD. Tel: +66-2682-6522 12th Floor, SV.City Building, Office Tower 1, No. 896/19 and 20 Rama 3 Road, Fax: +66-2682-6020 Kwaeng Bangpongpang, Khet Yannawa, Bangkok 10120, Thailand MITSUBISHI ELECTRIC VIETNAM COMPANY LIMITED Hanoi Branch Vietnam Tel: +84-4-3937-8075 6-Floor, Detech Tower, 8 Ton That Thuyet Street, My Dinh 2 Ward, Nam Tu Liem District, Hanoi, Vietnam Fax: +84-4-3937-8076 PT. MITSUBISHI ELECTRIC INDONESIA Tel: +62-21-3192-6461 Indonesia Gedung Jaya 11th Floor, JL. MH. Thamrin No.12, Jakarta Pusat 10340, Indonesia Fax: +62-21-3192-3942 MITSUBISHI ELECTRIC INDIA PVT. LTD. Pune Branch India Tel: +91-20-2710-2000 Emerald House, EL-3, J Block, M.I.D.C Bhosari, Pune-411026, Maharashtra, India Fax: +91-20-2710-2100 MITSUBISHI ELECTRIC AUSTRALIA PTY. LTD. Tel: +61-2-9684-7777 Australia 348 Victoria Road, P.O. Box 11, Rydalmere, N.S.W 2116, Australia Fax: +61-2-9684-7245

# MITSUBISHI ELECTRIC CORPORATION

HEAD OFFICE: TOKYO BUILDING, 2-7-3, MARUNOUCHI, CHIYODA-KU, TOKYO 100-8310, JAPAN NAGOYA WORKS: 1-14, YADA-MINAMI 5, HIGASHI-KU, NAGOYA, JAPAN

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